

**YUKEN**

# High-Speed Linear Servo Valves

## OBE (On-Board Electronic) Type Linear Servo Valves



0 5 10 15 20 25

**YUKEN KOGYO CO.,LTD.**

## Hydraulic Fluids

### Type of Fluids

Any type of hydraulic fluid listed in the table below can be used.

Petroleum Base Oils	Use fluids equivalent to ISO VG32 or VG46.
Synthetic Fluids	Use phosphate ester or polyol ester type. When phosphate ester type fluid is used, prefix "F-" to the model number because a special seal (fluororubber) will be used.
Water Containing Fluids	Use water-glycol fluids. Water-glycol fluids cannot be used for valves "without Y port" (wet type: LSVG-*EH-* <u>W</u> ) or "without DR port" (wet type pilot valve: LSVHG-*EH-* <u>W</u> ).

Note: For use with hydraulic fluids other than those listed above, please consult your Yuken representatives in advance.

### Recommended Viscosity and Temperature

Use hydraulic fluids which satisfy both recommended viscosity and oil temperatures given in the table below.

Viscosity	Temperature
15 - 400 mm <sup>2</sup> /s	-15 - +60 °C

### Control of Contamination

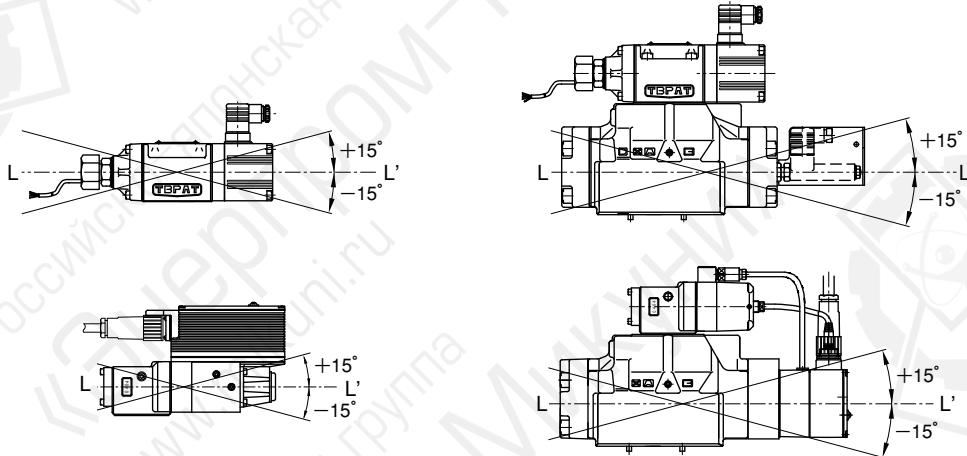
Keep the hydraulic fluid clean and provide a line filter so that contamination of the fluid will not obstruct proper valve operation. To assure long life of linear servo valves, it is recommended to improve fluid cleanliness before use.

Contamination Level	Line Filter
NAS1638 Class 10 ISO4406 21/19/15	Absolute 20 $\mu\text{m}$

## Instructions

### Mounting

Mount the valve with the angle of the axis line L-L' within about  $\pm 15^\circ$  from the horizontal plane, as shown below. The valve must be mounted in such a way that the spool axis direction is not matched with the main vibration direction; otherwise, an external force may cause the spool to malfunction.



## ■ Installation Requirements

Avoid installing the valve in a strong magnetic field. Especially, the position sensor for detecting the spool position is affected by the magnetic field. Keep the valve away from devices that generate magnetic fields, such as solenoid operated directional valves. At the same time, a magnetic field generated by the valve may affect other devices; any device vulnerable to magnetic fields must not be installed near the valve.

## ■ Drain Piping (LSVG: Y Port/LSVHG: DR Port)

LSVG/LSVHG series high speed linear servo valves have a diaphragm mechanism that keeps the inside of the linear motor dry in order to meet the requirements below.

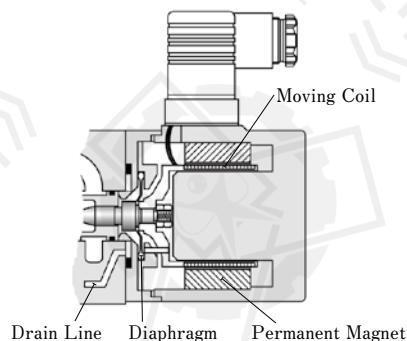
- 1) Keeping response characteristics almost unchanged when fluid viscosity varies (the response characteristics of existing proportional/servo valves vary with changes in fluid viscosity).
- 2) Protecting moving coils from iron powder or moisture in hydraulic fluids.

A special drain port is provided to define the upper limit of pressure for the diaphragm, if any, so that the valve performance is maintained. For valve installation, provide a drain line by taking into account the following piping considerations.

① Back pressure at the drain port should be 0.05 MPa or less and not be a negative pressure.

② The drain line should be open to the air (the line end must not contact the fluid).

★ There are two types of pilot valves available: a dry type good in response characteristics and a wet type that eliminates the Y or DR port to improve usability.



## ■ Cable Length for I/O Signals

- 1) High speed linear servo valves (amplifier-separated type)

Use a cable of up to 30 m in length.

Consult us for customized products (Model: LSVG-03/LSVHG-04, 06) that allow the use of a cable of up to 200 m in length.

- 2) OBE (on-board electronics) type liner servo valves

The maximum cable length depends on the I/O signal type. See the table below.

I/O Signal Type	Valve Model Number	Max. Cable Length
±10 V	LSV(H) G-* * EH-* * -*-A*/D*-10	50 m*
4 - 20 mA	LSV(H) G-* * EH-* * -*-B*/E*-10	300 m
±10 mA	LSV(H) G-* * EH-* * -*-C*/F*-10	

★ Consult us when the cable length exceeds 50 m.

For both valve types in 1) and 2), pay attention to ensure that the power cable resistance is within 1 Ω and is as low as possible.

Structure of the Linear Motor

## ■ Electrical Failure and Safety Measures for Startup

Provide a separate safety circuit (e.g. uninterruptible power supply), if required, to securely continue/stop the operation of the hydraulic actuator for safety in case of electrical failure (power failure, cable disconnection, etc.) or upon startup.

## ■ Supply Pressure

The servo valves are designed to operate at constant supply pressure; variations in supply pressure should be avoided as much as possible. Especially, for systems requiring high accuracy, the circuit must be designed to keep the supply pressure constant.

Ideally, an accumulator will be installed in the supply pressure line near the servo valve to avoid supply pressure fluctuations during pressure transients.

## ■ Pressure at the Return Port

The return port of the servo valve may be subject to a considerably high pressure depending on the circuit type. However, it should be used at atmospheric pressure or similar pressure as much as possible. The pressure at the return port should be equal to or below actual supply pressure.

## ■ Disassembly/Reassembly

Linear servo valves consist of high precision components. You are prohibited from disassembling or reassembling the valves; otherwise, the designed valve performance may be degraded.

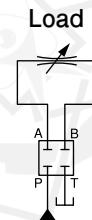
## Valve Pressure Difference/Load Pressure Difference

This catalog uses two terms related to pressure differences: "valve pressure difference" (used for the range of flow control and no-load flow characteristics) and "load pressure difference" (used for load flow characteristics). The terms are described below.

### ■ Valve Pressure Difference

Suppose that, in the circuit shown on the right, the fluid flows from P to A and from B to T. In this case, the sum of the pressure differences between P and A and between B and T is the pressure difference of this valve. For this four-way valve, the valve pressure difference " $\Delta P$ " is:

$$\text{Valve Pressure Difference} = [(\text{Pres. at P}) - (\text{Pres. at A})] + [(\text{Pres. at B}) - (\text{Pres. at T})].$$



In relation to the flow rate, an increase in the flow through the valve with a constant valve opening leads to an increase in the valve pressure difference due to increased flow resistance at the control part.

### ■ Load Pressure Difference

In the circuit above, the absolute pressure difference between A and B is the load pressure difference.

$$\text{Load Pressure Difference} = |(\text{Pres. at A}) - (\text{Pres. at B})|$$

If the resistance of piping, etc. is ignored, the difference between the supply pressure and the load pressure difference is the valve pressure difference of the linear servo valve. Therefore, a smaller load pressure difference means a larger valve pressure difference, allowing increasing the flow rate through the valve.

## Flow Rate

In this catalog, the rated flow tolerance is  $\pm 10\%$

The flow rate depends on the viscosity and specific gravity of each hydraulic fluid.

- Multiply each viscosity by the corresponding coefficient in the table below.

Viscosity mm <sup>2</sup> /s	15	20	30	40	50	60	70	80	90	100
Coefficient	1.19	1.11	1.00	0.93	0.88	0.84	0.81	0.78	0.76	0.74

- Use the following formula to obtain the flow rate corresponding to a specific gravity.  $Q' = Q_{\text{rate}} \sqrt{(0.85/G')}$

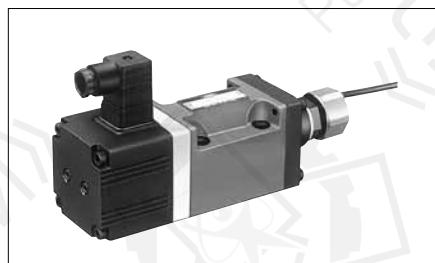
- Use the following formula to obtain the relationship between the flow rate and the pressure for a servo valve.

$$Q_X = Q_{\text{rate}} \sqrt{\frac{\Delta P_X}{7}}$$

where       $Q_X$  : Flow rate to be determined;  
 $Q_{\text{rate}}$  : Rated flow rate (at  $\Delta P = 7$  MPa); and  
 $\Delta P_X$ : Valve pressure difference in the actual circuit.

## Direct type High-Speed Linear Servo Valves

Direct type high speed servo valves use a compact and powerful linear motor as an actuator and have an extremely simple structure that connects the linear motor moving coil, the spool, and the position sensor in series.

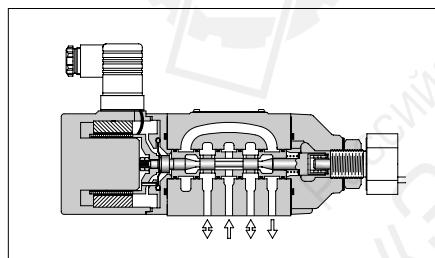


### High accuracy

These valves have a low hysteresis of 0.1 % or less, achieving high accuracy. They allow the main unit to operate with much higher repeatability.

### High response characteristics

The valves provide significantly high levels of step and frequency responses, which are typically used as measures of response characteristics; the step response is 2 ms (0 <=> 100 %)\*, and the frequency response is 450 Hz/-90° ( $\pm 25\%$  amplitude)\*. Thus, the valves ensure that the main unit can achieve unprecedented high response. (\*: Representative values)



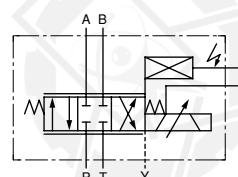
### Excellent vibration-proof characteristics

With a simple structure, the valves offer high vibration resistance.

### Excellent contamination resistance

The valves are also featured by excellent contamination resistance since they have a simple structure that directly connects the linear motor moving coil, the spool, and the position sensor. Compared to conventional servo valves for which the permissible contamination level is up to NAS 1638 class 7, the direct type linear servo valves can accept a contamination level of up to NAS 1638 class 10. These valves can contribute to greatly reducing the cost of fluid management.

### Graphic Symbols



### Model Number Designation

F—	LSVG	—03	—40	—R	—10
Fluid Type	Series Number	Valve Size	Rated Flow @ $\Delta P = 7$ MPa	Cable Departure Direction	Design Number
F : Special Seals for Phosphate Ester Type Fluid (Omit if not required)	LSVG : Direct Type High Speed Linear Servo Valves	03	4 : 4 L/min 10 : 10 L/min 20 : 20 L/min 40 : 40 L/min 60 : 60 L/min	(Viewed from the linear motor side) <b>None</b> : Upper (Standard) <b>R</b> : Right <b>L</b> : Left	10

### Exclusive Amplifiers

To ensure stable performance, it is recommended to use Yuken's AMLS series linear servo amplifiers.

Valve Model Number	Amplifier Model
LSVG-03-4/10/20/40	AMLS-A-D * - * -10
LSVG-03-60	AMLS-B-D * - * -10

### Attachment

Mounting Bolt	Bolt Tightening Torque
Hex. Soc. Head Cap Screw: M8×65L…4 Pieces	30.8 - 37.7 Nm

## ■ Specifications

The specifications below are for use with a 48 V DC type exclusive amplifier; for use with a 24 V DC type amplifier, see the values in parentheses ( ).

Model Numbers		LSVG-03-4/10/20/40	LSVG-03-60
Description			
Rated Flow @ $\Delta P = 7 \text{ MPa}$ <sup>(1)</sup>	L/min	4, 10, 20, 40	60
Max. Operating Pressure	MPa		35
Proof Pres. at Return Port	MPa		35
Drain Port (Y Port) Permissible Back Pres. <sup>(2)</sup>	MPa		0.05
Internal Leakage (PS = 14 MPa) (Viscosity: 32 mm <sup>2</sup> /s)	L/min		1.7 or less
Hysteresis	%		0.1 or less
Step Response (0 <=> 100 %, Typical) <sup>(3)</sup>	ms	2 (3)	3 (4)
Frequency Response ( $\pm 25\%$ Amplitude, Typical) <sup>(3)</sup>	Gain: -3 dB	350 (300)	330 (240)
	Phase: -90°	450 (370)	410 (330)
Vibration Proof <sup>(4)</sup>		Frequency: 10 - 60 Hz, Amplitude: 4 mm, Acceleration: 7.8 - 282 m/s <sup>2</sup> Frequency: 61 - 2000 Hz, Amplitude: 4 - 0.0038 mm, Acceleration: 294 m/s <sup>2</sup>	
Protection		IP 64	
Ambient Temperature	°C		-15 - +60
Spool Type		Neutral/Zero Lap	
Spool Stroke to Stops	mm	±0.5	±0.75
Polarity		See the description about I/O signal characteristics on page 18.	
Linear Motor Specification	Current	2 [Max. 6 ]	
	Coil Resistance	4.5 [at 20 °C ]	
Mass	kg	5	

Note: <sup>(1)</sup> Use the valves so that the relationship between the valve pressure difference and the flow rate, as specified below in "Range of Flow Control", is met.

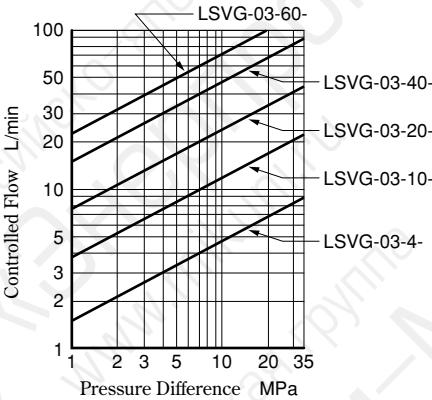
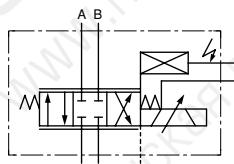
<sup>(2)</sup> Back pressure at the drain port (Y) should be 0.05 MPa or less and not be a negative pressure.

<sup>(3)</sup> This value is measured for each valve; it may vary depending on the actual circuit.

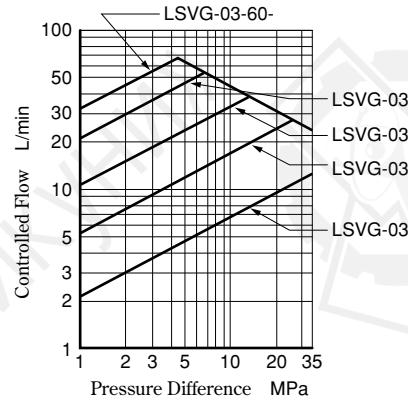
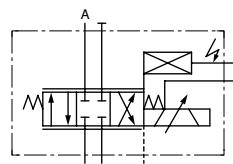
<sup>(4)</sup> There are restrictions on the mounting position; refer to the instructions for details.

## ■ Range of Flow Control

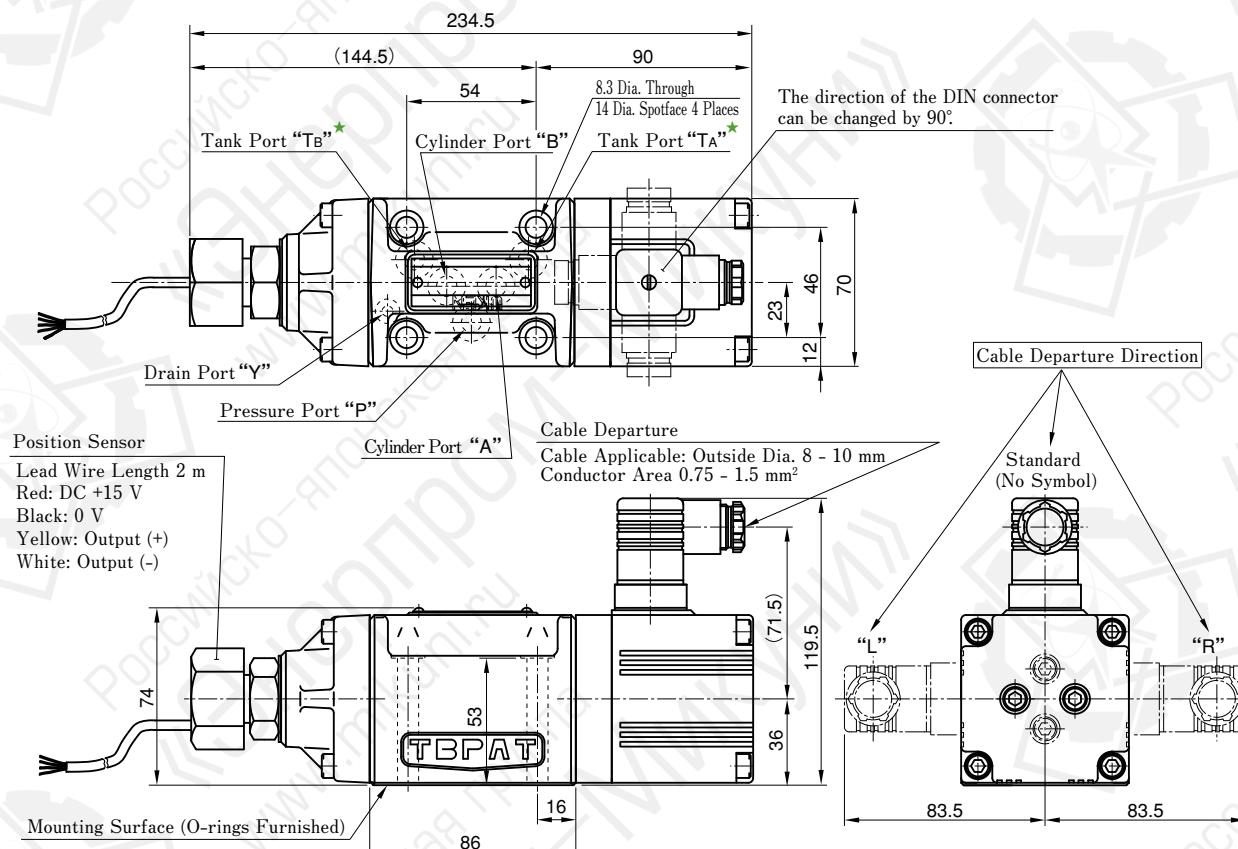
● Control Method: 4-Way Valve



● Control Method: 3-Way Valve



## LSVG-03



Note) Refer to the wiring diagram on page 20 for detailed connection between the DIN connector/position sensor and the amplifier.

### ● O-rings for the Ports

Port	O-ring Size	Qty.
P, A, B, T	AS568-014 (NBR,Hs90)	5
Y	JIS B2401-1B-P7	1

O-rings made of fluorinated rubber are required to use phosphate ester type fluids.

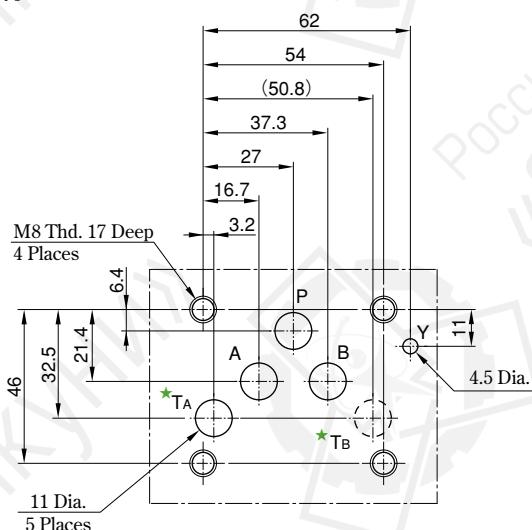
### 【Mounting Surface】

Prepare a mounting surface shown on the right. Basically, the dimensions of the mounting surface conform to the ISO standard, but the specifications for valve mounting screws are different as follows.

Consult us for valves available with M6 mounting screws.

	ISO 4401-05-04-0-94	Mounting Surface for LSVG-03
Valve Mounting Screw	M6	M8

The mounting surface should have a good machined finish.



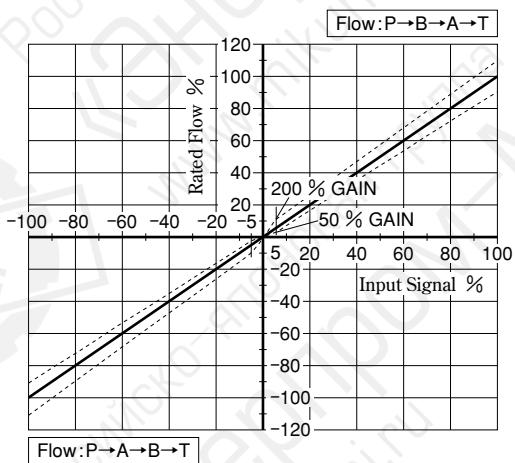
\*There are two tank ports "T<sub>A</sub>" and "T<sub>B</sub>" ; however, "T<sub>A</sub>" may be used alone.

## Characteristics of LSVG-03-4/10/20/40/60 (Fluid Viscosity: 30 mm<sup>2</sup>/s)

### No-Load Flow Characteristics

Conditions

Valve Pressure Difference : 7 MPa

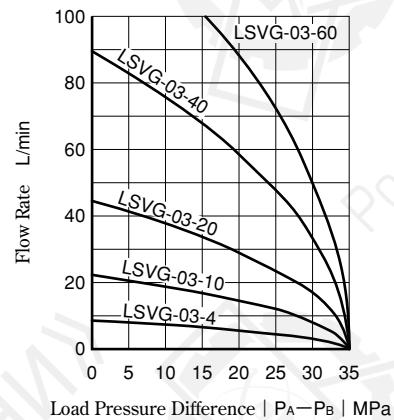


### Load Flow Characteristics

Conditions

Input Signal : 100 %

Note) Tolerance for Load Flow : ±10 %



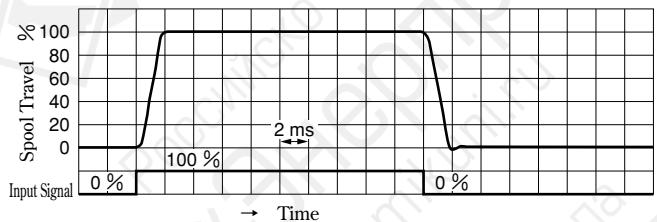
### Step Response

Conditions

Input Amplitude : 0 ⇔ 100 % Supply Pressure : 14 MPa

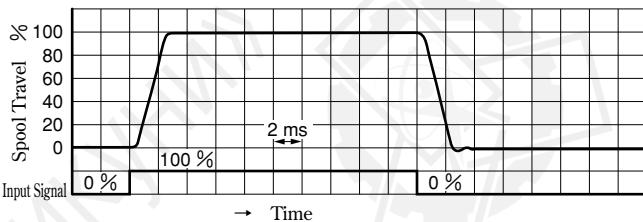
LSVG-03-4/10/20/40-10

Amplifier : AMLS-A-D48-\*\*-10 (Power Supply: 48 V DC)

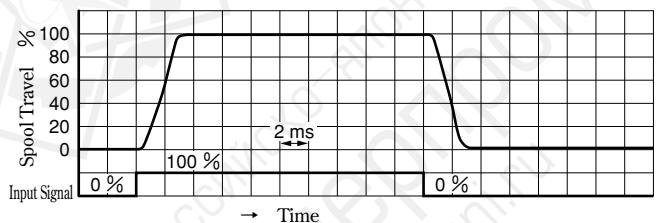


LSVG-03-60-10

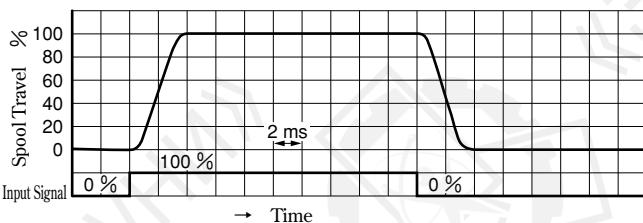
Amplifier : AMLS-B-D48-\*\*-10 (Power Supply: 48 V DC)



Amplifier : AMLS-A-D24-\*\*-10 (Power Supply: 24 V DC)



Amplifier : AMLS-B-D24-\*\*-10 (Power Supply: 24 V DC)



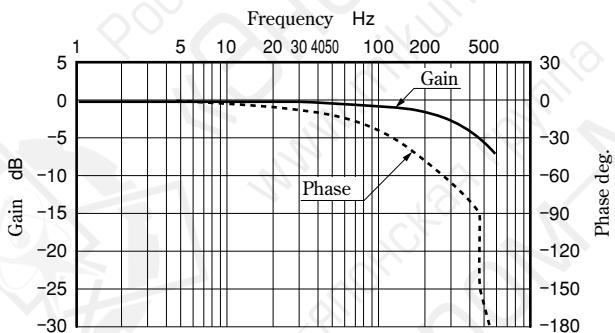
## ■ Frequency Response

### Conditions

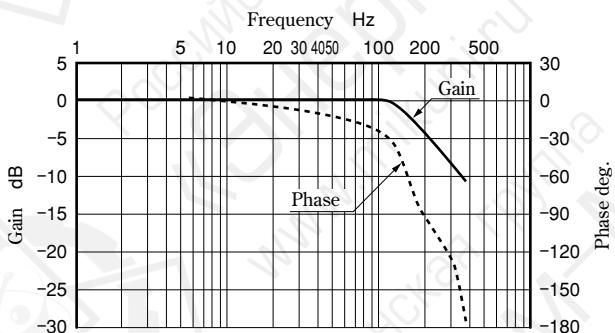
Hydraulic Circuit: Port A/B Closed Supply Pressure : 14 MPa

● LSVG-03-4/10/20/40-10

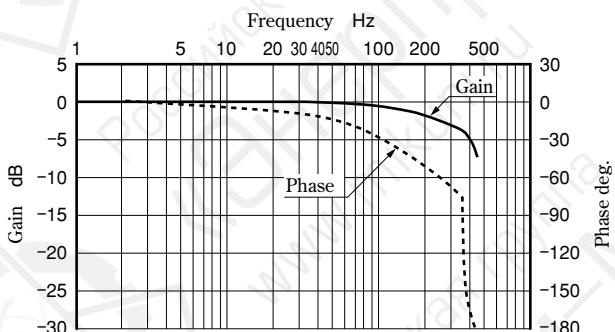
Amplifier : AMLS-A-D48-\* -10 (Power Supply: 48 V DC)  
Input Signal  $\pm 25\%$



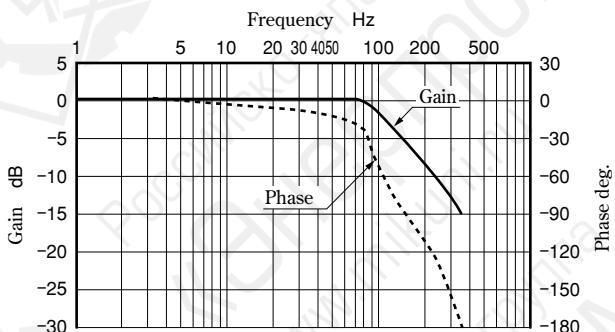
Input Signal  $\pm 100\%$



Amplifier : AMLS-A-D24-\* -10 (Power Supply: 24 V DC)  
Input Signal  $\pm 25\%$

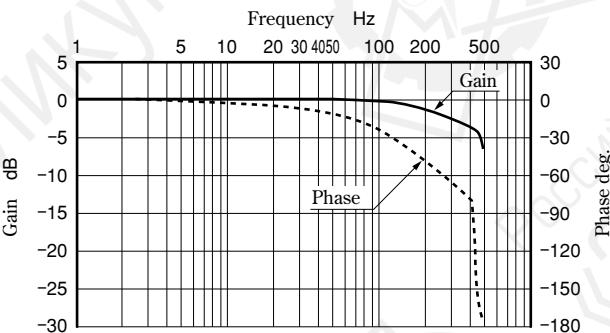


Input Signal  $\pm 100\%$

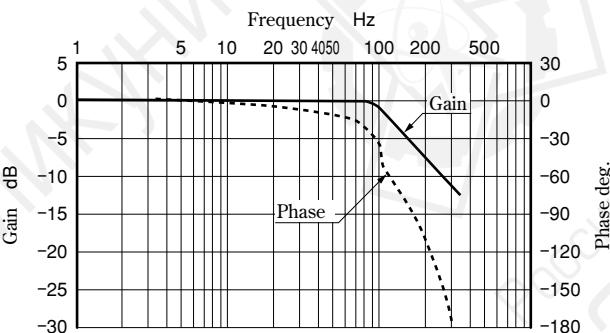


● LSVG-03-60-10

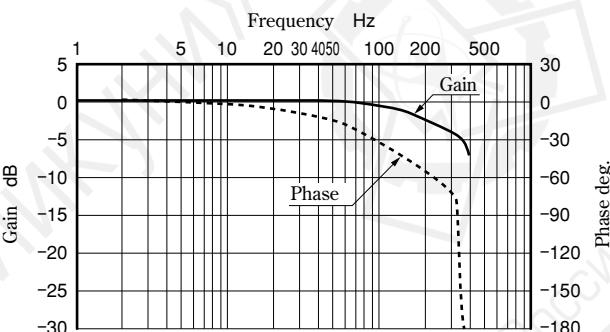
Amplifier : AMLS-B-D48-\* -10 (Power Supply: 48 V DC)  
Input Signal  $\pm 25\%$



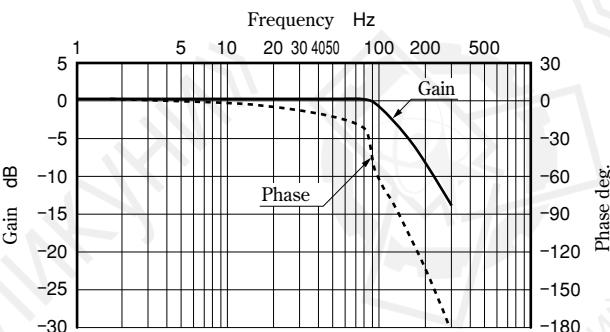
Input Signal  $\pm 100\%$



Amplifier : AMLS-B-D24-\* -10 (Power Supply: 24 V DC)  
Input Signal  $\pm 25\%$



Input Signal  $\pm 100\%$



## Tow Stage Type High-Speed Linear Servo Valves

Two stage type linear servo valves are a type of high-flow servo valve that has a direct type high speed linear servo valve in its pilot stage to drive the main spool. These valves control the positions of the pilot and main spools with electrical feedback, achieving high accuracy and response.

### High flow

The valves consist of two stages to provide a high flow rate (Rated flow at  $\Delta P = 7$  MPa: 750 - 3800 L/min).

### High accuracy

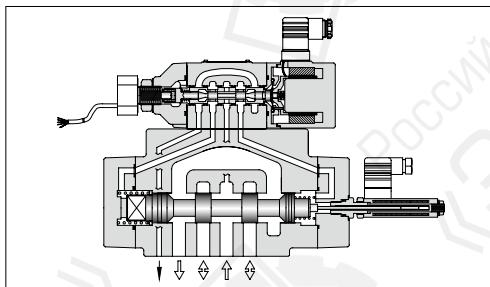
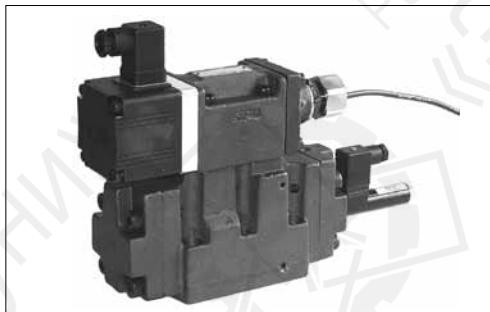
The valves have a low hysteresis of 0.1 % or less, achieving high accuracy. They allow the main unit to operate with much higher repeatability.

### High response characteristics

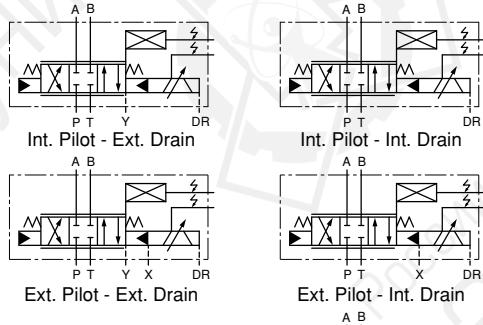
The valves provide significantly high levels of step and frequency responses, which are typically used as measures of response characteristics; the step response is 8 ms (0 <=> 100 %), and the frequency response is 105 Hz/-90° ( $\pm 25$  % amplitude) (Representative values for LSVHG-06-900). Thus, the valves ensure the achievement of unprecedented high response.

### Excellent contamination resistance

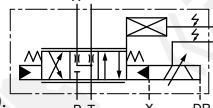
As is the case with the direct type linear servo valves, the permissible level of fluid contamination for these valves is up to NAS 1638 class 10.



**Graphic Symbols**



Note) The symbols above indicate the spool types "2" and "2P".  
The graphic symbol of the spool type "40" is shown on the right (external pilot/internal drain type).



### Model Number Designation

F—	LSVHG	—06	—900	—2P	—E	T	—R	—A	—10
Fluid Type	Series Number	Valve Size	Rated Flow @ $\Delta P = 7$ MPa	Spool Type	Pilot Connection	Drain Connection	Cable Departure Direction	Fail-safe Function	Design Number
F : Special Seals for Phosphate Ester Type Fluid (Omit if not required)	LSVHG : Two Stage Type High Speed Linear Servo Valves	04	750 : 750 L/min	2 : 10% Overlap  40 : Open Centre A, B & T  2P : Zero Lap  (Dual Flow Gain)	None : Internal Pilot	None : External Drain	(Viewed from the linear motor side) None : Upper (Standard)	None : P→B→A→T Position Valve Opening: Full	10
		06	900 : 900 L/min 1300 : 1300 L/min		E : External Pilot	T : Internal Drain	R : Right L : Left	A : P→A→B→T Position Valve Opening: Full	20
		10	3800 : 3800 L/min						

### Exclusive Amplifiers

To ensure stable performance, it is recommended to use Yuken's AMLS series linear servo amplifiers.

Valve Model Number	Amplifier Model
LSVHG-04-750	AMLS-C2-D * - * -10
LSVHG-06-900	AMLS-C-D * - * -10
LSVHG-06-1300 LSVHG-10-3800	AMLS-D-D * - * -10

### Attachment

Model Number	Mounting Bolt	Qty.	Bolt Tightening Torque
LSVHG-04	Hex. Soc. Head Cap Screw:M 6 × 55L	2	12.9 - 15.9 Nm
	Hex. Soc. Head Cap Screw:M 10 × 60L	4	60.6 - 74.1 Nm
LSVHG-06	Hex. Soc. Head Cap Screw:M 12 × 85L	6	104 - 127 Nm
LSVHG-10	Hex. Soc. Head Cap Screw:M 20 × 90L	6	494 - 603 Nm

### ■ Specifications

The specifications below are for use with a 48 V DC type exclusive amplifier; for use with a 24 V DC type amplifier, see the values in parentheses ( ).

Model Numbers		LSVHG-04-750	LSVHG-06-900	LSVHG-06-1300	LSVHG-10-3800												
Description																	
Rated Flow @ $\Delta P = 7 \text{ MPa}$ (4-Way Valve)	L/min	750	900	1300	3800												
Rated Flow @ $\Delta P' = 0.5 \text{ MPa}$ (per Land)	L/min	283	340	490	1440												
Max. Operating Pressure	MPa	35	35	31.5	35												
Proof Pres. at Return Port	External Drain MPa	31.5	35	25	28												
	Internal Drain <sup>(1)</sup> MPa	31.5	35	25	28												
DR Port Permissible Back Pressure <sup>(2)</sup>	MPa	0.05															
Pilot Pressure <sup>(3)</sup>	MPa	1.5 - 35															
Pilot Flow Rate <sup>(4)</sup>	L/min	27 (22) or more	30 (24) or more	34 (27) or more	32 (27) or more												
Pilot Valve Max. Leakage	Ps=Pp=14 MPa 32 mm <sup>2</sup> /s	L/min	1.7														
Main Valve Max. Leakage	Spool Type Ps=Pp=14 MPa 32 mm <sup>2</sup> /s	L/min	-2-	-40-	-2P-	-2-	-40-	-2P-	-2-	-40-	-2P-						
	0.8	1.6	6.8	0.9	1.8	7	1	2	8	3	6						
Hysteresis	%	0.1 or less															
Step Response (0 <=> 100 %, Typical) <sup>(5)</sup>	ms	8 (10)		8 (10)		10 (13)		15 (18)									
Frequency Response ( $\pm 25\%$ Amplitude, Typical) <sup>(5)</sup>	Gain: -3 dB Phase: -90°	Hz	150 (140)	160 (130)	150 (110)	100 (60)	100 (100)	85 (75)									
Vibration Proof <sup>(6)</sup>	Frequency: 10 - 60 Hz, Amplitude: 4 mm, Acceleration: 7.8 - 282 m/s <sup>2</sup> Frequency: 61 - 2000 Hz, Amplitude: 4 - 0.0038 mm, Acceleration: 294 m/s <sup>2</sup>																
Protection	IP 64																
Ambient Temperature	°C	-15 - +60															
Spool Stroke to Stops	mm	±5		±5		±7		±7									
Spool End Area	cm <sup>2</sup>	7.1		8		8		11.3									
Polarity	See the description about I/O signal characteristics on page 18.																
Linear Motor Specification	Current Coil Resistance	A Ω	2 [Max. 6 ]				4.5										
質量	kg	12		20		21		78									

Note: <sup>(1)</sup> Pressure at the return port should be at actual supply pressure or less.

<sup>(2)</sup> Back pressure at the drain port should be 0.05 MPa or less and not be a negative pressure.

<sup>(3)</sup> Supply pressure for the pilot valve should be 1.5 to 35 MPa (1.5 to 25 MPa for LSVHG-10) and should also be 60 % of actual supply pressure or more.

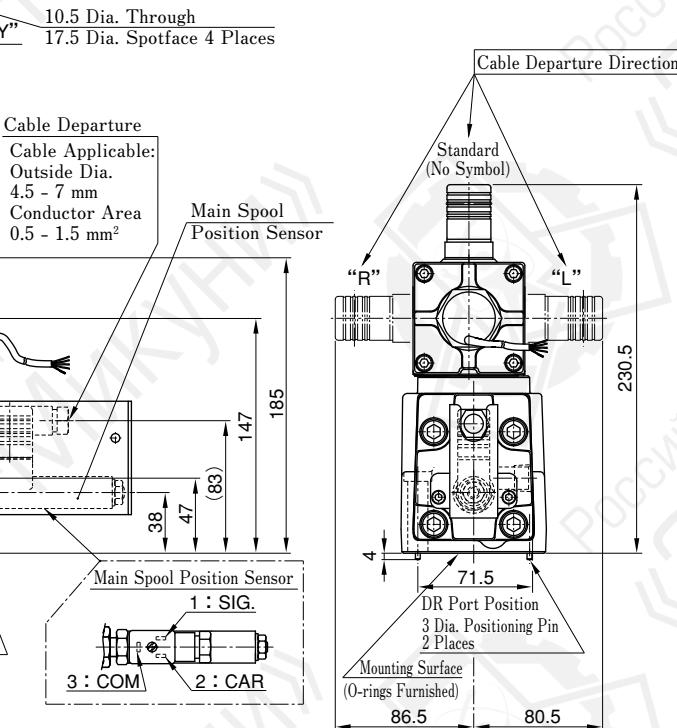
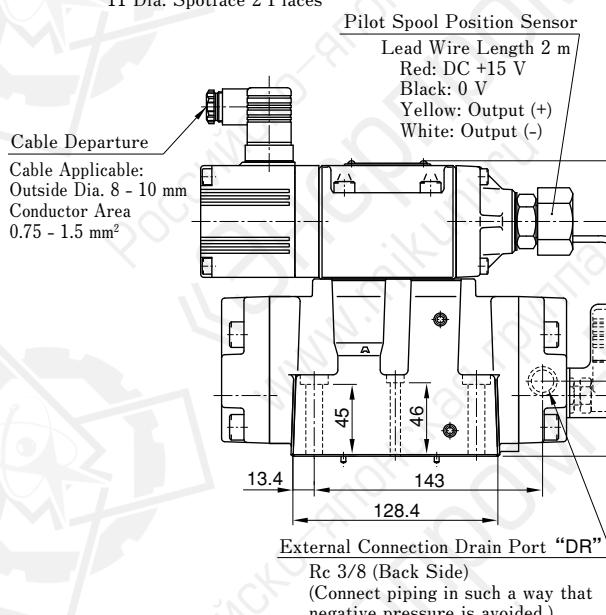
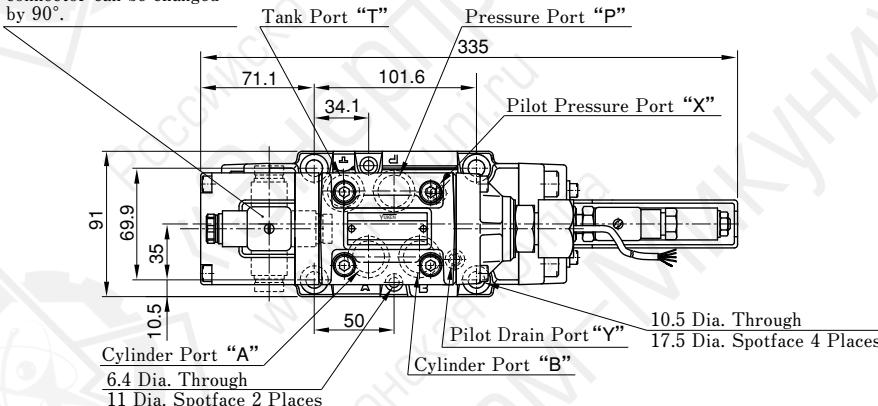
<sup>(4)</sup> The pilot flow is calculated based on a pilot pressure of 14 MPa and the above step response.

<sup>(5)</sup> This value is measured for each valve based on a pilot pressure of 14 MPa; it may vary depending on the actual circuit/operation conditions.

<sup>(6)</sup> There are restrictions on the mounting position; refer to the instructions for details.

**LSVHG-04**

The direction of the DIN connector can be changed by 90°.



Note) Refer to the wiring diagram on page 20 for detailed connection between the pilot valve DIN connector/position sensors (pilot and main spools) and the amplifier.

**[Mounting Surface]**

Prepare a mounting surface shown on the right. Basically, the dimensions of the mounting surface conform to the ISO standard, but the specifications for the ports P, A, B, and T are different as follows.

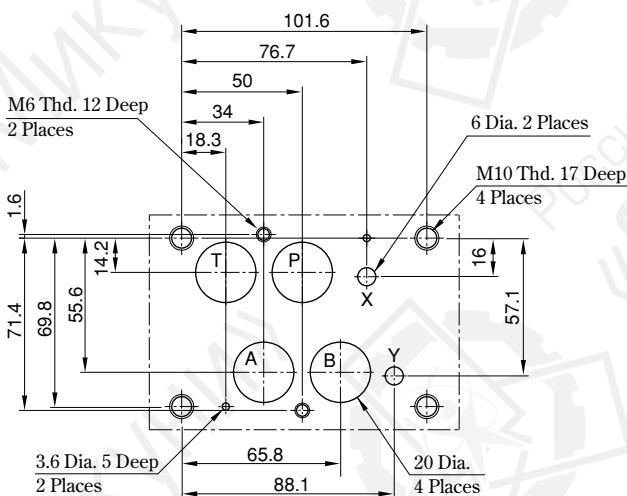
	ISO 4401-07-06-0-94	Mounting Surface for LSVHG-04
Dia. of Port P, A, B, T	17.5 Dia.	20 Dia.

The mounting surface should have a good machined finish.

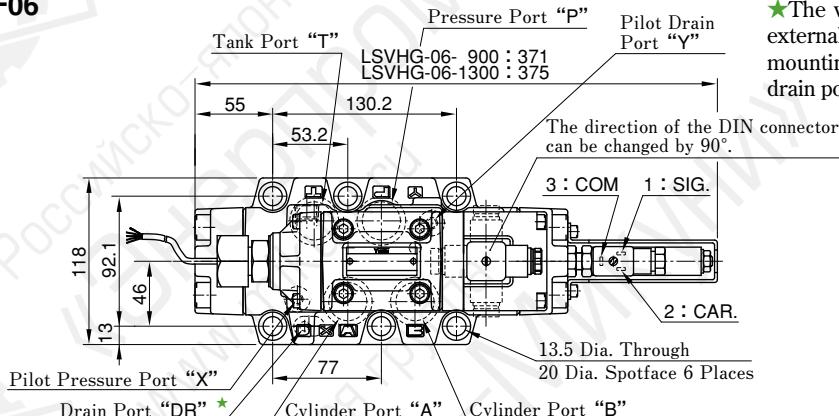
**● O-rings for the Ports**

Port	O-ring Size	Qty.
P, A, B, T	JIS B2401-1B-P22	4
X, Y	AS568-012 (NBR, Hs90)	2

O-rings made of fluorinated rubber are required to use phosphate ester type fluids.



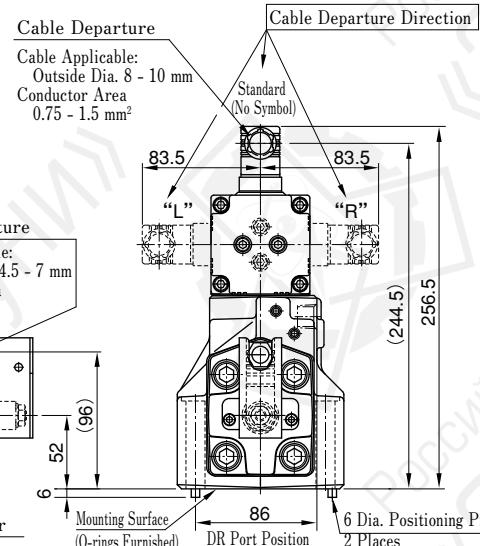
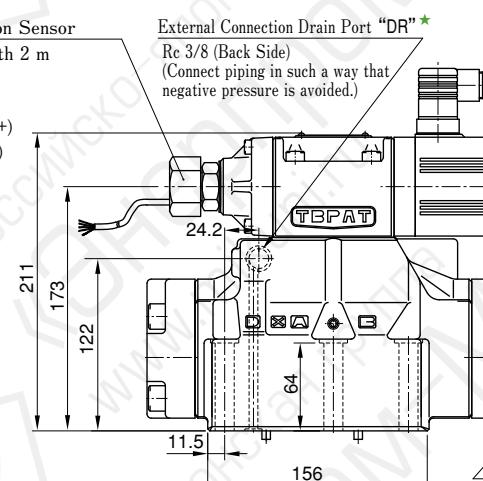
## LSVHG-06



★The valve has two "DR" ports: one for external connection and the other on the mounting surface. Use either one of the drain ports.

Pilot Spool Position Sensor  
Lead Wire Length 2 m  
Red: DC +15 V  
Black: 0 V  
Yellow: Output (+)  
White: Output (-)

External Connection Drain Port "DR"★  
Re 3/8 (Back Side)  
(Connect piping in such a way that negative pressure is avoided.)



Note) Refer to the wiring diagram on page 20 for detailed connection between the pilot valve DIN connector/position sensors (pilot and main spools) and the amplifier.

### [Mounting Surface]

Prepare a mounting surface shown on the right. Basically, the dimensions of the mounting surface conform to the ISO standard, but the specifications for the ports P, A, B, and T are different as follows.

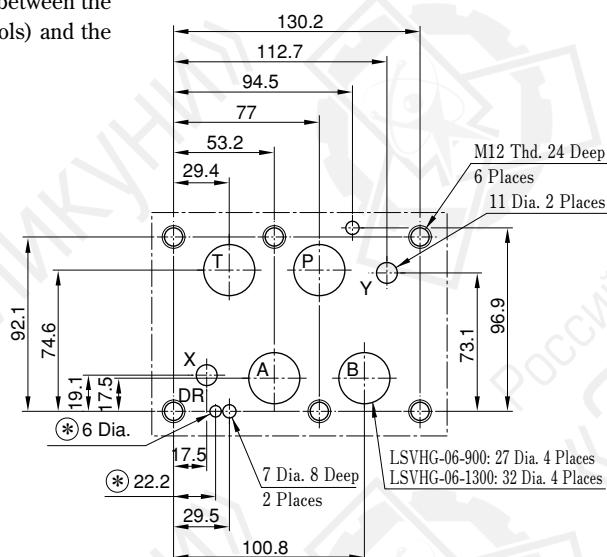
	ISO 4401-08-07-0-94	Mounting Surface for LSVHG-06-900	Mounting Surface for LSVHG-06-1300
Dia. of Port P, A, B, T	23.4 Dia.	27 Dia.	32 Dia.
Drain Port	None	Available (6 Dia.)	

The mounting surface should have a good machined finish.

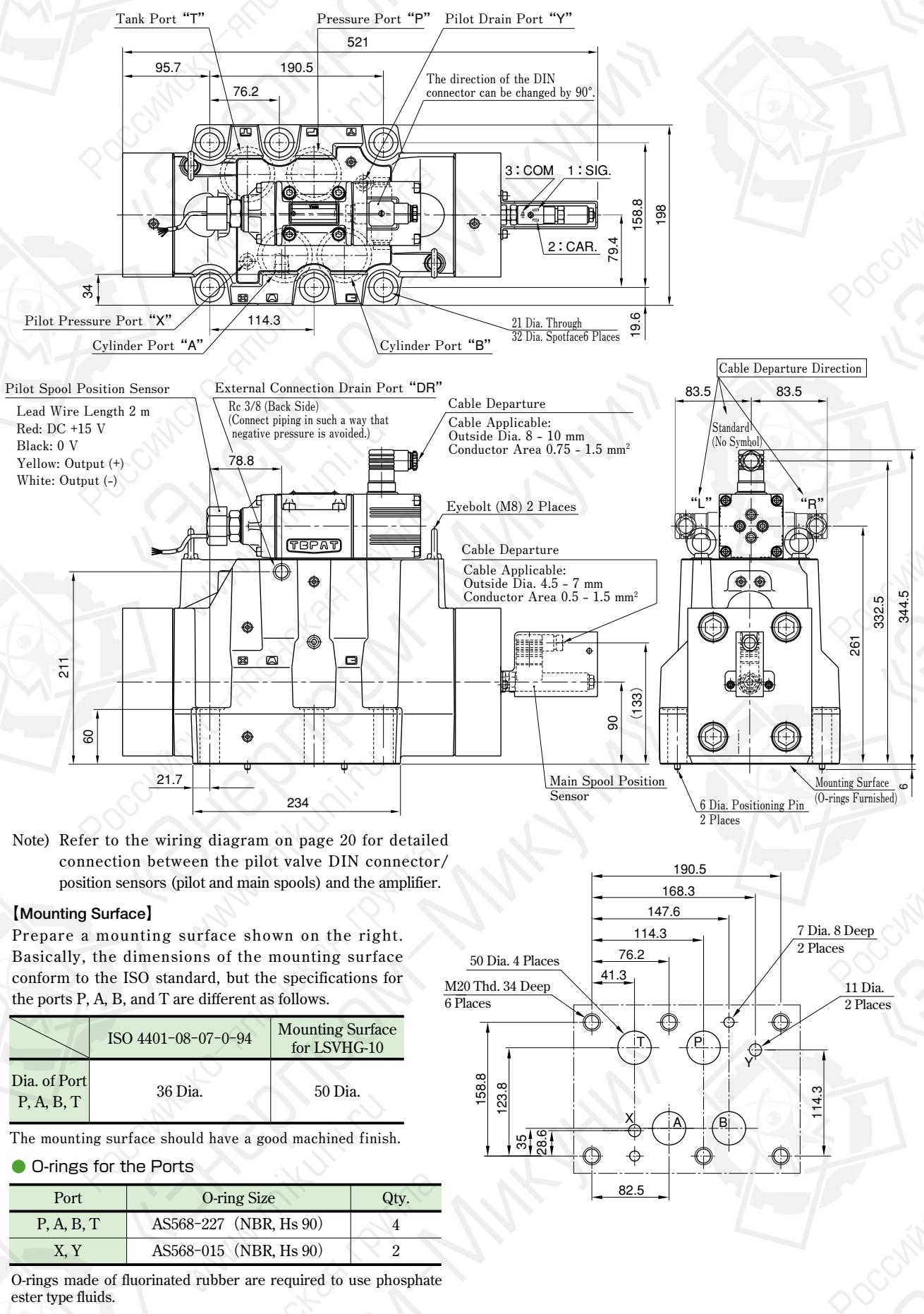
### ● O-rings for the Ports

Port	O-ring Size		Qty.
	LSVHG-06-900	LSVHG-06-1300	
P, A, B, T	AS568-123 (NBR, Hs90)	AS568-126 (NBR, Hs90)	4
X, Y	JIS B2401-1B-P14		2
DR	AS568-016 (NBR, Hs90)		1

O-rings made of fluorinated rubber are required to use phosphate ester type fluids.



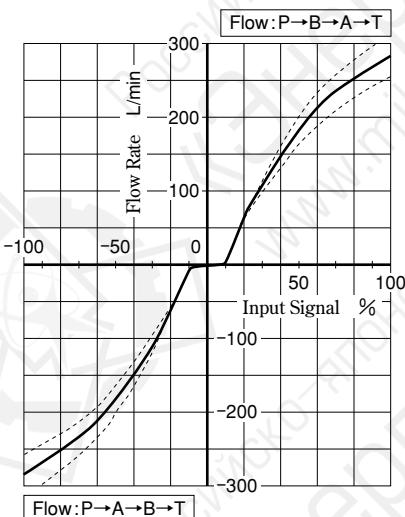
Note) ⑧: Not required if the external connection drain port is used.

**LSVHG-10**

## Characteristics of LSVHG-04-750 (Fluid Viscosity: 30 mm<sup>2</sup>/s)

### No-Load Flow Characteristics

Conditions Valve Pressure Difference : 1 MPa (Pressure Difference per Land : 0.5 MPa)

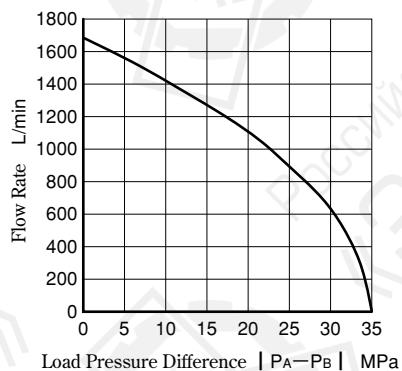
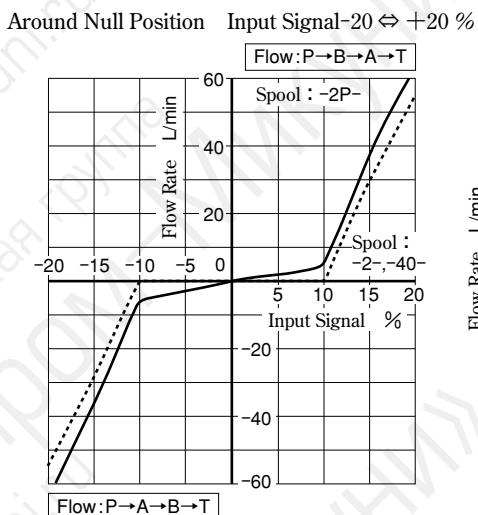


### Load Flow Characteristics

Conditions

Input Signal : 100 %

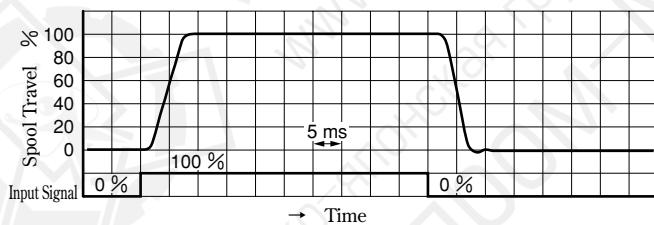
Note) Tolerance for Load Flow



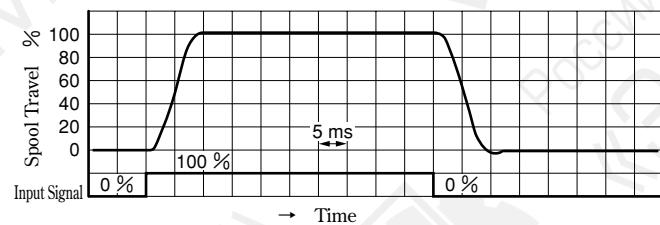
### Step Response

Conditions Input Signal : 0 ⇔ 100 % Supply/Pilot Pressure : 14 MPa

Amplifier: AMLS-C2-D48-\*10 (Power Supply: 48 V DC)



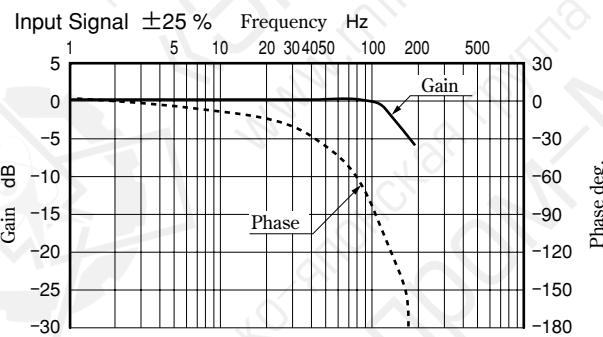
Amplifier: AMLS-C2-D24-\*10 (Power Supply: 24 V DC)



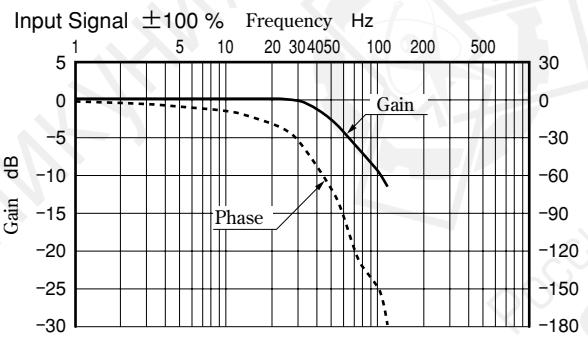
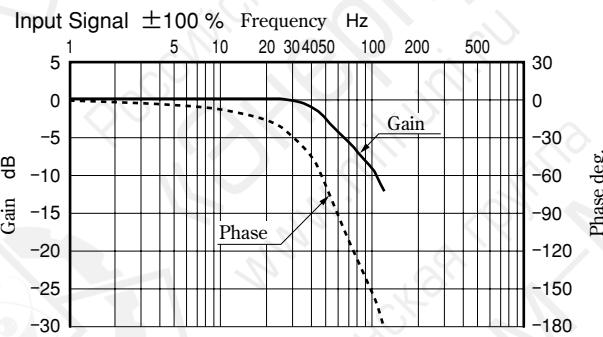
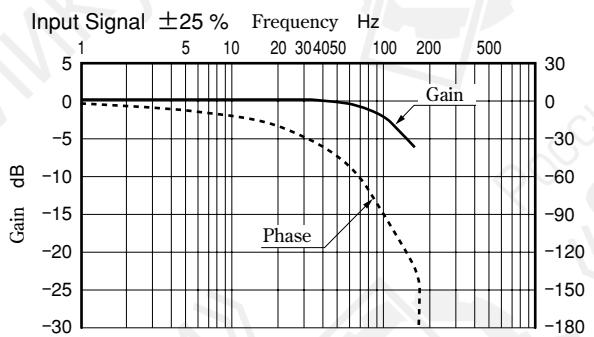
### Frequency Response

Conditions Hydraulic Circuit: Port A/B Closed Supply/Pilot Pressure : 14 MPa

Amplifier: AMLS-C2-D48-\*10 (Power Supply: 48 V DC)



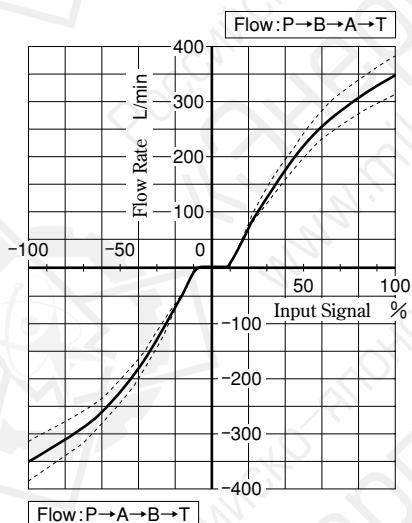
Amplifier: AMLS-C2-D24-\*10 (Power Supply: 24 V DC)



## Characteristics of LSVHG-06-900 (Fluid Viscosity: 30 mm<sup>2</sup>/s)

### No-Load Flow Characteristics

Conditions Valve Pressure Difference : 1 MPa (Pressure Difference per Land : 0.5 MPa)

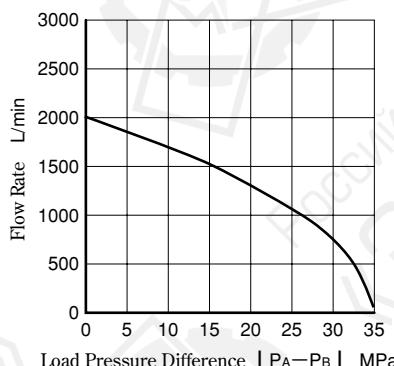
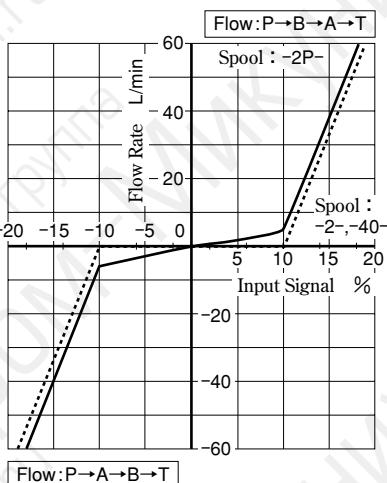


### Load Flow Characteristics

Conditions

Input Signal : 100 %

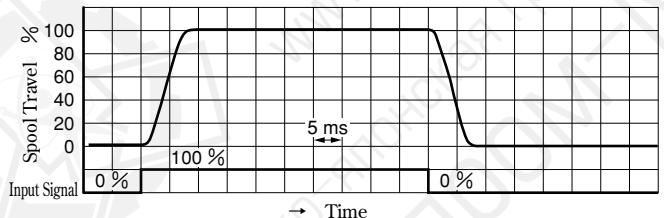
Around Null Position Input Signal -20 ⇔ +20 % Note Tolerance for Load Flow : ±10 %



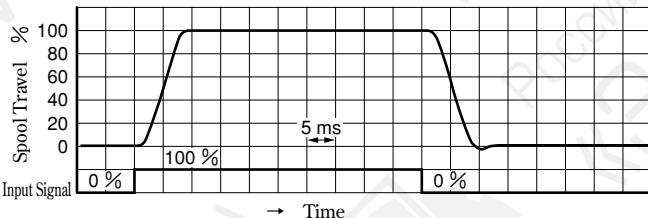
### Step Response

Conditions Input Signal : 0 ⇔ 100 % Supply/Pilot Pressure : 14 MPa

Amplifier : AMLS-C-D48-\*10 (Power Supply: 48 V DC)



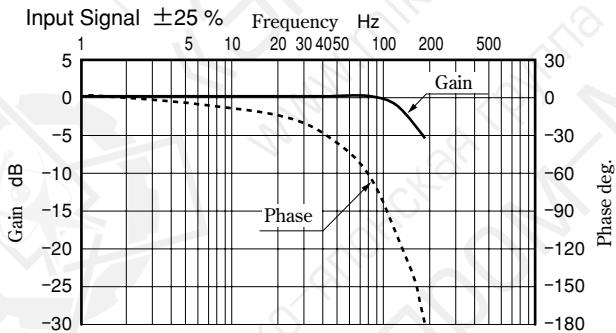
Amplifier: AMLS-C2-D24-\*10 (Power Supply: 24 V DC)



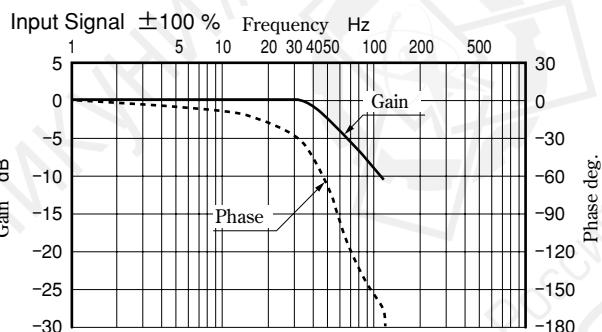
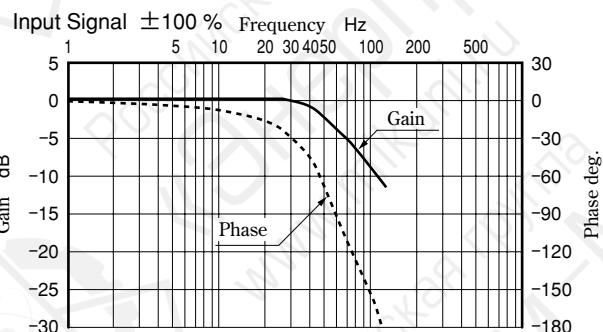
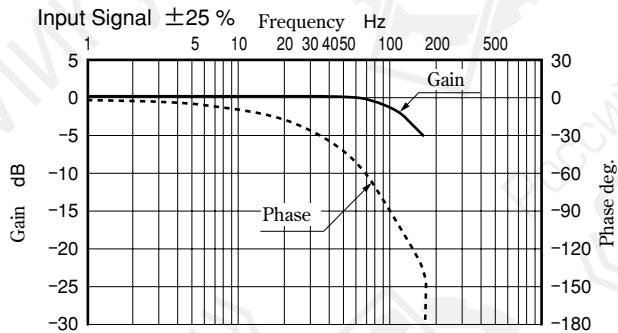
### Frequency Response

Conditions Hydraulic Circuit: Port A/B Closed Supply/Pilot Pressure : 14 MPa

Amplifier : AMLS-C-D48-\*10 (Power Supply: 48 V DC)



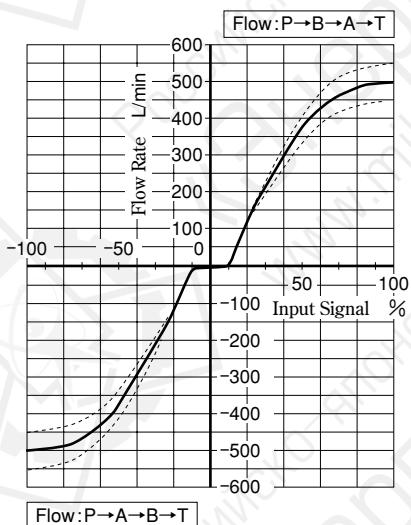
Amplifier : AMLS-C-D24-\*10 (Power Supply: 24 V DC)



## Characteristics of LSVHG-06-1300 (Fluid Viscosity: 30 mm<sup>2</sup>/s)

### No-Load Flow Characteristics

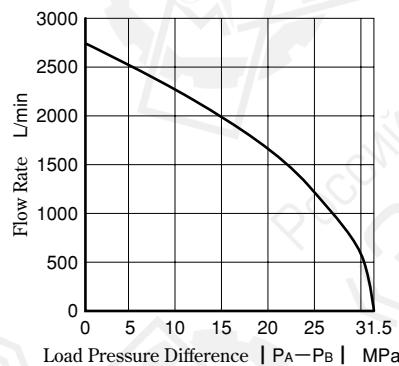
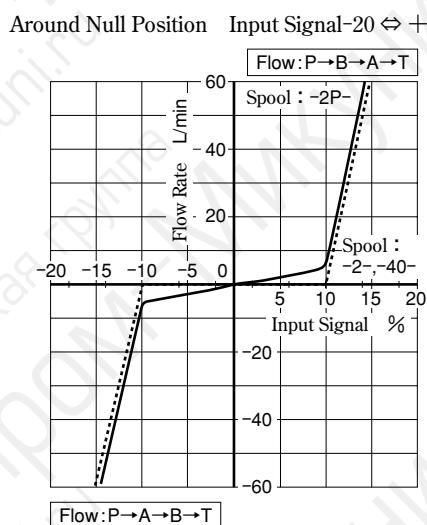
Conditions Valve Pressure Difference: 1 MPa (Pressure Difference per Land : 0.5 MPa)



### Load Flow Characteristics

Conditions Input Signal : 100 %

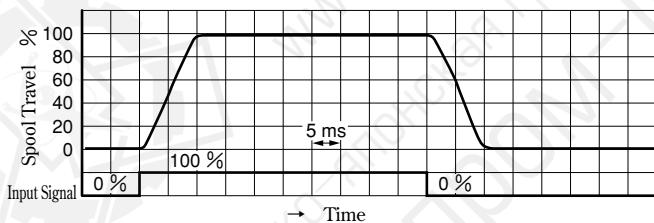
Note) Tolerance for Load Flow : ±10 %



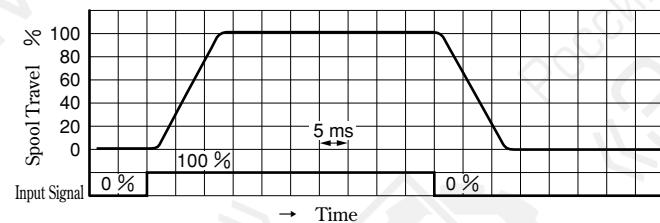
### Step Response

Conditions Input Signal : 0 ⇌ 100 % Supply/Pilot Pressure : 14 MPa

Amplifier : AMLS-D-D48-\* -10 (Power Supply: 48 V DC)



Amplifier : AMLS-D-D24-\* -10 (Power Supply: 24 V DC)

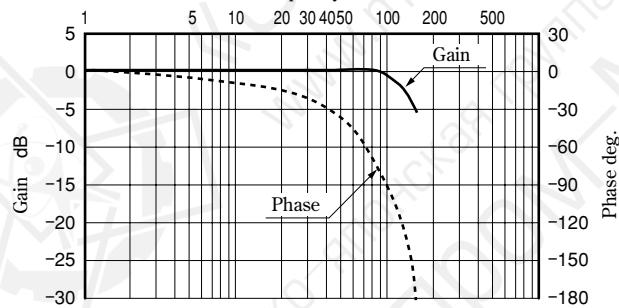


### Frequency Response

Conditions Hydraulic Circuit: Port A/B Closed Supply/Pilot Pressure : 14 MPa

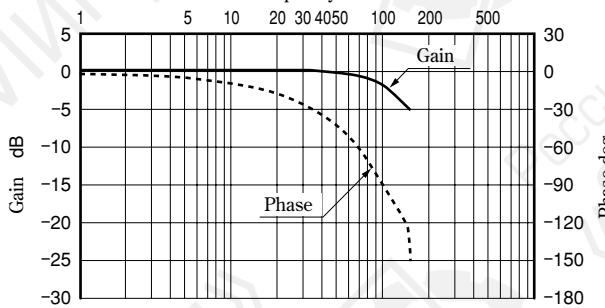
Amplifier : AMLS-D-D48-\* -10 (Power Supply: 48 V DC)

Input Signal ±25 % Frequency Hz

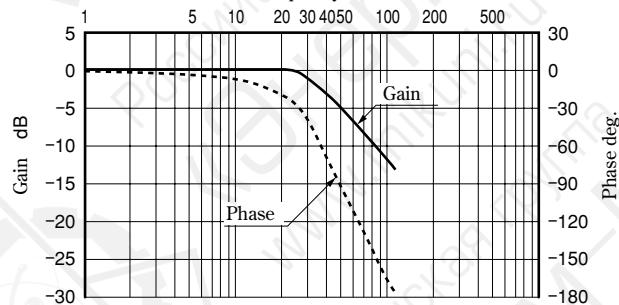


Amplifier : AMLS-D-D24-\* -10 (Power Supply: 24 V DC)

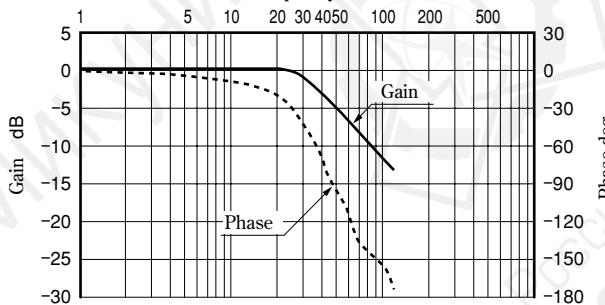
Input Signal ±25 % Frequency Hz



Input Signal ±100 % Frequency Hz



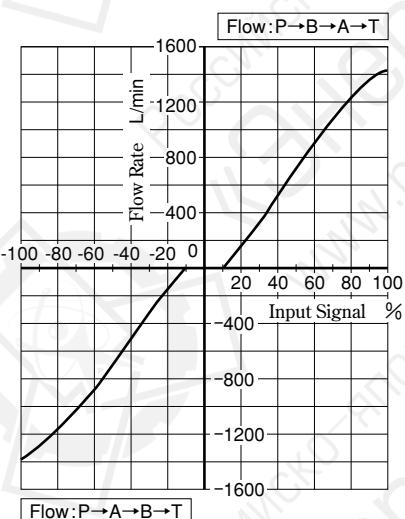
Input Signal ±100 % Frequency Hz



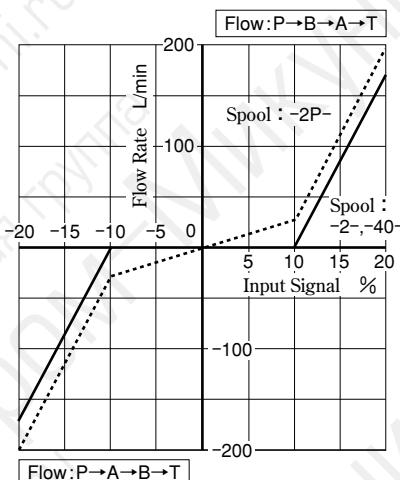
## Characteristics of LSVHG-10-3800 (Fluid Viscosity: 30 mm<sup>2</sup>/s)

### No-Load Flow Characteristics

Conditions Valve Pressure Difference : 1 MPa (Pressure Difference per Land : 0.5 MPa)



Around Null Position Input Signal-20 ⇄ +20 %

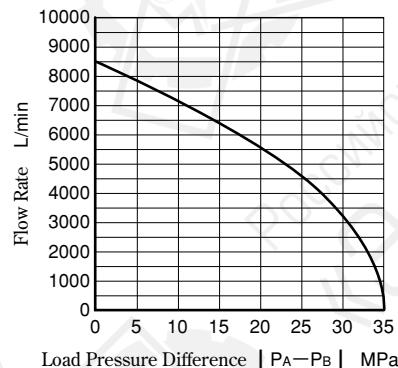


### Load Flow Characteristics

Conditions

Input Signal : 100 %

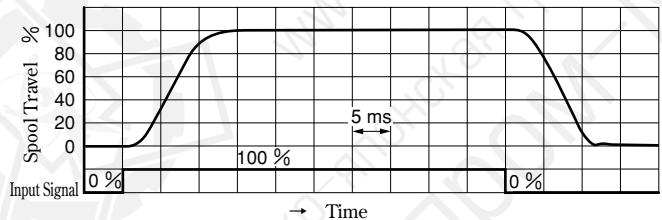
Note) Tolerance for Load Flow : ±10 %



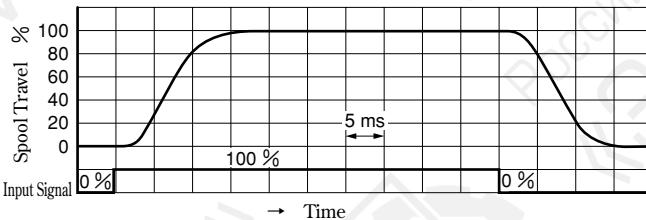
### Step Response

Conditions Input Signal : 0 ⇄ 100 % Supply/Pilot Pressure : 14 MPa

Amplifier: AMLS-D-D48-\*10 (Power Supply: 48 V DC)



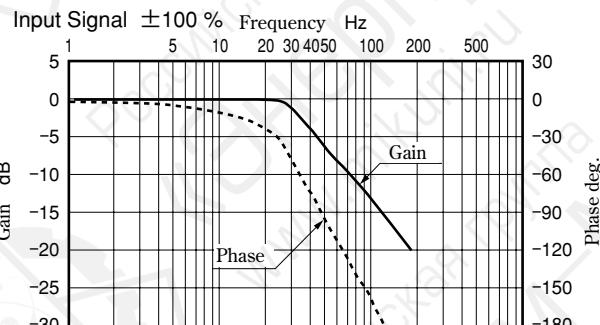
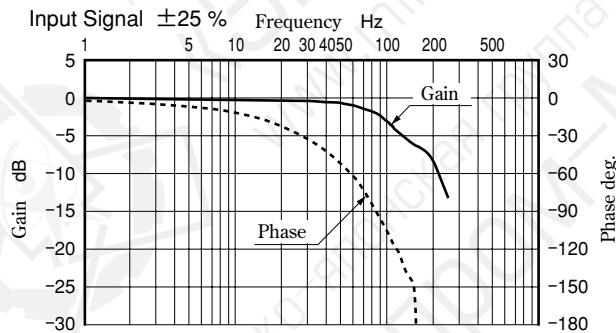
Amplifier: AMLS-D-D24-\*10 (Power Supply: 24 V DC)



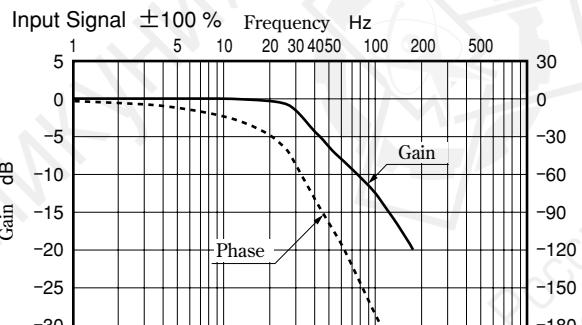
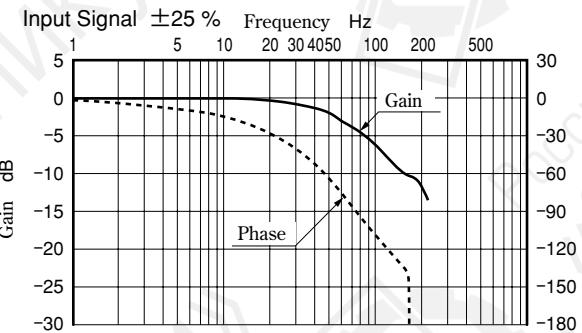
### Frequency Response

Conditions Hydraulic Circuit: Port A/B Closed Supply/Pilot Pressure : 14 MPa

Amplifier: AMLS-D-D48-\*10 (Power Supply: 48 V DC)



Amplifier: AMLS-D-D24-\*10 (Power Supply: 24 V DC)



# Linear Servo Amplifier

This amplifier is used to drive LSVG/LSVHG series high speed linear servo valves. With an optimal design for the servo valves, the amplifier can maximize the valve performance.



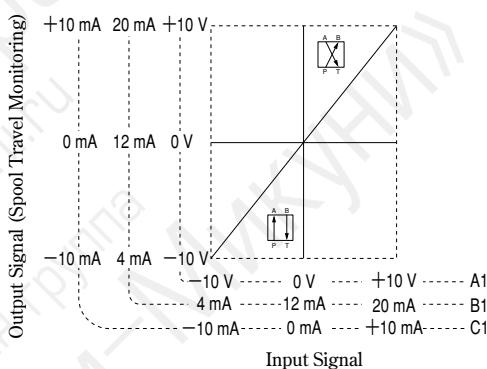
## Specifications

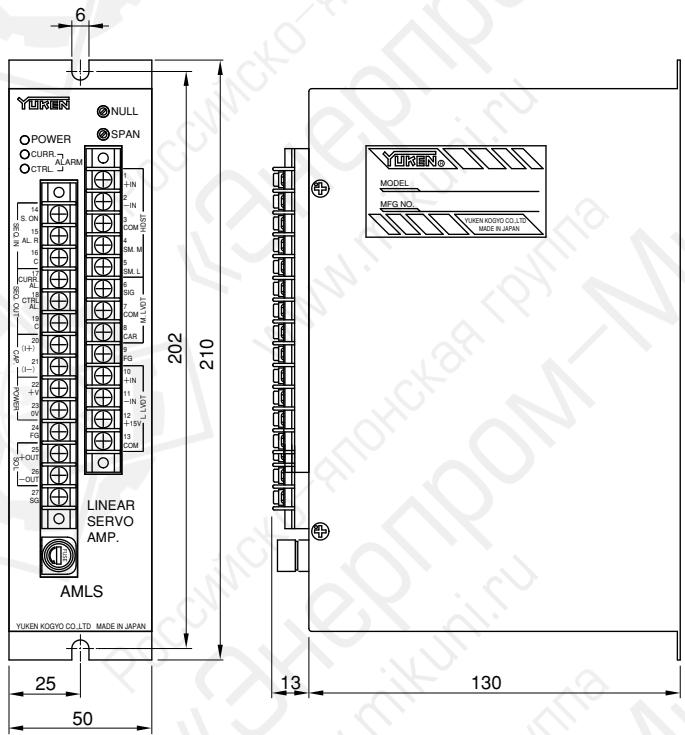
Model Numbers	AMLS-* -D48-* -10	AMLS-* -D24-* -10
Description		
Power Supply	48 V $\pm$ 2.4 V DC (200 VA or more)	24 V $\pm$ 1.2 V DC (100 VA or more)
Rated Output Current	Continuous $\pm$ 2 A (4 A Peak)	Continuous $\pm$ 2 A (3 A Peak)
Input/Output Signal	Output Signal = Spool Travel Monitoring A1 : Voltage Signal $\pm$ 10 V ( $R_i = 100 \text{ k}\Omega$ , $R_L \geq 10 \text{ k}\Omega$ ) B1 : Current Signal 4 - 20 mA ( $R_i = 200 \Omega$ , $R_L = 100 - 500 \Omega$ ) C1 : Current Signal $\pm$ 10 mA ( $R_i = 200 \Omega$ , $R_L = 100 - 500 \Omega$ )	
Control Input /Output Signal	a) Servo "ON" Input/Alarm Reset Input: Photocoupler Input Voltage: +15 V DC to +28 V DC, Input Impedance: 2.2 k $\Omega$ b) Overcurrent Output (CURRAL.)/Deviation Alarm Output (CRTLAL.): Photocoupler Output Voltage: Max. 50 V DC, Current: Max. 30 mA	
Ambient Temperature	0 - 50 °C	
Ambient Humidity	20 - 90 %Rh (No Condensation)	
Mass	1.8 kg	

## Model Number Designation

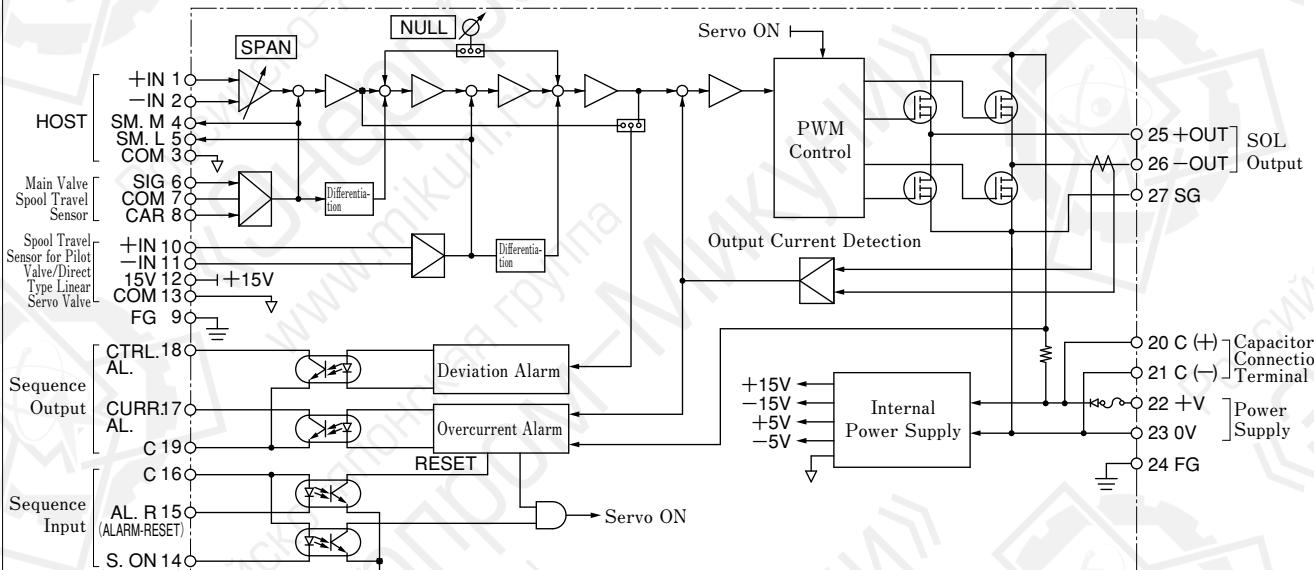
AMLS	-A	-D48	-A1	-10
Series Number	Applicable Valve Type	Supply Voltage	Input Signal/ Spool Travel Monitoring	Design Number
AMLS : Linear Servo Amplifier	<b>A</b> : LSVG-03-4/10/20/40 <b>B</b> : LSVG-03-60 <b>C</b> : LSVHG-06-900 <b>C2</b> : LSVHG-04 <b>D</b> : LSVHG-06-1300 LSVHG-10-3800	<b>D48</b> : DC 48 V <b>D24</b> : DC 24 V	<b>A1</b> : Voltage Signal $\pm$ 10 V <b>B1</b> : Current Signal 4 - 20 mA <b>C1</b> : Current Signal $\pm$ 10 mA	10

## I/O Signal Characteristics



**Appearance/Terminal Names****Terminal Name**

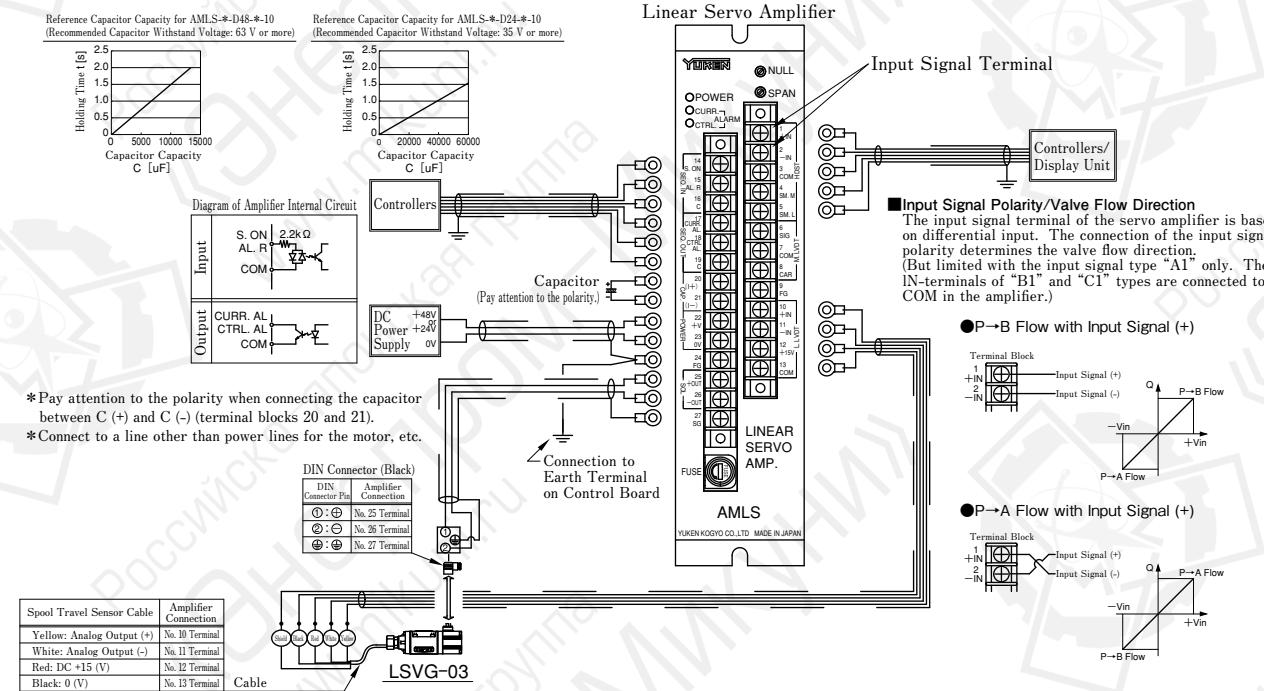
No.	Terminal Name	
1	Input Signal	+IN
2		-IN
3	Common	COM
4	Sensor	Main Valve Spool
5	Monitoring	SM. M
6		SM. L
7	Main Valve Spool Travel Sensor	SIG
8		CAR
9	Frame Grounding	FG
10		+IN
11	Spool Travel Sensor for Pilot	-IN
12	Valve/Direct Type Linear Servo Valve	+15V
13		COM
14	Sequence Input	S. ON
15		Alarm Reset
16		Input Common
17	Sequence Output	Overcurrent Alarm
18		Deviation Alarm
19		Output Common
20		Capacitor Connection Terminal
21		Cap. (-)
22		+V
23		0V
24		FG
25		+OUT
26		-OUT
27		SG

**Block Diagram**

## Wire Connection Diagram

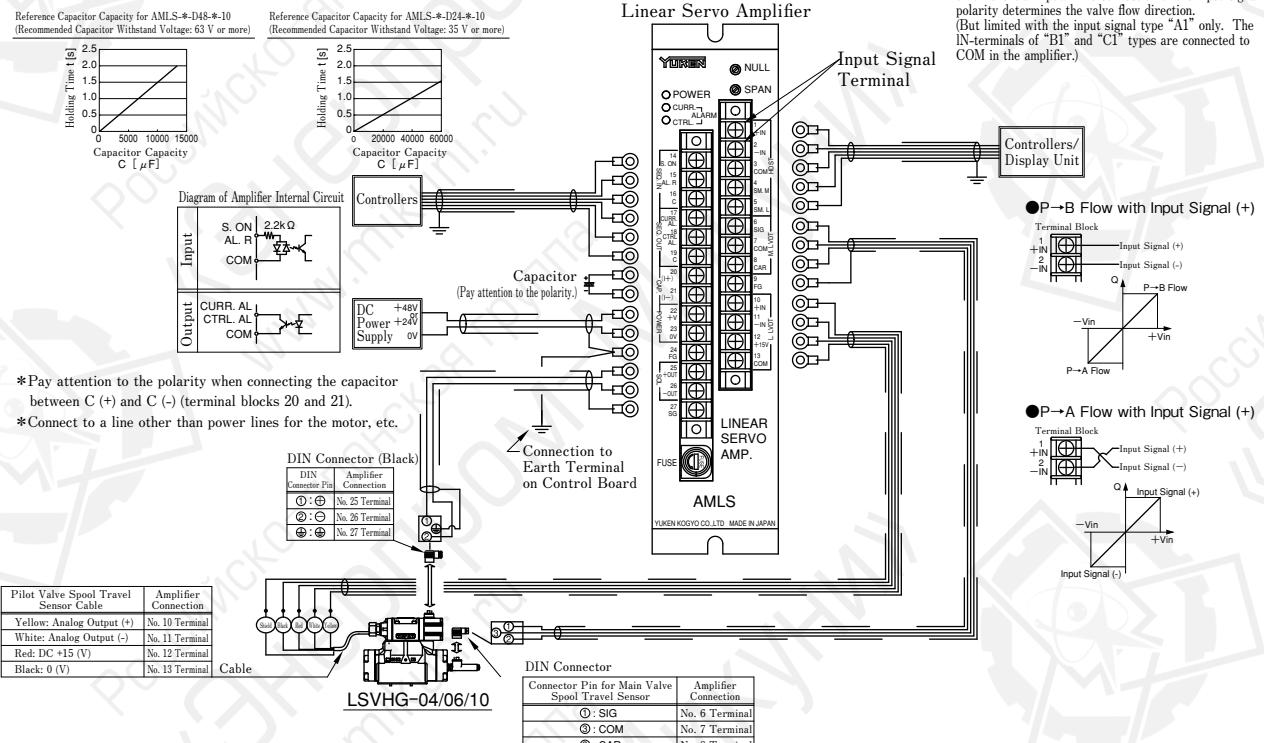
### ●AMLS-A,AMLS-B

\* To hold the valve spool at the neutral position for a few seconds upon power failure or after power-off, connect the capacitor between C (+) and C (-) (terminal blocks 20 and 21).



### ●AMLS-C, AMLS-C2, AMLS-D

\* To hold the valve spool at the neutral position for a few seconds upon power failure or after power-off, connect the capacitor between C (+) and C (-) (terminal blocks 20 and 21).



## OBE type Direct Operated Linear Servo Valves

On-board electronics (OBE) type direct operated linear servo valves are based on high speed linear servo valves (LSVG) and OBE type linear servo valves (LSVHG-\*EH), providing "high accuracy, easiness to use, and great usability".



### High accuracy

As is the case with the high speed linear servo valves, all of the OBE type direct operated linear servo valves have a low hysteresis of 0.1 % or less, realizing high accuracy. These valves allow the main unit to operate with much higher repeatability.

### High response characteristics

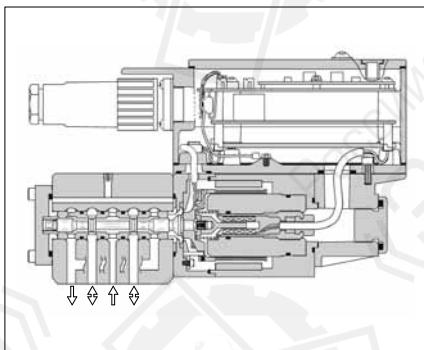
Compared to other equivalent models, these valves provide higher levels of step and frequency responses, which are typically used as measures of response characteristics; the step response is 3 ms (0 <= 100 %)\*, and the frequency response is 260 Hz/-3 dB ( $\pm 25\%$  amplitude)\*.

[★ : Representative values for LSVG-03EH with the Y port (dry type)]

### Easiness to use

These valves can offer high accuracy for hydraulic control systems just with 24 V DC power supply and command signal input.

Six types of input signals in three input voltage/current ranges are available: 0 -  $\pm 10$  V, 0 -  $\pm 10$  mA, and 4 - 20 mA.



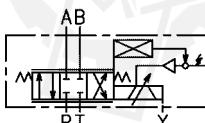
### Great usability

The small amplifier in the valves has a fault indicator lamp. This lamp indicates an error when valve failure causes any deviation between the spool position commanded by the signal and the actual spool position. It facilitates you to immediately troubleshoot the failure of the valves, if any.

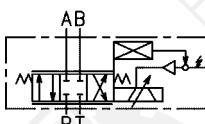
### Excellent contamination resistance

As is the case with the high speed linear servo valves, the OBE type direct operated linear servo valves have a simple pilot valve structure, exhibiting excellent contamination resistance. The permissible level of fluid contamination for these valves is up to NAS 1638 class 10.

### Graphic Symbols



With Y Port (Dry Type)



Without Y Port (Wet Type)

### Model Number Designation

F-	LSVG	-03	EH	-60	-W	A	-A	1	-10	
Fluid Type	Series Number	Valve Size	Amp. Type	Rated Flow @ $\Delta P=7$ MPa	Drain Port and Permissible Back Pres.	Fail-safe Function	Input Signal/Spool Travel Monitoring	Connector Type	Design Number	
F : Special Seals for Phosphate Ester Type Fluid (Omit if not required)	LSVG : Direct Operated Linear Servo Valves	01	EH : OBE Type	4: 4 L/min	None: With Y Port (Permissible Back Pres.: 0.05 MPa) (Dry Type)	A: P→A→B→T Position  B: P→B→A→T Position  C: Neutral	A: Voltage Signal $\pm 10$ V (P→B→A→T Flow with Input Signal (+))  B: Current Signal 4 - 20 mA (P→B→A→T Flow with Current Signal 12 - 20 mA)  C: Current Signal $\pm 10$ mA (P→B→A→T Flow with Input Signal (+))  D: Voltage Signal $\pm 10$ V (P→A→B→T Flow with Input Signal (+))  E: Current Signal 4 - 20 mA (P→A→B→T Flow with Current Signal 12 - 20 mA)  F: Current Signal $\pm 10$ mA (P→A→B→T Flow with Input Signal (+))	1: 6 + PE Pole	10 10 1006 (Mounting bolt: M6)	
		03		10: 10 L/min						
				20: 20 L/min						
				40: 40 L/min						
				60: 60 L/min						

\* For the wet type, water-glycol fluids cannot be used.

# Linear Servo Valves

**Specifications** The values in parentheses in the specification table below are applicable to the models "LSVG-\*EH-\*W\*" (wet type).

Model Numbers		LSVG-01EH-4-*	LSVG-01EH-10-*	LSVG-01EH-20-*	LSVG-03EH-40-*	LSVG-03EH-60-*
Description						
Rated Flow at $\Delta P = 7 \text{ MPa}$ <sup>(1)</sup>	L/min	4	10	20	40	60
Max. Operating Pressure	MPa		35		35 <sup>(2)</sup>	
Proof Pres. at Return Port	MPa		21 (7)		35 <sup>(2)</sup> (7)	
Drain Port (Y Port) Permissible Back Pres. <sup>(3)</sup>	MPa			0.05 (No Y Port for Wet Type)		
Internal Leakage $(P_s = 14 \text{ MPa})$ Max. Leakage (Viscosity: 32 mm <sup>2</sup> /s)	L/min	0.4 or less	0.8 or less	1.2 or less	1.7 or less	
Hysteresis	%			0.1 or less		
Step Response $[P_2 = 14 \text{ MPa}]$ (Typical) <sup>(4)</sup>	ms		3 (3.5)			4 (4.5)
Frequency Response (±25 % Amplitude) (Typical) <sup>(4)</sup>	Gain: -3 dB Hz	240 (230)		260 (240)	250 (220)	
	Phase: -90° Hz	300 (270)		310 (310)	260 (220)	
Vibration Proof	m/s <sup>2</sup>		100			
Protection			IP 65			
Ambient Temperature	°C		0 - + 50			
Spool Stroke to Stops	mm		± 0.5		± 0.75	
Polarity		See the description about I/O signal characteristics on page 23.				
Linear Motor Specification	Current A		1.5 (Max. 3.2)			
	Coil Resistance Ω		7 at 20 °C			
Approx. Mass	kg	4.3		5.2		
Electric Connection		6 + PE/11 + PE Connector				

Note: <sup>(1)</sup> Use the valves so that the relationship between the valve pressure difference and the flow rate, as specified below in "Range of Flow Control", is met.

<sup>(2)</sup> For LSVG-03EH-\*-\*-\*-\*1006 (mounting bolt: M6), the pressure should be 31.5 MPa.

<sup>(3)</sup> Back pressure at the drain port (Y) should be 0.05 MPa or less and not be a negative pressure.

<sup>(4)</sup> This value is measured for each valve; it may vary depending on the actual circuit/operation conditions.

## Attachment

### Mounting Bolts

Model Number	Mounting Bolt	Qty.	Bolt Tightening Torque
LSVG-01EH	Hex. Soc. Head Cap Screw : M5×55 L	4	6.0 - 8.0 Nm
LSVG-03EH-*-10	Hex. Soc. Head Cap Screw : M8×65 L	4	30.8 - 37.7 Nm
LSVG-03EH-*-1006	Hex. Soc. Head Cap Screw : M6×60 L	4	13.0 - 16.0 Nm

### Connector

Model Number	Connector	Qty.	Remarks
LSVG-*EH-*-*1	6 + PE Electrical Plug	1	Compatible with EN 175201 PART 804
LSVG-*EH-*-*2	11 + PE Electrical Plug	1	

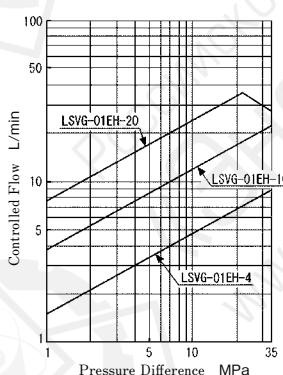
## Cable with Connector (Separately Available)

Model Number	Connector	Cable Model Number	Remarks
LSVG-*EH-*-*1	6 + PE Electrical Plug	LSVC-6PE-*-10	* Cable Length 03 : 3 m 05 : 5 m 10 : 10 m
LSVG-*EH-*-*2	11 + PE Electrical Plug	LSVC-12PE-*-10	

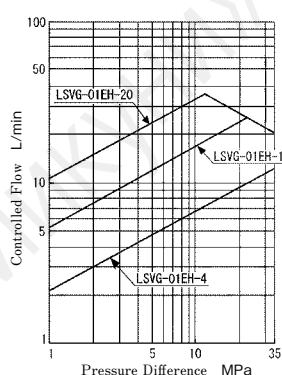
The cable with a connector is a cable assembly that includes the same connector as the one supplied with the valves.

## Range of Flow Control

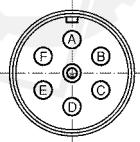
### Control Method: 4-Way Valve



### Control Method: 3-Way Valve



- Electrical Specifications
- 6 + PE Connector



Pin	Valve Model	LSVG-*EH-* -A1 LSVG-*EH-* -D1	LSVG-*EH-* -B1 LSVG-*EH-* -E1	LSVG-*EH-* -C1 LSVG-*EH-* -F1
Pin A	Power Supply	24 V DC (21.6 - 26.4 V DC Included Ripple), 100 VA or more		
Pin B		0 V		
Pin C	Signal Common		COM(0 V)	
Pin D	Input (+) (Differential) <sup>★1</sup>	0 - ±10 V $R_i=100\text{ k}\Omega$	4 - 20 mA $R_i=200\text{ }\Omega$	0 - ±10 mA $R_i=200\text{ }\Omega$
Pin E	Input (-) (Differential) <sup>★1</sup>			
Pin F	Spool Travel Monitoring	0 - ±10 V $R_L\geq 10\text{ k}\Omega$	4 - 20 mA $R_L=100\sim 500\text{ }\Omega$ <sup>★2</sup>	0 - 10 mA $R_L=100\sim 500\text{ }\Omega$ <sup>★2</sup>
Pin	Protective Earth		—	

- 11 + PE Connector



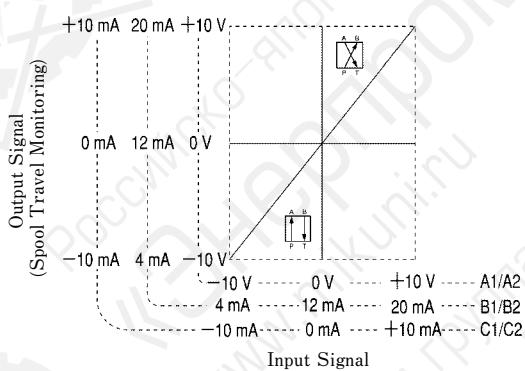
Pin	Valve Model	LSVG-*EH-* -A2 LSVG-*EH-* -D2	LSVG-*EH-* -B2 LSVG-*EH-* -E2	LSVG-*EH-* -C2 LSVG-*EH-* -F2
Pin 1	Power Supply	24 V DC (21.6 - 26.4 V DC Included Ripple), 100 VA or more		
Pin 2		0 V		
Pin 3	Enable (Servo ON) Input		Input Current = 3 - 5 mA at 4.8 - 28 V DC	
Pin 4	Input (+) (Differential) <sup>★1</sup>	0 - ±10 V $R_i=100\text{ k}\Omega$	4 - 20 mA $R_i=200\text{ }\Omega$	0 - ±10 mA $R_i=200\text{ }\Omega$
Pin 5	Input (-) (Differential) <sup>★1</sup>			
Pin 6	Spool Travel Monitoring	0 - ±10 V $R_L\geq 10\text{ k}\Omega$	4 - 20 mA $R_L=100\sim 500\text{ }\Omega$ <sup>★2</sup>	0 - ±10 mA $R_L=100\sim 500\text{ }\Omega$ <sup>★2</sup>
Pin 7	Signal Common		COM (0 V)	
Pin 8	Valve Ready Output		Open Collector Output Voltage: Max. 30 V, Current: Max. 20 mA	
Pin 9	—		—	
Pin 10	—		—	
Pin 11	Alarm Output		Open Collector Output Voltage: Max. 30 V, Current: Max. 20 mA	
Pin	Protective Earth		—	

<sup>★1</sup>. Differential input signals can be used only for the valves with the voltage signal specifications of ±10 V (LSVG-\*EH-\* -A\*/D\*).

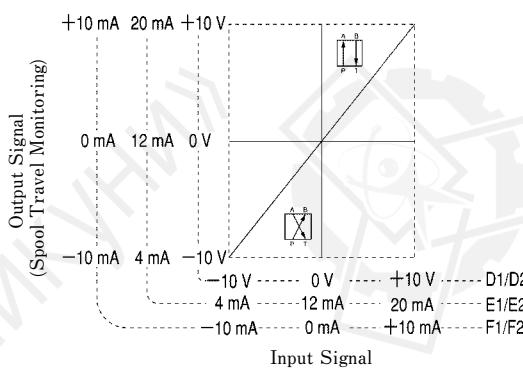
<sup>★2</sup>. The recommended load resistance is 200 Ω.

- I/O Signal Characteristics

#### • LSVG-\*EH-\* -A\*/B\*/C\*

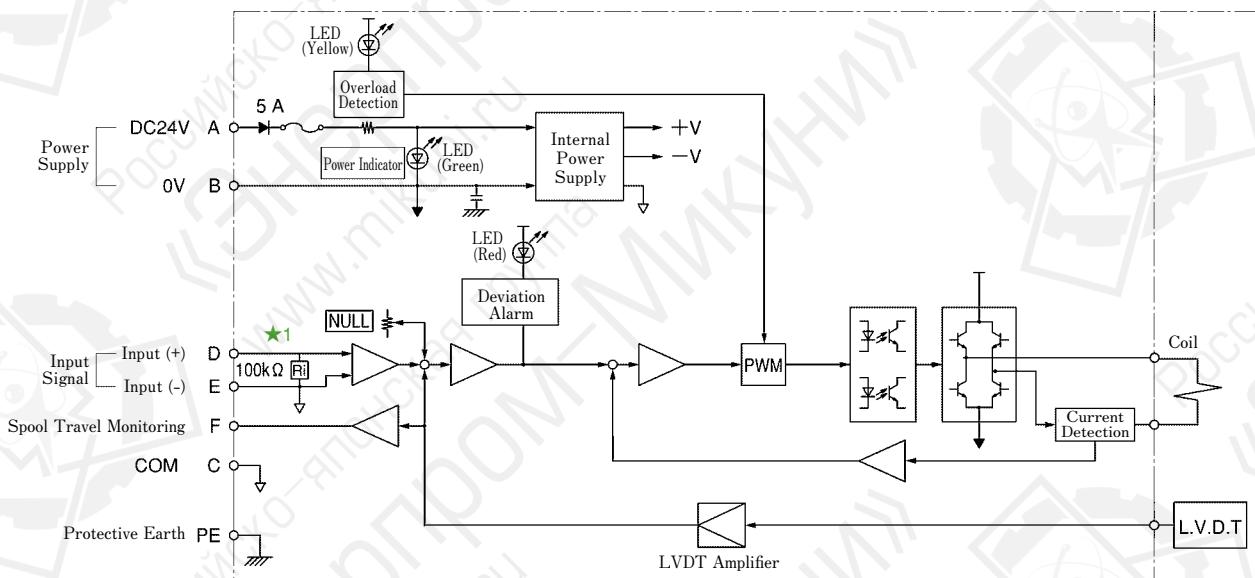


#### • LSVG-\*EH-\* -D\*/E\*/F\*

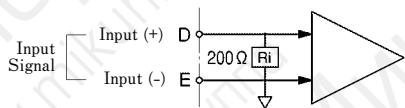


## Block Diagram

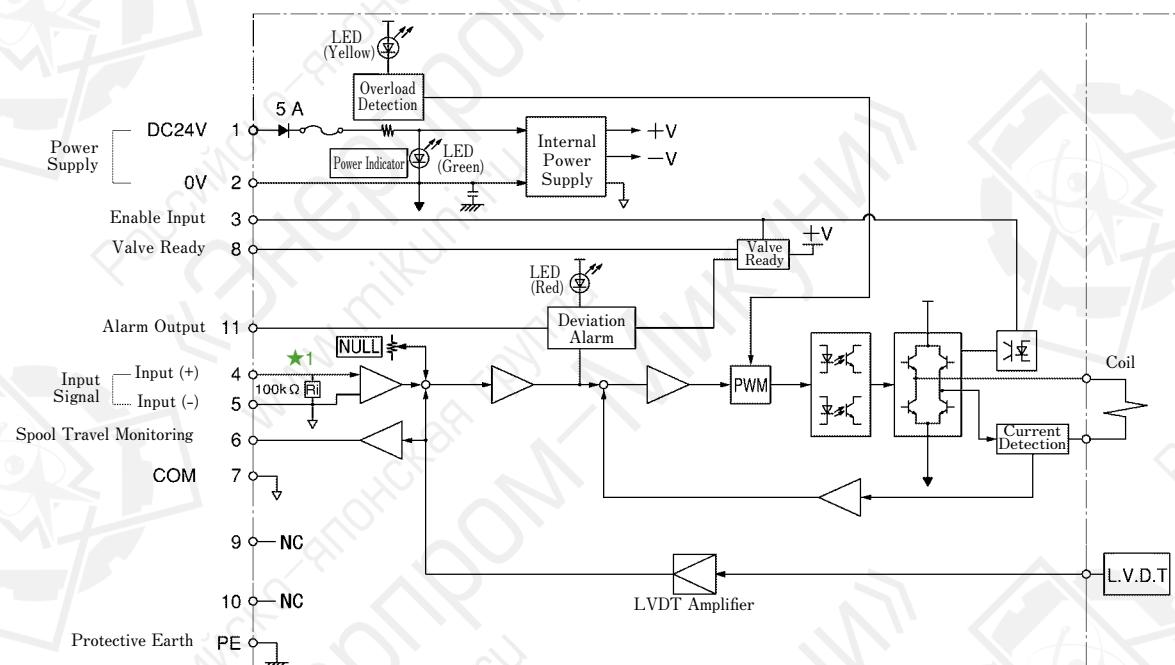
● LSVG- \* EH- \* - \* -A1/B1/C1/D1/E1/F1 (6 + PE Connector)



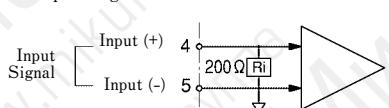
★1. The input stage for the models LSVG- \* EH- \* - \* -B1/C1/E1/F1 (current signal) is as follows.



● LSVG- \* EH- \* - \* -A2/B2/C2/D2/E2/F2 (11 + PE Connector)

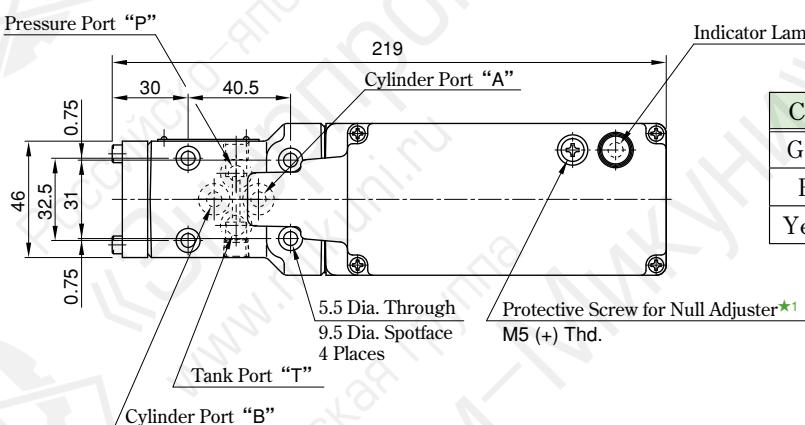


★1. The input stage for the models LSVG- \* EH- \* - \* -B2/C2/E2/F2 (current signal) is as follows.

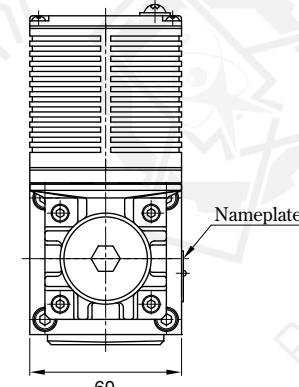
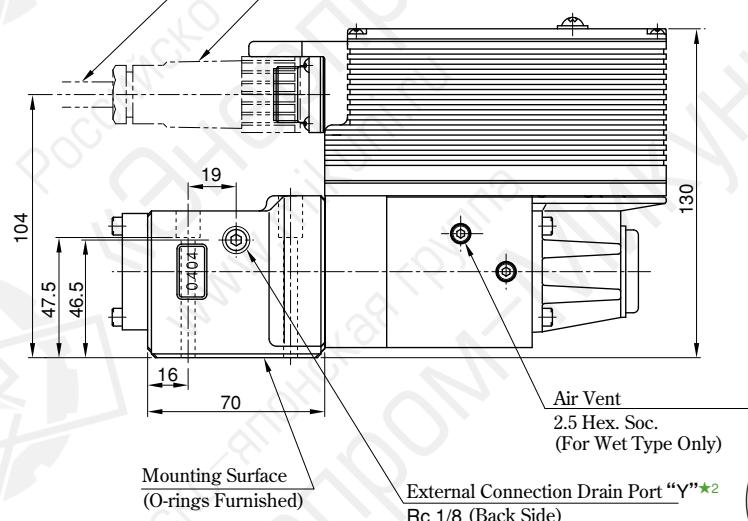


## LSVG-01EH

Mounting Surface: Conforming to ISO 4401-03-02-0-94



Color	Indicator Lamp
Green	Power Supply
Red	Deviation Alarm
Yellow	Overload

Cable Applicable:  
Outside Dia. 8 - 10 mm6 + PE/11 + PE Electrical Plug  
EN175201 Part 804

Connect piping in such a way that negative pressure is avoided. For the wet type, no piping work is required.

- ★1. To adjust the null, remove the protective screw and turn the null trimmer. After adjustment, be sure to attach the protective screw.
- ★2. For the dry type, the external connection drain port "Y" on the tank port side is usually plugged. To use the port on the tank port side, remove the hexagon socket head plug (5 Hex.) from the drain port on the tank port side and plug the port on the pressure port side.

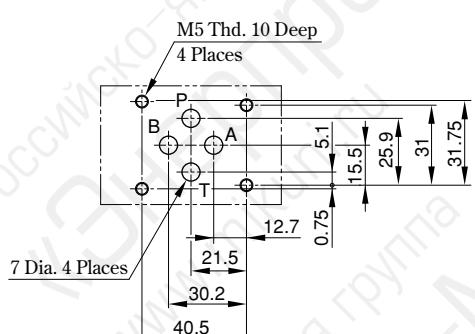
## ● O-rings for the Ports

AS568-012 (NBR, Hs90): 4 pieces

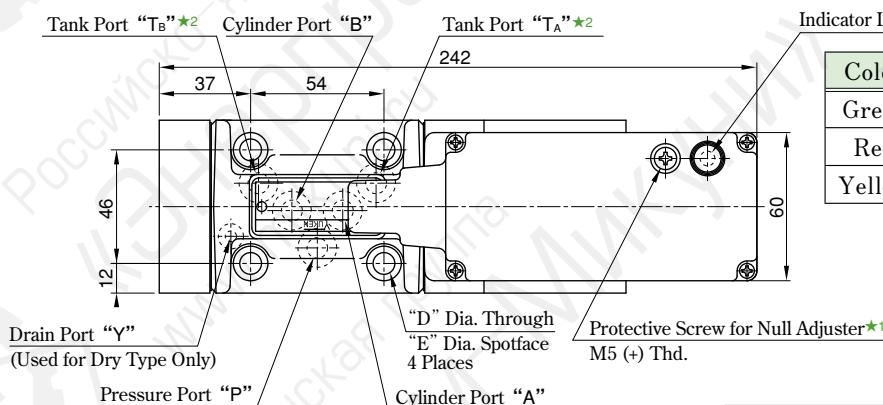
O-rings made of fluorinated rubber are required to use phosphate ester type fluids.

## ● Dimensions of Mounting Surface

Prepare a mounting surface shown below. Basically, the dimensions of the mounting surface conform to the ISO standard. The mounting surface should have a good machined finish.

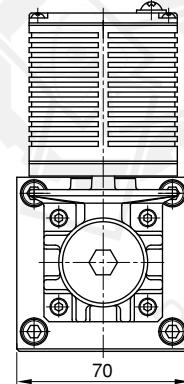
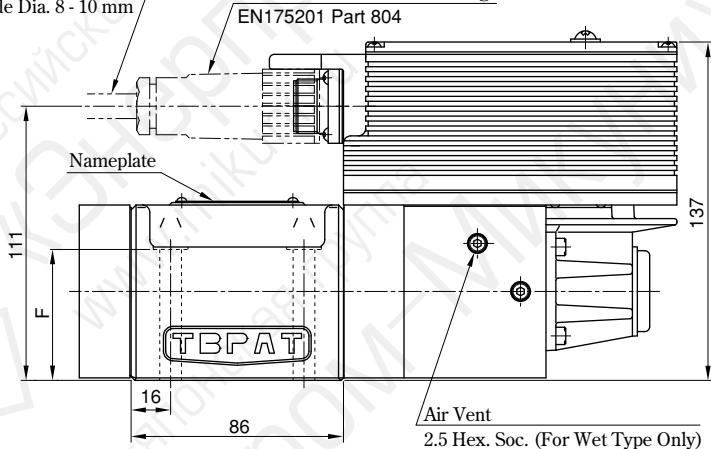


## LSEV-03EH



Color	Indicator Lamp
Green	Power Supply
Red	Deviation Alarm
Yellow	Overload

Cable Applicable:  
Outside Dia. 8 - 10 mm  
6 + PE/11 + PE Electrical Plug  
EN175201 Part 804



★1. To adjust the null, remove the protective screw and turn the null trimmer. After adjustment, be sure to attach the protective screw.

### O-rings for the Ports

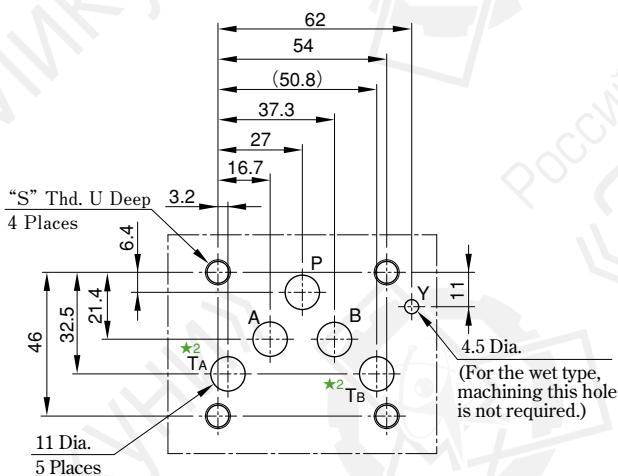
Port	O-ring Size	Qty.
P, A, B, T	AS568-014 (NBR, Hs90)	5
Y	JIS B2401-1B-P7	1

O-rings made of fluorinated rubber are required to use phosphate ester type fluids.

### Dimensions of Mounting Surface

Prepare a mounting surface shown on the right. Basically, the dimensions of the mounting surface conform to the ISO standard, but the specifications for the valve mounting screws and the drain port "Y" (for the dry type) are different as follows.

	ISO 4401-05-04-0-94	Mounting Surface for LSEV-03EH-*10	Mounting Surface for LSEV-03EH-*1006
Valve Mounting Screw	M6	M8	M6
Drain Port "Y" (For Dry Type)	Without "Y" Port	With "Y" Port	With "Y" Port



★2. There are two tank ports "T<sub>A</sub>" and "T<sub>B</sub>"; however, "T<sub>A</sub>" may be used alone.

Model Number	S	U
LSEV-03EH-*10	M8	17
LSEV-03EH-*1006	M6	13

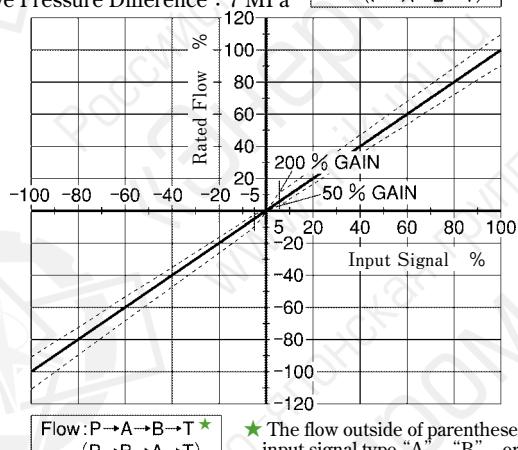
## Characteristics of LSVG-01EH-4/10/20 (Fluid Viscosity: 30 mm<sup>2</sup>/s)

### No-Load Flow Characteristics

Conditions

Valve Pressure Difference : 7 MPa

Flow: P→B→A→T ★  
(P→A→B→T)



Flow: P→A→B→T ★  
(P→B→A→T)

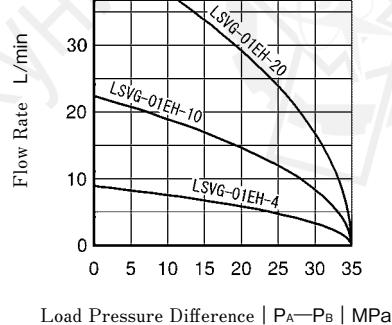
★ The flow outside of parentheses is achieved when the input signal type "A", "B", or "C" is selected. The flow in parentheses is achieved when "D", "E", or "F" is selected.

### Load Flow Characteristics

Conditions

Input Signal : 100 %

Note) Tolerance for Load Flow : ±10 %

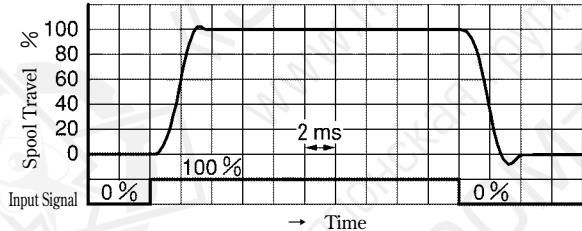


### Step Response

Conditions

Input Amplitude : 0 ⇄ 100 % Supply Pressure : 14 MPa

LSVG-01EH-4/10/20-\*\*\*-10 (Dry Type)

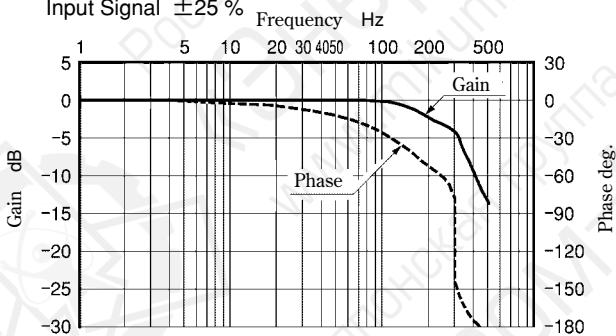


### Frequency Response

Conditions

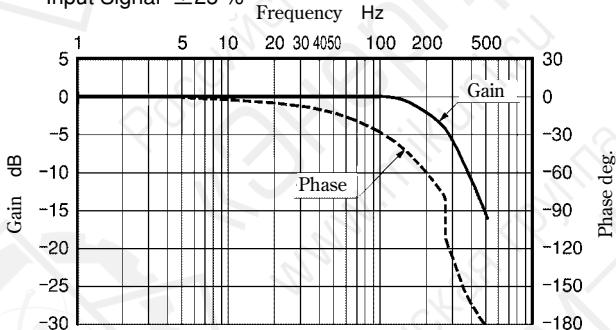
Hydraulic Circuit: Port A/B Closed Supply Pressure : 14 MPa

LSVG-01EH-4/10/20-\*\*\*-10 (Dry Type)

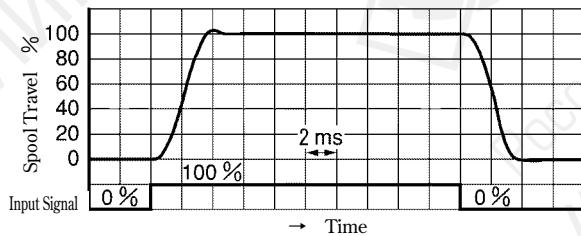


LSVG-01EH-4/10/20-W-\*\*\*-10 (Wet Type)

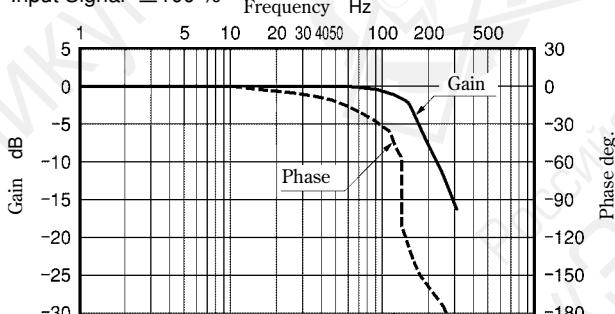
Input Signal ±25 %



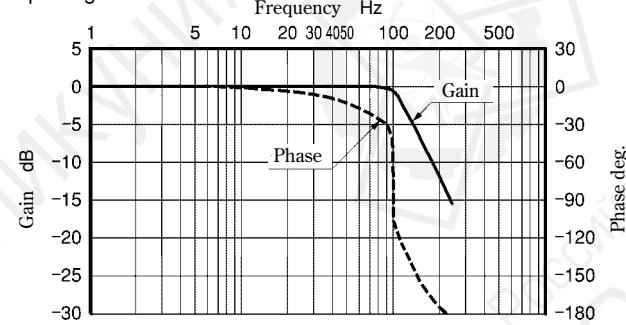
LSVG-01EH-4/10/20-W-\*\*\*-10 (Wet Type)



Input Signal ±100 %



Input Signal ±100 %



## Characteristics of LSVG-03EH-40/60 (Fluid Viscosity: 30 mm<sup>2</sup>/s)

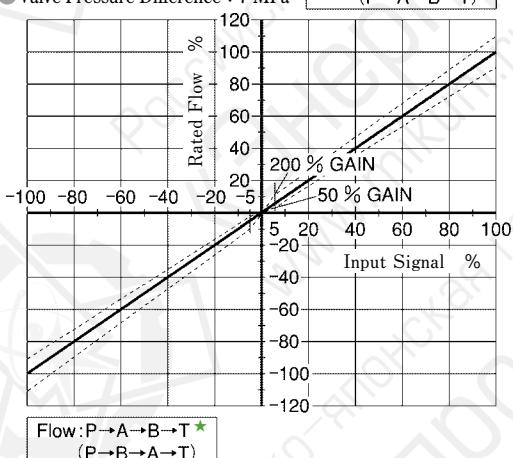
### ■ No-Load Flow Characteristics

Conditions

Valve Pressure Difference : 7 MPa

Flow: P→B→A→T ★

(P→A→B→T)

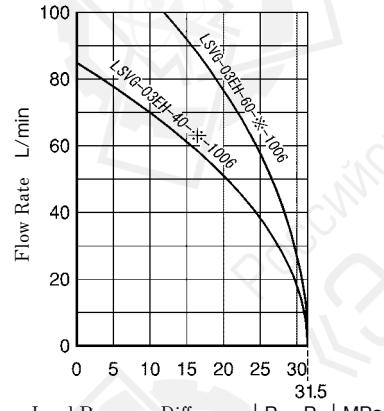
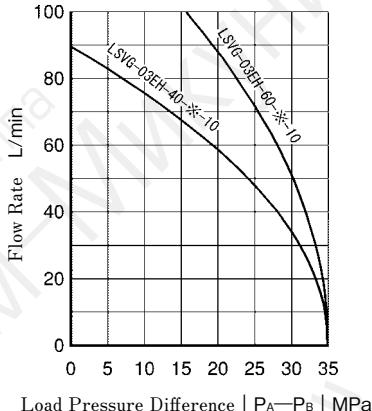


### ■ Load Flow Characteristics

Conditions

Input Signal : 100 %

Note) Tolerance for Load Flow : ±10 %



★ The flow outside of parentheses is achieved when the input signal type "A", "B", or "C" is selected. The flow in parentheses is achieved when "D", "E", or "F" is selected.

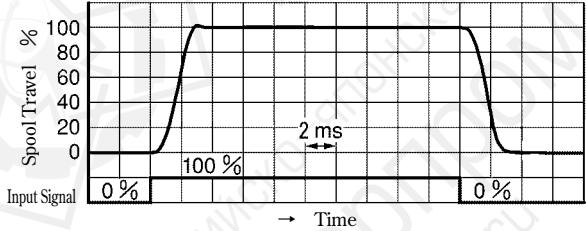
### ■ Step Response

Conditions

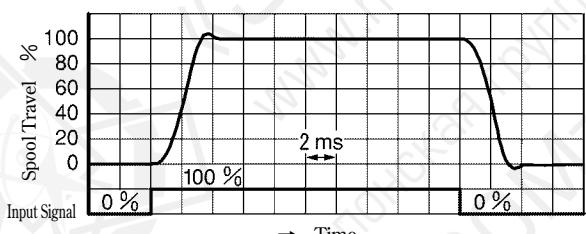
Input Amplitude : 0 ⇄ 100 %

Supply Pressure : 14 MPa

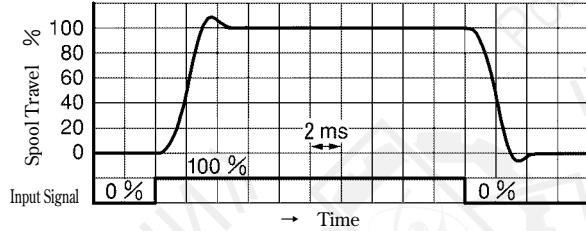
#### ● LSVG-03EH-40-\*\*-10 (Dry Type)



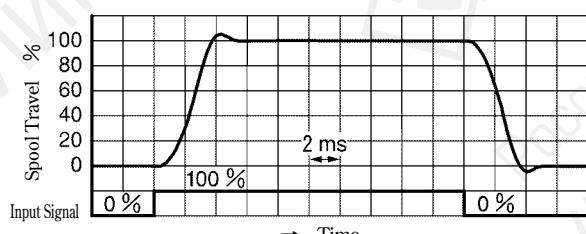
#### ● LSVG-03EH-60-\*\*-10 (Dry Type)



#### ● LSVG-03EH-40-W\*\*-10 (Wet Type)



#### ● LSVG-03EH-60-W\*\*-10 (Wet Type)

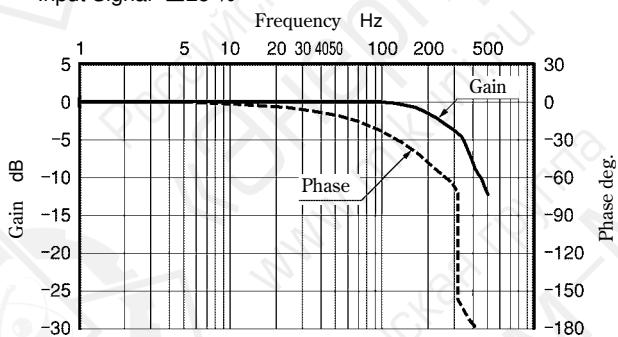


### Frequency Response

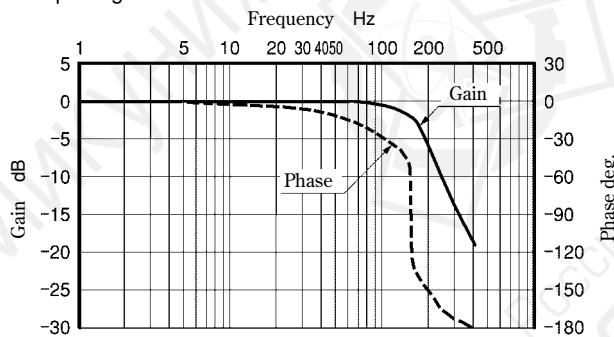
<Conditions> ● Hydraulic Circuit: Port A/B Closed ● Supply Pressure : 14 MPa

#### ● LSVG-03EH-40-\*\*\*-10 (Dry Type)

Input Signal  $\pm 25\%$

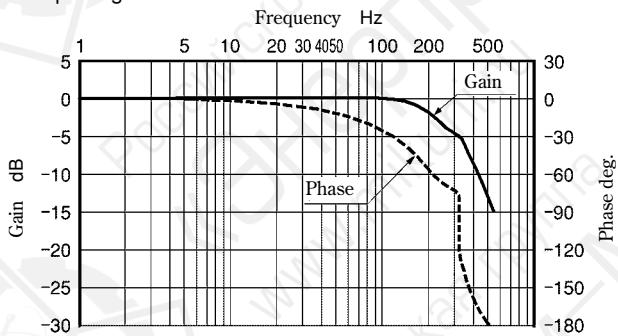


Input Signal  $\pm 100\%$

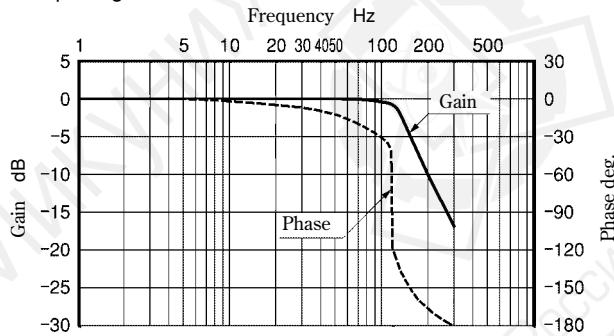


#### ● LSVG-03EH-40-W\*\*\*-10 (Wet Type)

Input Signal  $\pm 25\%$

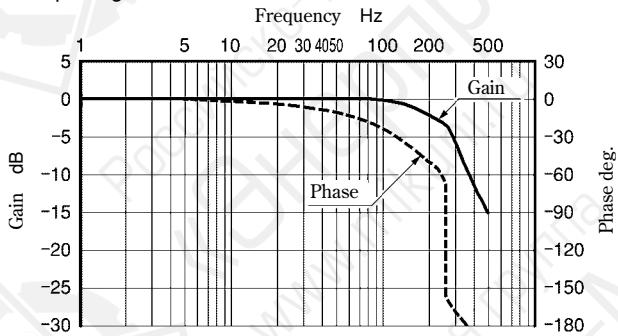


Input Signal  $\pm 100\%$

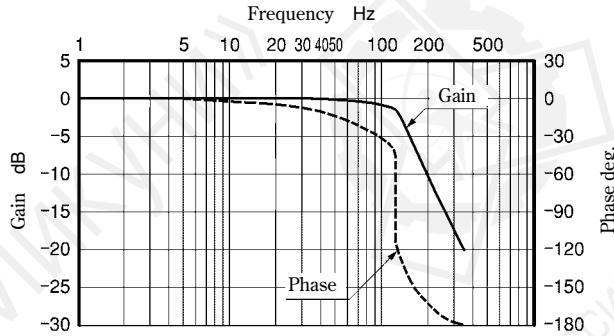


#### ● LSVG-03EH-60-\*\*\*-10 (Dry Type)

Input Signal  $\pm 25\%$

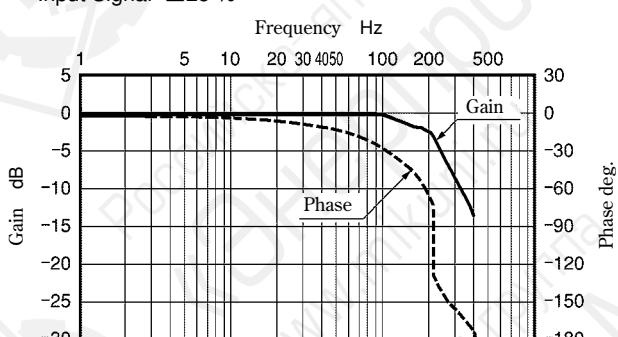


Input Signal  $\pm 100\%$

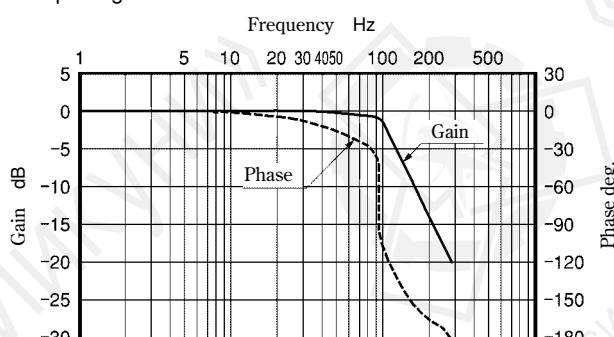


#### ● LSVG-03EH-60-W\*\*\*-10 (Wet Type)

Input Signal  $\pm 25\%$



Input Signal  $\pm 100\%$

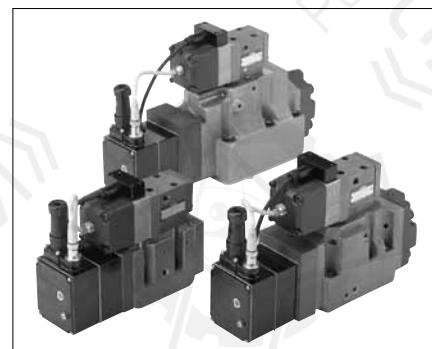


## OBE(On-Board Electronic) Type Linear Servo Valves (Std. Type)

On-board electronics (OBE) type linear servo valves have been developed based on two stage type high speed linear servo valves, but with a focus on downsizing the pilot valve. The integration of the exclusive amplifier and the linear servo valve in a compact package provides "high accuracy, easiness to use, and great usability".

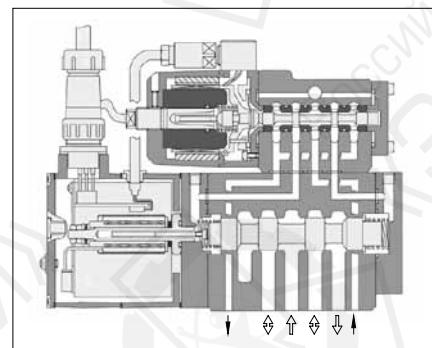
### ● High accuracy

As is the case with the high speed linear servo valves, all of the OBE type linear servo valves have a low hysteresis of 0.1 % or less, realizing high accuracy. These valves allow the main unit to operate with much higher repeatability.



### ● High response characteristics

Compared to other equivalent models, these valves provide higher levels of step and frequency responses, which are typically used as measures of response characteristics; the step response is 7 ms (0 <=> 100 %)\*, and the frequency response is 125 Hz/-3 dB ( $\pm 25\%$  amplitude)\*. (\* : Representative values for LSVHG-03EH)



### ● Easiness to use

These valves can offer high accuracy for hydraulic control systems just with 24 V DC power supply and command signal input.

Six types of input signals in three input voltage/current ranges are available: 0 -  $\pm 10$  V, 0 -  $\pm 10$  mA, and 4 - 20 mA.

### ● Great usability

The small amplifier in the valves has a fault indicator lamp. This lamp indicates an error when valve failure causes any deviation between the spool position commanded by the signal and the actual spool position. It facilitates you to immediately troubleshoot the failure of the valves, if any.

### ● Two types of pilot valves available

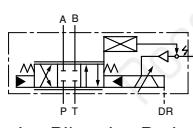
There are two types of pilot valves available: a dry type good in response characteristics and a wet type that eliminates the drain (DR) port to improve usability. They can be selected according to users' purposes.

### ● Excellent contamination resistance

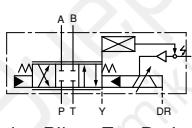
As is the case with the high speed linear servo valves, the OBE type linear servo valves have a simple pilot valve structure, exhibiting excellent contamination resistance. The permissible level of fluid contamination for these valves is up to NAS 1638 class 10.

### Graphic Symbols

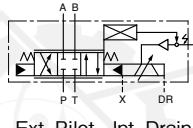
#### ● Spool Types "2", "2P", and "2L"



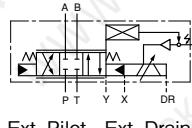
Int. Pilot - Int. Drain



Int. Pilot - Ext. Drain

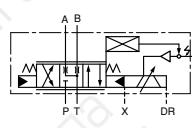


Ext. Pilot - Int. Drain



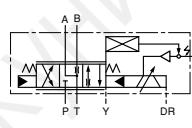
Ext. Pilot - Ext. Drain

#### ● Spool Type "40"



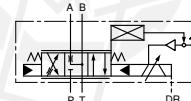
Int. Pilot - Int. Drain

#### ● Spool Type "4J"



The symbols above indicate the external pilot/internal drain type. The internal pilot/internal drain type is the same as that for the spool types "2", "2P", and "2L".

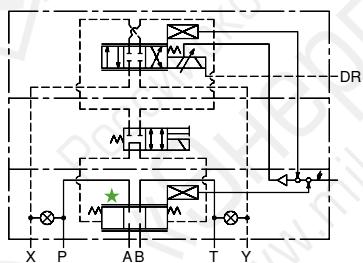
Input Signal/Spool Travel Monitoring "D" / "E" / "F"



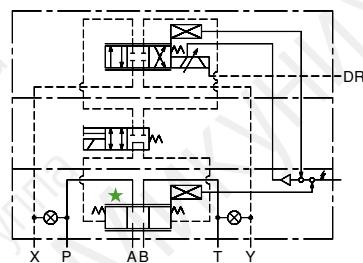
The pilot and drain types are the same as those for the input signal/spool travel monitoring "A"/"B"/"C".

### ● Detailed Graphic Symbols (With Fail-safe Solenoid Operated Valve)

LSVHG-03/04EH-\*\*-EA/\*EB/\*EC



LSVHG-06/10EH-\*\*-EA/\*EB/\*EC



⊗ : Plugs for selecting the pilot and drain types

\* : Depending on the spool type.

(Same as the graphic symbols shown above)

## Model Number Designation

F—	LSVHG	—06	EH	—900	—2P	—E	T	—W	A	—A	1	—20						
Fluid Type	Series Number	Valve Size	Amp. Type	Rated Flow @ $\Delta P = 7 \text{ MPa}$	Spool Type <sup>*1 *5</sup>	Pilot Type	Drain Type	DR Port and Permissible Back Pres.	Fail-safe Function <sup>*1</sup>	Input Signal/Spool Travel Monitoring	Connector Type	Design Number						
<b>F:</b> Special Seals for Phosphate Ester Type Fluid (Omit if not required)	<b>LSVHG:</b> Two Stage Type Linear Servo Valves	03	EH: OBE Type	230: 230 L/min	2L	None: Internal Pilot	None: External Drain	None: With DR Port (Permissible Back Pres.: 0.05 MPa) (Dry Type Pilot Valve)	None: P→B→A→T Position Valve Opening: Full <b>A:</b> P→A→B→T Position Valve Opening: Full	A: Voltage Signal ±10 V (P→B→A→T Flow with Input Signal (+))	20							
				270: 270 L/min	2, 40, 2P						B: Current Signal 4 - 20 mA (P→B→A→T Flow with Current Signal 12 - 20 mA)							
				210: <sup>*4</sup> 210 L/min	4J:Open Centre A, B & T													
		04		750: 750 L/min	2L: 2 % Overlap (Linear Flow Gain)	E: External Pilot	T: Internal Drain		EA: With Solenoid Operated Valve P→A→B→T Position Valve Opening: 10% <b>B:</b> With Solenoid Operated Valve P→B→A→T Position Valve Opening: 10%	C: Current Signal ±10 mA (P→B→A→T Flow with Input Signal (+))	1: 6+ PE Pole							
				580: <sup>*4</sup> 580 L/min	4J:Open Centre A, B & T													
				900: 900 L/min	2, 40, 2P													
		06	EH: OBE Type	1300: 1300 L/min	2L: 2 % Overlap (Linear Flow Gain)	W: <sup>*2</sup> Without DR Port (Wet Type Pilot Valve)	T: Internal Drain	EC: With Solenoid Operated Valve Neutral Position	D: Voltage Signal ±10 V (P→A→B→T Flow with Input Signal (+))	2: 11+ PE Pole								
				820: <sup>*4</sup> 820 L/min	4J:Open Centre A, B & T													
				1300: 1300 L/min	2, 40, 2P													
		10		3800: 3800 L/min	2L: 2 % Overlap (Linear Flow Gain)	None: P→B→A→T Position Valve Opening: Full <b>A:</b> P→A→B→T Position Valve Opening: Full	None: P→B→A→T Position Valve Opening: Full <b>A:</b> P→A→B→T Position Valve Opening: Full	None: P→B→A→T Position Valve Opening: Full <b>A:</b> P→A→B→T Position Valve Opening: Full	F: Current Signal ±10 mA (P→A→B→T Flow with Input Signal (+))									

- ★ 1. The available combinations of the spool type, fail-safe function, and input signal/spool travel monitoring are limited. For details, see the chart on the right.
- ★ 2. The valves with the model number "W" (without DR port) cannot use water-glycol fluids.
- ★ 3. For the valves with the fail-safe function "EC", select "2" only for the connector type.
- ★ 4. For the spool type "4J", the rated flow is a value obtained with +100% input and P→A flow (input signal/spool travel monitoring "A", "B", and "C") or P→B flow ("D", "E", and "F").
- ★ 5. For the spool function in the neutral position, see the chart below.

Spool Type	Fail-safe Function	Input Signal/Spool Travel Monitoring
2	With Solenoid Operated Valve: EC	All (A, B, C, D, E, F)
40	Without Solenoid Operated Valve: None/A	
2L	With Solenoid Operated Valve: EA/EB	
2P	Without Solenoid Operated Valve: None/A	
4J	With Solenoid Operated Valve: EC	
	Without Solenoid Operated Valve: None	D, E, F
	Without Solenoid Operated Valve: A	A, B, C

## Spool Function in Neutral Position

Spool Type	Function
2, 2P, 2L	
40	
4J	

## Fail-safe Function of the Valves

With reference to the information given below, select the option for the fail-safe function according to the use of applications. The valves have a fail-safe function, but a separate safety circuit should be provided if the hydraulic actuator must be reliably held or stopped to ensure safety in the event of electric failure (power failure, power cable disconnection, etc.) or upon startup.

### 1) Electric System: OFF and Hydraulic System: ON (Power Failure/Power Cable Disconnection)

No.	Model Number	Fail-safe Function *
1	(F-) LSVHG-* * EH-* -2/2P/2L (-E) (T) (-W)	P→B→A→T Position Valve Opening: Full
2	(F-) LSVHG-* * EH-* -2/2P/2L (-E) (T) (-W) A	P→A→B→T Position Valve Opening: Full
3	(F-) LSVHG-* * EH-* -4J (-E) (T) (-W)	P→B→A→T Position Valve Opening: Full
4	(F-) LSVHG-* * EH-* -4J (-E) (T) (-W) A	P→A→B→T Position Valve Opening: Full
5	(F-) LSVHG-* * EH-* -2/2P/2L (-E) (T) (-W) EA (With Fail-safe Solenoid Operated Valve)	P→A→B→T Position Valve Opening: 10%
6	(F-) LSVHG-* * EH-* -2/2P/2L (-E) (T) (-W) EB (With Fail-safe Solenoid Operated Valve)	P→B→A→T Position Valve Opening: 10%
7	(F-) LSVHG-* * EH-* -4J (-E) (T) (-W) EC-A */B */C *(With Fail-safe Solenoid Operated Valve)	A, B, T Connection (Neutral)
8	(F-) LSVHG-* * EH-* -4J (-E) (T) (-W) EC-D */E */F *(With Fail-safe Solenoid Operated Valve)	A, B, T Connection (Neutral)

\*The fail-safe activation time depends on the electric and hydraulic conditions.

### 2) Electric System: OFF and Hydraulic System: OFF (Startup)

For Models No. 1 and 2 in the table above, the fail-safe function holds the spool in the neutral position. For Models No. 5 and 6, the function is the same as that for "Electric System: OFF and Hydraulic System: ON". For Models No. 3, 4, 7, and 8, the function is based on A, B, T connection (neutral).

## ■ Specifications

### ● LSVHG-\*EH-\*2/40/2P/2L

The values in parentheses in the specification table below are applicable to the models "LSVHG-\*EH-\*-\*-\*W\*" (without DR port).

Description		Model Numbers	LSVHG-03EH-230-*	LSVHG-03EH-270-*	LSVHG-04EH-750-*	LSVHG-06EH-900-*	LSVHG-06EH-1300-*	LSVHG-10EH-3800-*														
Spool Type		2 L	2	40	2P	2	40	2P														
Rated Flow at $\Delta P = 7 \text{ MPa}$ (4-Way Valve)	L/min	230	270	750	900	1300	3800	2 L														
Rated Flow at $\Delta P' = 0.5 \text{ MPa}$ (per Land)	L/min	87	102	283	340	490	1440	2 L														
Max. Operating Pressure	MPa	31.5		35	35	31.5	35															
Proof Pres. at Return Port <sup>(1)</sup>	External Drain	T Port MPa	21 (5)		31.5	35	25	28														
	Y Port MPa	21(7) (5)			21(7)																	
	Internal Drain	T & Y Port MPa	21(7) (5)			21(7)																
DR Port Permissible Back Pressure <sup>(2)</sup>	MPa	0.05 (The valves with the model number "W" have no DR port.)																				
Pilot Pressure <sup>(3)</sup>	MPa	1.5 - 21																				
Pilot Flow Rate <sup>(4)</sup>	L/min	9 (8) or more		20 (17) or more	22 (19) or more	23 (19) or more	28 (24) or more															
Pilot Valve Max. Leakage	Pres.: $P_S = P_P = 14 \text{ MPa}$	L/min	0.8			1.2																
Main Valve Max. Leakage	Max. Leakage Viscosity: $32 \text{ mm}^2/\text{s}$		1.6	0.5	1	5.6	0.8	1.6	6.8	2.5	0.9	1.8	7	2.5	1	2	8	2.5	3	6	10	8
Hysteresis	%	0.1 or less																				
Step Response ( $0 \leftrightarrow 100\%$ , Typical) <sup>(6)</sup>	ms	8 (10)	7 (9)	11 (13)	11 (13)	15 (18)	18 (20)															
Frequency Response ( $\pm 25\%$ Amplitude, Typical) <sup>(6)</sup>	Gain: -3 dB	Hz	120 (100)	125 (110)	100 (90)	100 (90)	75 (70)	60 (55)														
	Phase: -90°	Hz	110 (90)	110 (100)	90 (90)	90 (90)	70 (75)	70 (60)														
Vibration Proof <sup>(7)</sup>	m/s <sup>2</sup>	100																				
Protection		IP 65																				
Ambient Temperature	°C	0 - +50																				
Spool Stroke to Stops	mm	±4	±3.5	±5	±5	±7	±7															
Spool End Area	cm <sup>2</sup>	3		7	8	8	11.3															
Polarity		See the description about I/O signal characteristics on page 35.																				
Linear Motor Specification	Current A	Max. 2.1																				
	Coil Resistance Ω	9.6 [at 20 °C]																				
Approx. Mass <sup>(8)</sup>	kg	8.5 [11]	14 [16]	20 [24]	20 [24]	77																
Electric Connection		6 + PE/11 + PE Connector (EN175201 Part 804)																				

Note: <sup>(1)</sup> Pressure at the return port should be at actual supply pressure or less.

<sup>(2)</sup> Back pressure at the drain port should be 0.05 MPa or less and not be a negative pressure.

<sup>(3)</sup> Supply pressure for the pilot valve should be 1.5 - 21 MPa and should also be 60 % of actual supply pressure or more.

<sup>(4)</sup> The pilot flow is calculated based on a pilot pressure of 14 MPa and the above step response.

<sup>(5)</sup> To use an external pilot type valve with a supply pressure of 21 MPa or more, pressures at the T and Y ports should be 7 MPa or less.

<sup>(6)</sup> This value is measured for each valve based on a pilot pressure of 14 MPa; it may vary depending on the actual circuit/operation conditions.

<sup>(7)</sup> There are restrictions on the mounting position; refer to the instructions for details.

<sup>(8)</sup> A value in brackets indicates the mass of each valve with a fail-safe solenoid operated valve.

<sup>(9)</sup> For the effective range of the fail-safe function, see page 59.

## ■ Specifications

### ● LSVHG-\*EH-\*4J-\*A\*/B\*/C\*

The values in parentheses in the specification table below are applicable to the models "LSVHG-\*EH-\*-\*-\*EH-W\*" (without DR port).

Model Numbers		LSVHG-03EH-210 -4J-*A*/B*/C*	LSVHG-04EH-580 -4J-*A*/B*/C*	LSVHG-06EH-820 -4J-*A*/B*/C*	LSVHG-06EH-1300 -4J-*A*/B*/C*			
Description		4J: Open Centre A, B & T P→B Flow: 10 % Overlap, A→T Flow: 50 % Underlap P→A Flow: 60 % Overlap, B→T Flow: 5 % Underlap						
Spool Type								
Rated Flow (±10%)	Δ P = 3.5 MPa (per Land)	P→B Flow: 210 A→T Flow: 235 P→A Flow: 95 B→T Flow: 240	P→B Flow: 580 A→T Flow: 675 P→A Flow: 255 B→T Flow: 660	P→B Flow: 820 A→T Flow: 950 P→A Flow: 370 B→T Flow: 940	P→B Flow: 1300 A→T Flow: 1440 P→A Flow: 660 B→T Flow: 1375			
	Δ P = 0.5 MPa (per Land)	P→B Flow: 79 A→T Flow: 89 P→A Flow: 36 B→T Flow: 91	P→B Flow: 219 A→T Flow: 255 P→A Flow: 96 B→T Flow: 249	P→B Flow: 310 A→T Flow: 359 P→A Flow: 140 B→T Flow: 355	P→B Flow: 491 A→T Flow: 544 P→A Flow: 249 B→T Flow: 520			
Max. Operating Pressure		MPa	31.5	35	35			
Proof Pres. at Return Port <sup>(1)</sup>	External Drain	T Port Y Port	MPa	21	31.5			
	Internal Drain	T & Y Ports	MPa	21 (7)				
DR Port Permissible Back Pressure <sup>(2)</sup>		MPa	0.05 or less (The valves with the model number "W" have no DR port.)					
Pilot Pressure <sup>(3)</sup>		MPa	1.5 - 21					
Pilot Flow Rate <sup>(4)</sup>		L/min	9 (8) or more	20 (17) or more	22 (19) or more	23 (19) or more		
Pilot Valve Max. Leakage	Pres.: $P_s = P_p = 14 \text{ MPa}$	L/min	0.8 or less	1.2 or less	1.2 or less			
Main Valve Max. Leakage	Max. Leakage Viscosity: 32 mm <sup>2</sup> /s		0.7 or less	1.1 or less	1.2 or less			
Hysteresis		%	0.1 or less					
Step Response (0 => 100 %) P <sub>p</sub> = 14 MPa (Typical) <sup>(5)</sup>		ms	7 (9)	11 (13)	11 (13)	15 (18)		
Frequency Response (±25 % Amplitude) P <sub>p</sub> = 14 MPa (Typical) <sup>(5)</sup>		Hz	Gain = -3 dB: 125 (110) Phase = -90° : 110 (100)	Gain = -3 dB: 100 (90) Phase = -90° : 90 (90)	Gain = -3 dB: 100 (90) Phase = -90° : 90 (90)	Gain = -3 dB: 75 (70) Phase = -90° : 70 (75)		
Vibration Proof		m/s <sup>2</sup>	100					
Protection			IP 65					
Ambient Temperature		°C	0 - +50					
Spool Stroke to Stops		mm	±3.5	±5	±5	±7		
Spool End Area		cm <sup>2</sup>	3	7	8	8		
Polarity			See the description about I/O signal characteristics on page 35.					
Linear Motor Specification	Current	A	Max. 2.1					
	Coil Resistance	Ω	9.6 [at 20 °C]					
Approx. Mass <sup>(6)</sup>		kg	8.5 [11]	14 [16]	20 [24]			
Electric Connection			6 + PE/11 + PE Connector [EN175201 Part 804]					

Note: (1) Pressure at the return port should be at actual supply pressure or less (to use an external pilot type valve with the size "03" at 21 MPa or more, pressures at the T and Y ports should be 7 MPa or less).

(2) Back pressure at the drain port should be 0.05 MPa or less and not be a negative pressure.

(3) Supply pressure for the pilot valve should be 1.5 - 21 MPa and should also be 60 % of actual supply pressure or more.

(4) The pilot flow is calculated based on a pilot pressure of 14 MPa and the above step response.

(5) This value is measured for each valve based on a pilot pressure of 14 MPa; it may vary depending on the actual circuit/operation conditions.

(6) A value in brackets indicates the mass of each valve with a fail-safe solenoid operated valve.

(7) For the effective range of the fail-safe function, see page 59.

## ■ Specifications

### ● LSVHG-\*EH-\* -4J-\* -D\*/E\*/F\*

The values in parentheses in the specification table below are applicable to the models "LSVHG-\*EH-\* -4J-\* -D\*/E\*/F\*" (without DR port).

Description		Model Numbers	LSVHG-03EH-210 -4J-* -D*/E*/F*	LSVHG-04EH-580 -4J-* -D*/E*/F*	LSVHG-06EH-820 -4J-* -D*/E*/F*	LSVHG-06EH-1300 -4J-* -D*/E*/F*
Spool Type					4J: Open Centre A, B & T P→A Flow: 10 % Overlap, B→T Flow: 50 % Underlap P→B Flow: 60 % Overlap, A→T Flow: 5 % Underlap	
Rated Flow (±10%)	Δ P = 3.5 MPa (per Land)	L/min	P→A Flow: 210 B→T Flow: 235 P→B Flow: 95 A→T Flow: 240	P→A Flow: 580 B→T Flow: 675 P→B Flow: 255 A→T Flow: 660	P→A Flow: 820 B→T Flow: 950 P→B Flow: 370 A→T Flow: 940	P→A Flow: 1300 B→T Flow: 1440 P→B Flow: 660 A→T Flow: 1375
	Δ P = 0.5 MPa (per Land)	L/min	P→A Flow: 79 B→T Flow: 89 P→B Flow: 36 A→T Flow: 91	P→A Flow: 219 B→T Flow: 255 P→B Flow: 96 A→T Flow: 249	P→A Flow: 310 B→T Flow: 359 P→B Flow: 140 A→T Flow: 355	P→A Flow: 491 B→T Flow: 544 P→B Flow: 249 A→T Flow: 520
Max. Operating Pressure		MPa	31.5	35	35	31.5
Proof Pres. at Return Port (¹)	External Drain	T Port Y Port	MPa	21	31.5	35
	Internal Drain	T & Y Ports	MPa		21 (7)	
DR Port Permissible Back Pressure (²)		MPa	0.05 or less (The valves with the model number "W" have no DR port.)			
Pilot Pressure (³)		MPa	1.5 - 21			
Pilot Flow Rate (⁴)		L/min	9 (8) or more	20 (17) or more	22 (19) or more	23 (19) or more
Pilot Valve Max. Leakage	Pres: PS = PP = 14 MPa	L/min	0.8 or less	1.2 or less	1.2 or less	
Main Valve Max. Leakage	Max. Leakage Viscosity: 32 mm²/s		0.7 or less	1.1 or less	1.2 or less	
Hysteresis		%	0.1 or less			
Step Response (0 => 100 %) Pp = 14 MPa (Typical) (⁵)		ms	7 (9)	11 (13)	11 (13)	15 (18)
Frequency Response (± 25 % Amplitude) Pp = 14 MPa (Typical) (⁵)		Hz	Gain = -3 dB: 125 (110) Phase = -90° : 110 (100)	Gain = -3 dB: 100 (90) Phase = -90° : 90 (90)	Gain = -3 dB: 100 (90) Phase = -90° : 90 (90)	Gain = -3 dB: 75 (70) Phase = -90° : 70 (75)
Vibration Proof		m/s²	100			
Protection			IP 65			
Ambient Temperature		°C	0 - +50			
Spool Stroke to Stops		mm	±3.5	±5	±5	±7
Spool End Area		cm²	3	7	8	8
Polarity			See the description about I/O signal characteristics on page 35.			
Linear Motor Specification	Current	A	Max. 2.1			
	Coil Resistance	Ω	9.6 [at 20 °C]			
Approx. Mass (⁶)		kg	8.5 [11]	14 [16]	20 [24]	
Electric Connection			6 + PE/11 + PE Connector [EN175201 Part 804]			

Note: (1) Pressure at the return port should be at actual supply pressure or less (to use an external pilot type valve with the size "03" at 21 MPa or more, pressures at the T and Y ports should be 7 MPa or less).

(2) Back pressure at the drain port should be 0.05 MPa or less and not be a negative pressure.

(3) Supply pressure for the pilot valve should be 1.5 - 21 MPa and should also be 60 % of actual supply pressure or more.

(4) The pilot flow is calculated based on a pilot pressure of 14 MPa and the above step response.

(5) This value is measured for each valve based on a pilot pressure of 14 MPa; it may vary depending on the actual circuit/operation conditions.

(6) A value in brackets indicates the mass of each valve with a fail-safe solenoid operated valve.

(7) For the effective range of the fail-safe function, see page 59.

## ■ Attachment

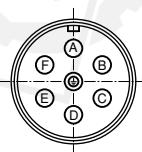
### ● Mounting Bolt

Model Number	Mounting Bolt	Qty.	Bolt Tightening Torque
LSVHG-03EH	Hex. Soc. Head Cap Screw : M6×35L	4	12.9 - 15.9 Nm
LSVHG-04EH	Hex. Soc. Head Cap Screw : M6×55L	2	12.9 - 15.9 Nm
	Hex. Soc. Head Cap Screw : M10×60L	4	60.6 - 74.1 Nm
LSVHG-06EH	Hex. Soc. Head Cap Screw : M12×85L	6	104 - 127 Nm
LSVHG-10EH	Hex. Soc. Head Cap Screw : M20×90L	6	493 - 603 Nm

### ● Connector

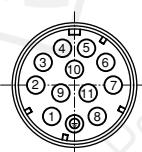
Model Number	Connector	Qty.	Remarks
LSVHG-* EH -* - * 1	6 + PE Electrical Plug	1	Compatible with EN 175201 PART 804
LSVHG-* EH -* - * 2	11 + PE Electrical Plug	1	

**Electrical Specifications**  
● 6 + PE Connector



Pin	Valve Model	LSVHG-*EH-*A1 LSVHG-*EH-*D1	LSVHG-*EH-*B1 LSVHG-*EH-*E1	LSVHG-*EH-*C1 LSVHG-*EH-*F1
Pin A	Power Supply	24 V DC (21.6 - 26.4 V DC Included Ripple), 50 VA or more		
Pin B		0 V		
Pin C	Signal Common	COM (0 V)		
Pin D	Input (+) (Differential) <sup>★1</sup>	0 - ±10 V	4 - 20 mA	0 - ±10 mA
Pin E	Input (-) (Differential) <sup>★1</sup>	R <sub>L</sub> = 100 kΩ	R <sub>L</sub> = 200 Ω	R <sub>L</sub> = 200 Ω
Pin F	Spool Travel Monitoring	0 - ±10 V R <sub>L</sub> ≥ 10 kΩ	4 - 20 mA R <sub>L</sub> = 100 - 500 Ω <sup>★2</sup>	0 - ±10 mA R <sub>L</sub> = 100 - 500 Ω <sup>★2</sup>
Pin (PE)	Protective Earth	—		

● 11 + PE Connector



Pin	Valve Model	LSVHG-*EH-*A2 LSVHG-*EH-*D2	LSVHG-*EH-*B2 LSVHG-*EH-*E2	LSVHG-*EH-*C2 LSVHG-*EH-*F2
Pin 1	Power Supply	24 V DC (21.6 - 26.4 V DC Included Ripple), 50 VA or more		
Pin 2		0 V		
Pin 3	Enable (Servo ON) Input	Input Current = 3 - 5 mA at 4.8 - 28 V DC		
Pin 4	Input (+) (Differential) <sup>★1</sup>	0 - ±10 V	4 - 20 mA	0 - ±10 mA
Pin 5	Input (-) (Differential) <sup>★1</sup>	R <sub>L</sub> = 100 kΩ	R <sub>L</sub> = 200 Ω	R <sub>L</sub> = 200 Ω
Pin 6	Spool Travel Monitoring	0 - ±10 V R <sub>L</sub> ≥ 10 kΩ	4 - 20 mA R <sub>L</sub> = 100 - 500 Ω <sup>★2</sup>	0 - ±10 mA R <sub>L</sub> = 100 - 500 Ω <sup>★2</sup>
Pin 7	Signal Common	COM (0 V)		
Pin 8	Valve Ready Output	Open Collector Output Voltage: Max. 30 V, Current: Max. 20 mA		
Pin 9 <sup>★3</sup>	Power Supply (For Solenoid Operated Valve)	24 V DC (21.6 - 26.4 V DC Included Ripple), 14 VA (Holding Current: 0.6 A)		
Pin 10 <sup>★3</sup>		0 V		
Pin 11	Alarm Output	Open Collector Output Voltage: Max. 30 V, Current: Max. 20 mA		
Pin (PE)	Protective Earth	—		

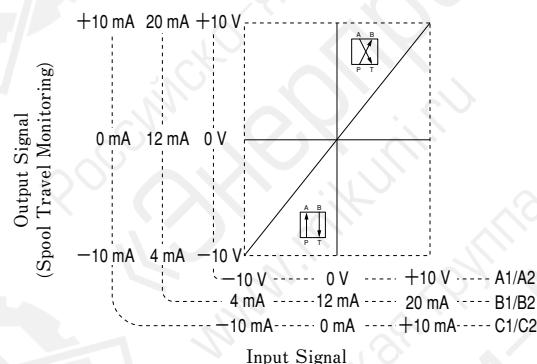
★1. Differential input signals can be used only for the valves with the voltage signal specifications of ±10 V (LSVHG-\*EH-A\* /D\*).

★2. The recommended load resistance is 200 Ω.

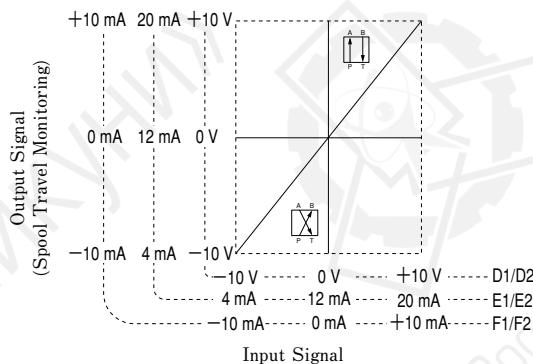
★3. Pins 9 and 10 are used only for the valves with a fail-safe solenoid operated valve. In this case, use a separate power source for the solenoid operated valve from the power source for the amplifier (Pins 1 and 2).

● I/O Signal Characteristics

• LSVHG-\*EH-\*A\* /B\* /C\*

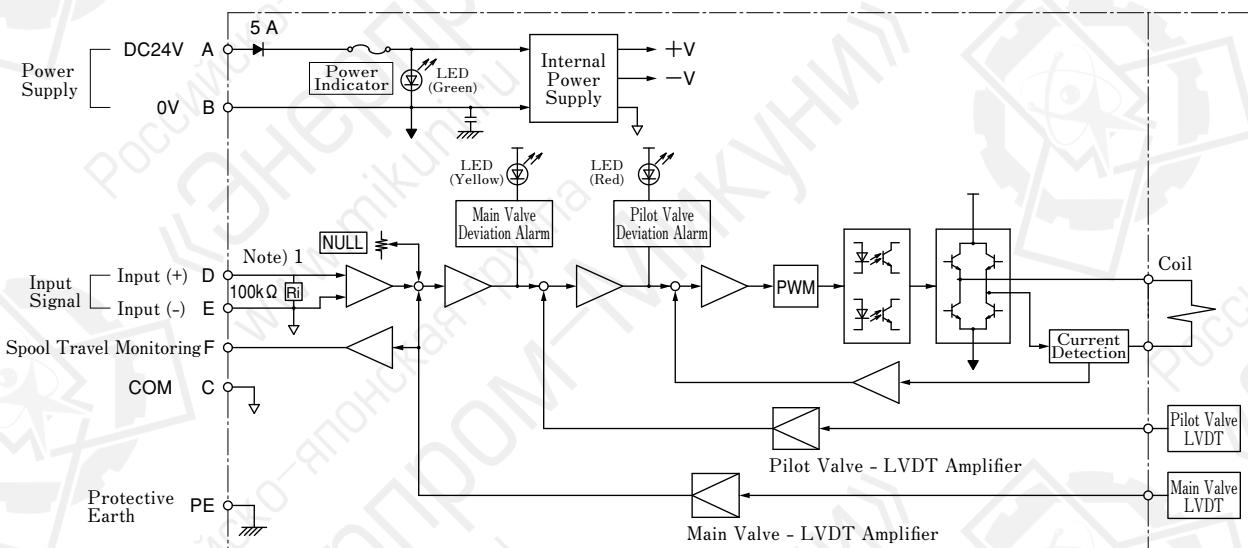


• LSVHG-\*EH-\*D\* /E\* /F\*

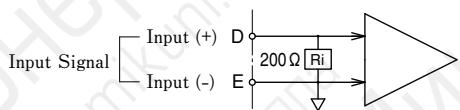


## Block Diagram

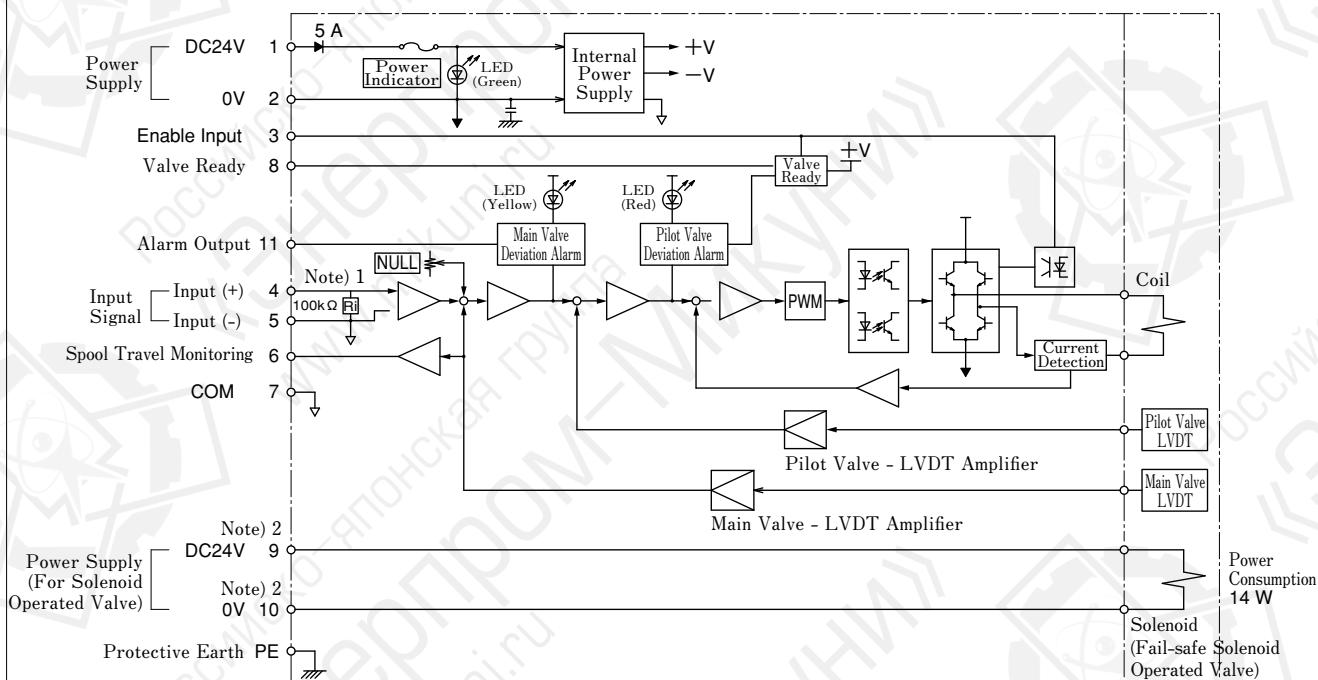
● LSVHG-\*EH-\*-\*A1/D1 (6 + PE Connector)



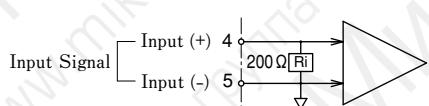
Note) 1. The input stage for the models LSVHS-\*EH-\*-\*B1/C1/E1/F1 (current signal) is as follows.



● LSVHG-\*EH-\*-\*A2/D2 (11 + PE Connector)



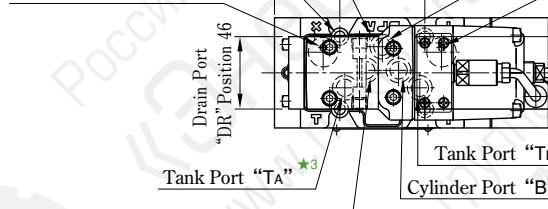
Note) 1. The input stage for the models LSVHG-\*EH-\*-\*B2/C2/E2/F2 (current signal) is as follows.



2. Pins 9 and 10 are used only for the models LSVHG-\*EH-\*-\*E\* with a fail-safe solenoid operated valve.

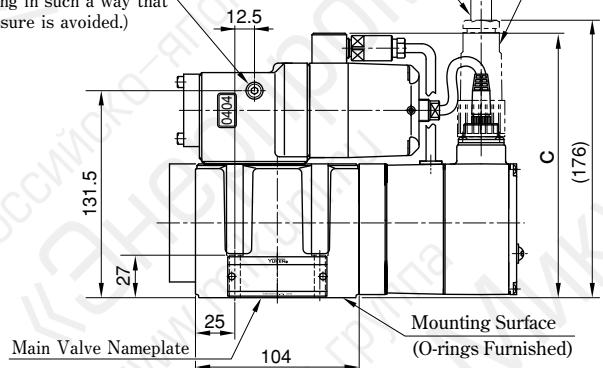
**LSVHG-03EH-230/270**

LSVHG-03EH-230:58  
LSVHG-03EH-270:41.5  
7 Dia. Through  
11 Dia. Spotface 4 Places  
Pilot Pressure Port "X"



External Connection Drain Port "DR" ★<sup>1</sup>  
Rc 1/8 (Back Side)  
Dry type pilot valve only.  
(Connect piping in such a way that negative pressure is avoided.)

Cable Applicable:  
Outside Dia. 8 - 10 mm



Mounting Surface: Conforming to ISO 4401-05-05-0-94

Model Number	C	Remarks
LSVHG-03EH- * - *	168	Pilot Valve: Dry Type
LSVHG-03EH- * - * - W	177	Pilot Valve: Wet Type

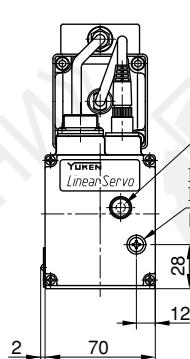
Pilot Spool Position Sensor

6 + PE/11 + PE Electrical Plug  
EN175201 Part 804

Color	Indicator Lamp
Green	Power Supply
Red	Pilot Valve Deviation Alarm
Yellow	Main Valve Deviation Alarm

Indicator Lamp

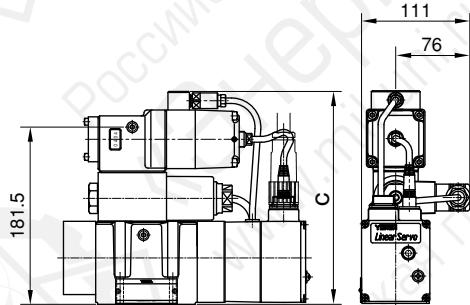
Protective Screw for ★<sup>2</sup>  
Null Adjuster  
M5 (+) Thd.



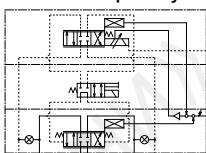
★<sup>1</sup>. The external connection drain port "DR" on the front side is usually plugged. To use the port on the front side, remove the hexagon socket head plug (5 Hex.) and plug the port on the back side.

★<sup>2</sup>. To adjust the null, remove the protective screw and turn the null trimmer. After adjustment, be sure to attach the protective screw.

### LSVHG-03EH-230/270- \* - \* EA/EB/EC (With Fail-safe Solenoid Operated Valve)



#### Detailed Graphic Symbol

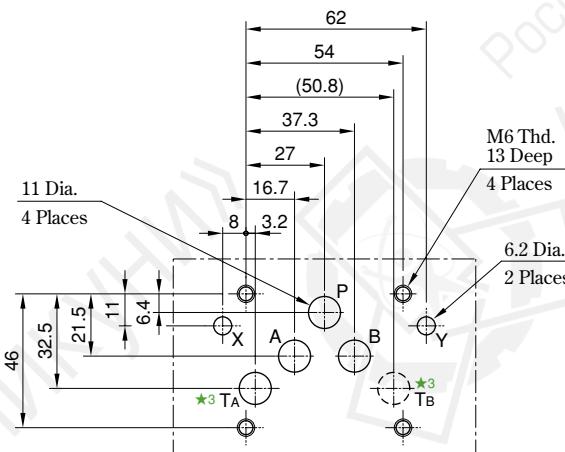


Note) The configuration in the shaded area varies with the selected spool type (corresponding to Graphic Symbols on page 30).

⊗ : Plugs for selecting the pilot and drain types

#### [Dimensions of Mounting Surface]

Prepare a mounting surface shown below. Basically, the dimensions of the mounting surface conform to ISO 4401-05-05-0-94. The mounting surface should have a good machined finish.



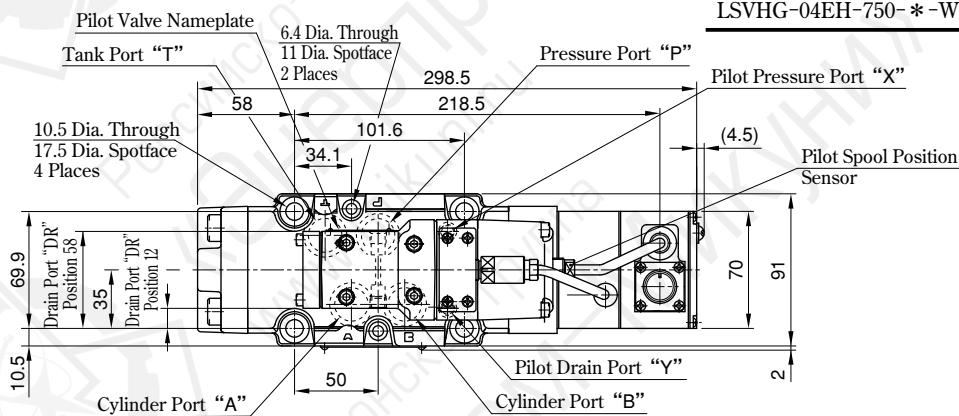
★<sup>3</sup>. There are two tank ports "TA" and "TB"; however, "TA" may be used alone.

#### O-rings for the Ports

Port	O-ring Size	Qty.
P, A, B, T	AS568-014 (NBR, Hs90)	5
X, Y	AS568-016 (NBR, Hs90)	2

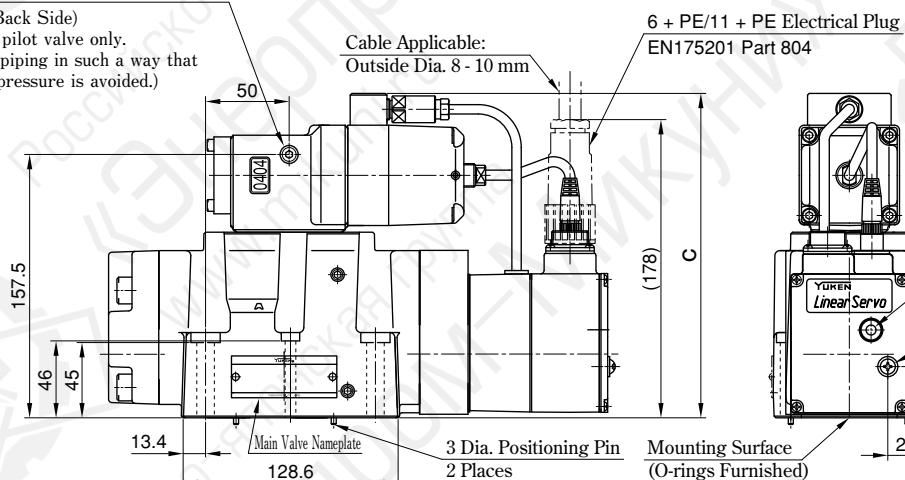
O-rings made of fluorinated rubber are required to use phosphate ester type fluids.

## LSVHG-04EH-750



### ★1 External Connection Drain Port "DR"

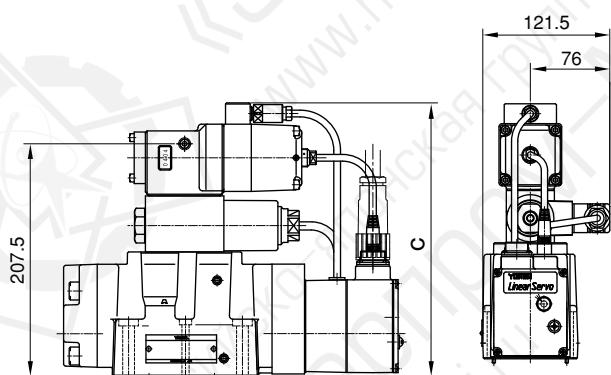
Rc 1/8 (Back Side)  
Dry type pilot valve only.  
(Connect piping in such a way that negative pressure is avoided.)



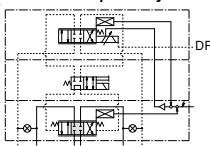
★1. The external connection drain port "DR" on the front side is usually plugged. To use the port on the front side, remove the hexagon socket head plug (5 Hex.) and plug the port on the back side.

★2. To adjust the null, remove the protective screw and turn the null trimmer. After adjustment, be sure to attach the protective screw.

## LSVHG-04EH-750- \* - \* EA/EB/EC (With Fail-safe Solenoid Operated Valve)



### Detailed Graphic Symbol



Note) The configuration in the shaded area varies with the selected spool type (corresponding to Graphic Symbols on page 30).

⊗ : Plugs for selecting the pilot and drain types

Model Number	C	Remarks
LSVHG-04EH-750- * - E *	244	Pilot Valve: Dry Type
LSVHG-04EH-750- * - WE *	253	Pilot Valve: Wet Type

● For other dimensions, see the figures above (the models without a fail-safe solenoid operated valve).

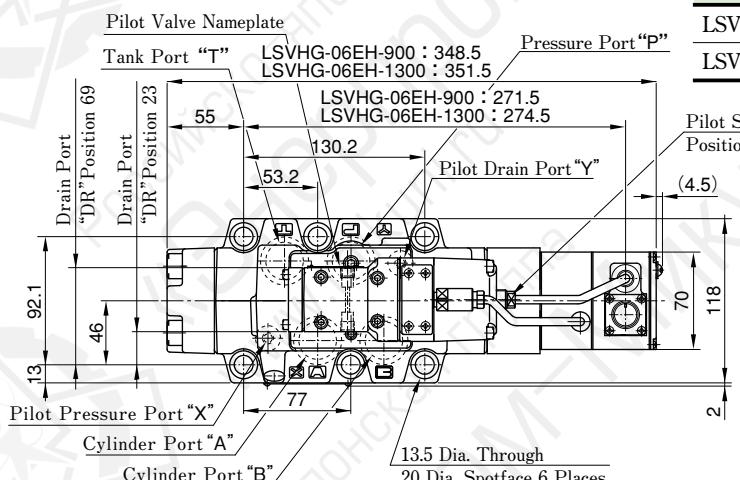
### [Dimensions of Mounting Surface]

The dimensions of the mounting surface are the same as those of the models LSVHG-04 (page 11).

### ● O-rings for the Ports

Port	O-ring Size	Qty.
P, A, B, T	JIS B2401-1B-P22	4
X, Y	AS568-012 (NBR, Hs90)	2

O-rings made of fluorinated rubber are required to use phosphate ester type fluids.

**LSVHG-06EH-900/1300**

External Connection Drain Port "DR" \*<sup>1</sup>  
Rc 1/8 (Both Sides)  
Dry type pilot valve only.  
(Connect piping in such a way  
that negative pressure is avoided.)

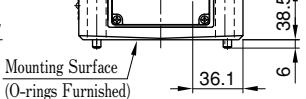
Cable Applicable:  
Outside Dia. 8 - 10 mm

6 + PE/11 + PE Electrical Plug  
EN175201 Part 804

Color	Indicator Lamp
Green	Power Supply
Red	Pilot Valve Deviation Alarm
Yellow	Main Valve Deviation Alarm

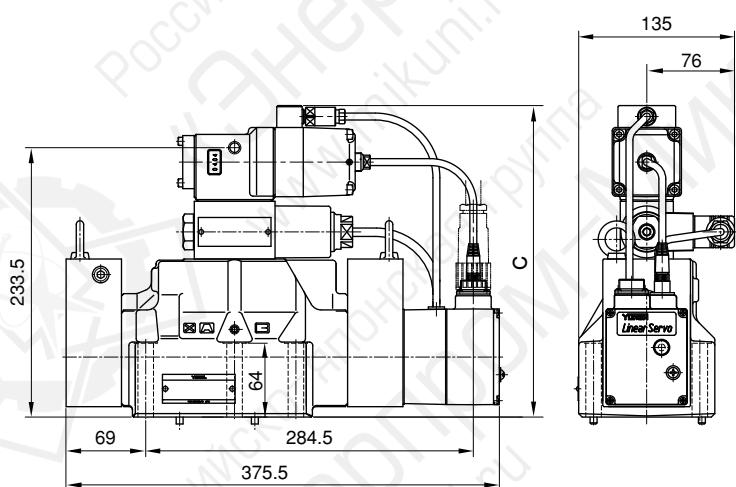
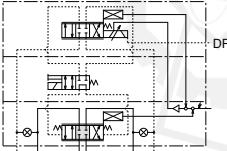
Indicator Lamp

Protective Screw for \*<sup>2</sup>  
Null Adjuster  
M5 (+) Thd.



\*<sup>1</sup>. The external connection drain port "DR" on the back side is usually plugged. To use the port on the back side, remove the hexagon socket head plug (Hex. 5) and plug the port on the front side.

\*<sup>2</sup>. To adjust the null, remove the protective screw and turn the null trimmer. After adjustment, be sure to attach the protective screw.

**LSVHG-06EH-900/1300- \* - \* EA/EB/EC (With Fail-safe Solenoid Operated Valve)****Detailed Graphic Symbol**

Note) The configuration in the shaded area varies  
with the selected spool type (corresponding  
to Graphic Symbols on page 30).

Model Number	C	Remarks
LSVHG-06EH- * - * - E *	270	Pilot Valve: Dry Type
LSVHG-06EH- * - * - WE *	279	Pilot Valve: Wet Type

● For other dimensions, see the figures above (the models without a fail-safe solenoid operated valve).

**O-rings for the Ports**

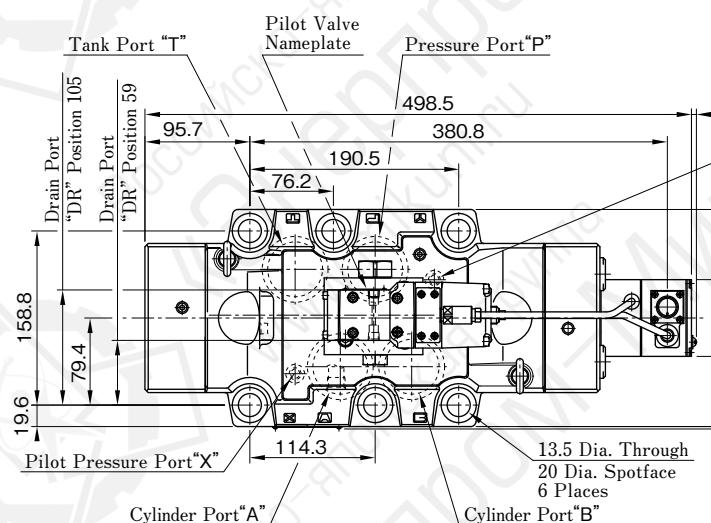
Port	O-ring Size		Qty.
	LSVHG-06EH-900	LSVHG-06EH-1300	
P, A, B, T	AS568-123 (NBR, Hs90)	AS568-126 (NBR, Hs90)	4
X, Y	JIS B2401-1B-P14		2

O-rings made of fluorinated rubber are required to use phosphate ester type fluids.

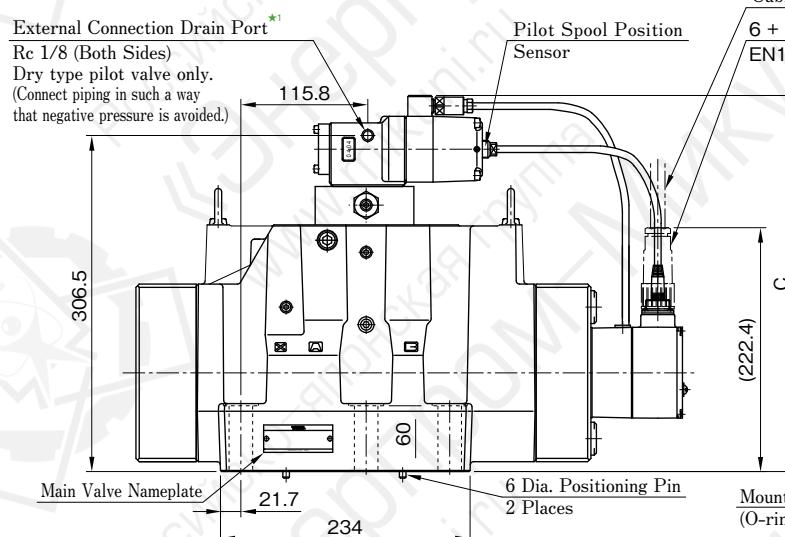
**[Dimensions of Mounting Surface]**

The dimensions of the mounting surface are the same as those of the models LSVHG-06 (page 12).

## LSVHG-10EH-3800



Model Number	C	Remarks
LSVHG-10EH- * - *	343	Pilot Valve: Dry Type
LSVHG-10EH- * - * - W	352	Pilot Valve: Wet Type



Cable Applicable: Outside Dia. 8 - 10 mm

6 + PE/11 + PE Electrical Plug  
EN175201 Part 804

Color	Indicator Lamp
Green	Power Supply
Red	Pilot Valve Deviation Alarm
Yellow	Main Valve Deviation Alarm

Indicator Lamp
Protective Screw for Null Adjuster ★2 M5 (+) Thd.

★1. The external connection drain port "DR" on the back side is usually plugged. To use the port on the back side, remove the hexagon socket head plug (Hex. 5) and plug the port on the front side.

★2. To adjust the null, remove the protective screw and turn the null trimmer. After adjustment, be sure to attach the protective screw.

### 【Dimensions of Mounting Surface】

The dimension of the mounting surface can be fitted with ISO standard.

However, the hole dia. of P,A,B,T are different with those.

Please see mounting surface as shown right.

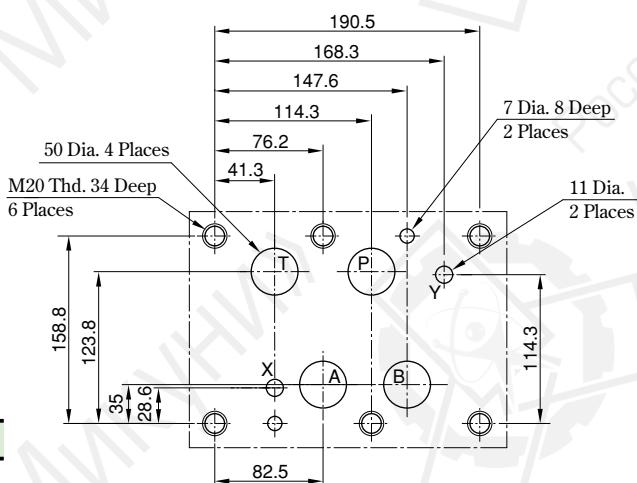
	ISO 4401-10-08-0-94	Mounting Surface for LSVHG-10EH
Hole dia. Of P,A,B,T port.	36 Dia.	50 Dia.

The mounting surface should have a good machined finish.

### ● O-rings for the Ports

Port	O-ring Size	Qty.
P, A, B, T	AS568-227 (NBR, Hs 90)	4
X, Y	AS568-015 (NBR, Hs 90)	2

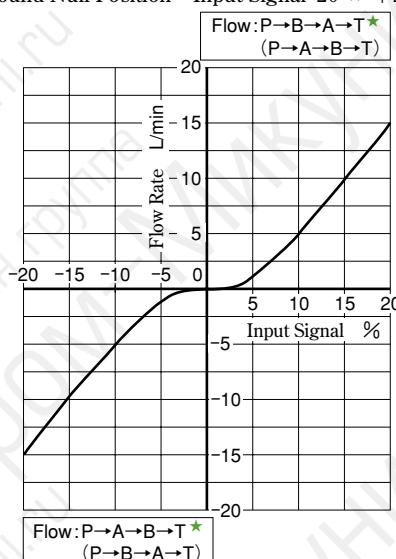
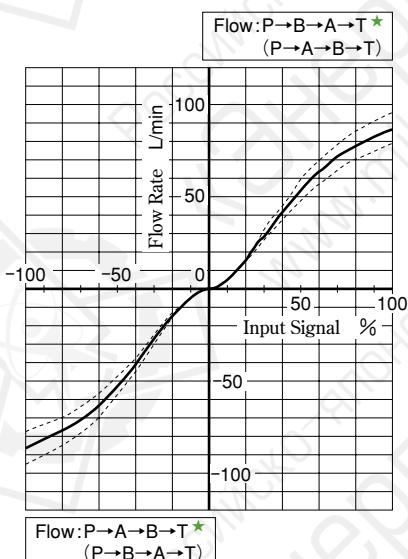
O-rings made of fluorinated rubber are required to use phosphate ester type fluids.



## Characteristics of LSVHG-03EH-230 (Fluid Viscosity: 30 mm<sup>2</sup>/s)

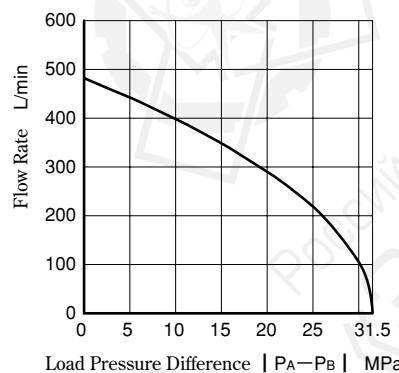
### No-Load Flow Characteristics

Conditions Valve Pressure Difference: 1 MPa (Pressure Difference per Land: 0.5 MPa)  
Around Null Position Input Signal-20 ⇄ +20 %



### Load Flow Characteristics

Conditions Input Signal : 100 %  
Note) Tolerance for Load Flow : ±10 %

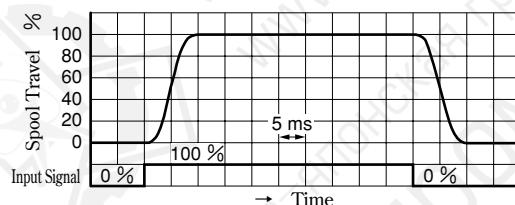


\* The flow outside of parentheses is achieved when the input signal type "A", "B", or "C" is selected. The flow in parentheses is achieved when "D", "E", or "F" is selected.

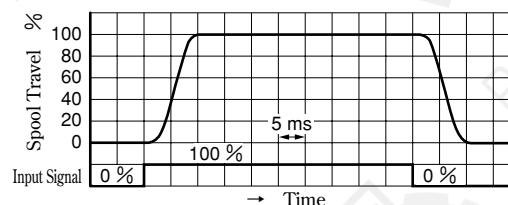
### Step Response

Conditions Input Signal : 0 ⇄ 100 % Supply/Pilot Pressure : 14 MPa

- Pilot Valve: Dry Type



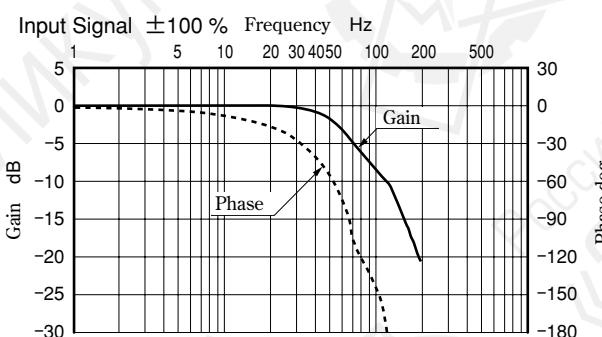
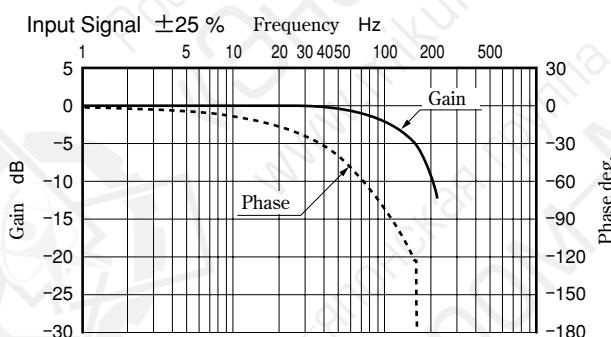
- Pilot Valve: Wet Type



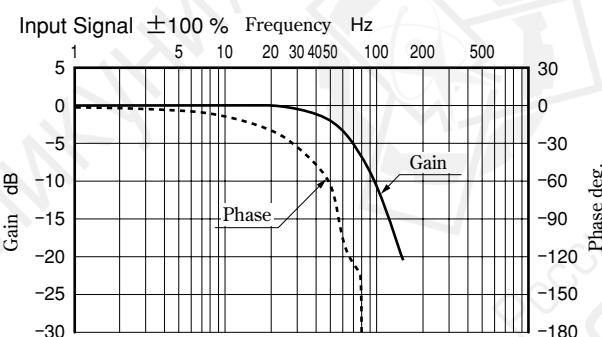
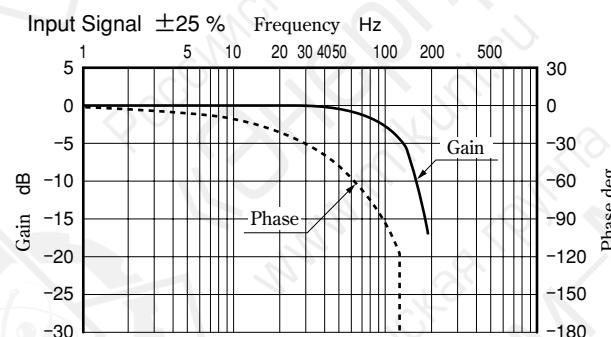
### Frequency Response

Conditions Hydraulic Circuit: Port A/B Closed Supply/Pilot Pressure : 14 MPa

- Pilot Valve: Dry Type



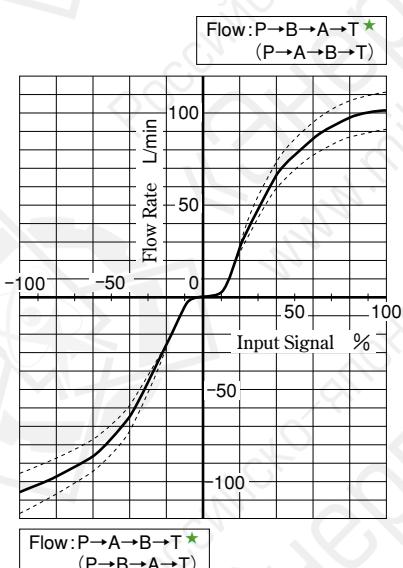
- Pilot Valve: Wet Type



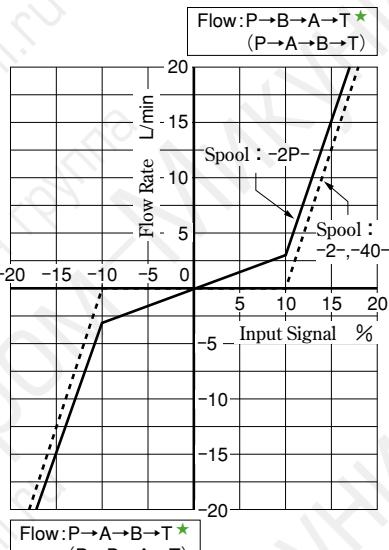
## Characteristics of LSVHG-03EH-270-2/40/2P (Fluid Viscosity: 30 mm<sup>2</sup>/s)

### No-Load Flow Characteristics

Conditions Valve Pressure Difference: 1 MPa (Pressure Difference per Land: 0.5 MPa)



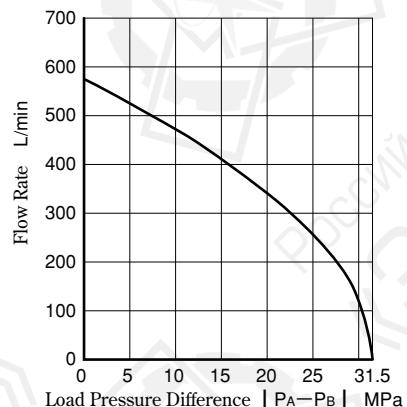
Around Null Position      Input Signal -20 ⇄ +20 %



### Load Flow Characteristics

Conditions Input Signal : 100 %

Note) Tolerance for Load Flow : ±10 %

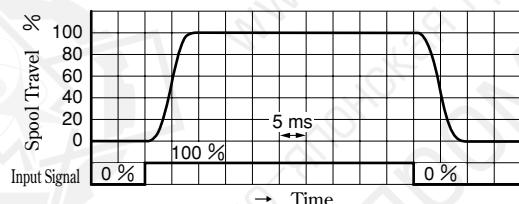


★ The flow outside of parentheses is achieved when the input signal type "A", "B", or "C" is selected. The flow in parentheses is achieved when "D", "E", or "F" is selected.

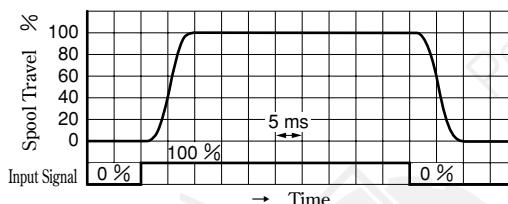
### Step Response

Conditions Input Signal : 0 ⇄ 100 % Supply/Pilot Pressure : 14 MPa

Pilot Valve: Dry Type



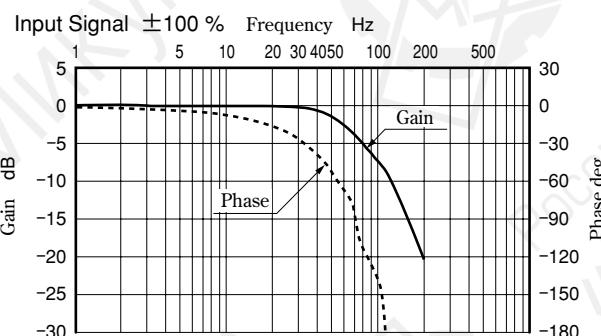
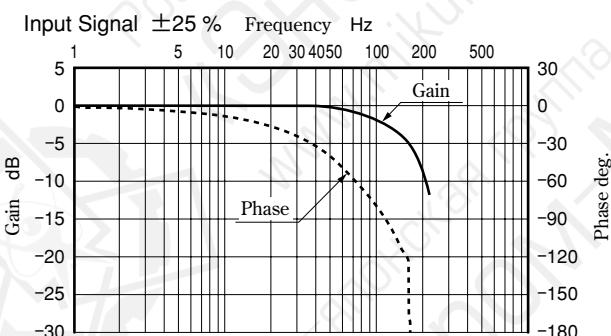
Pilot Valve: Wet Type



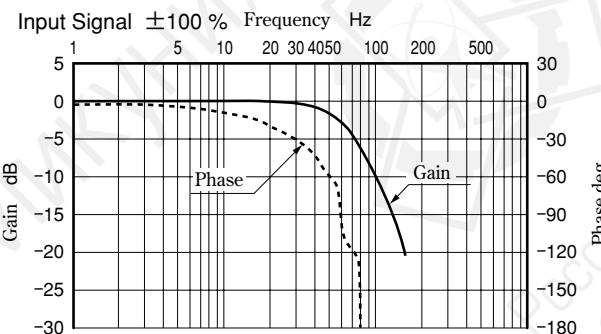
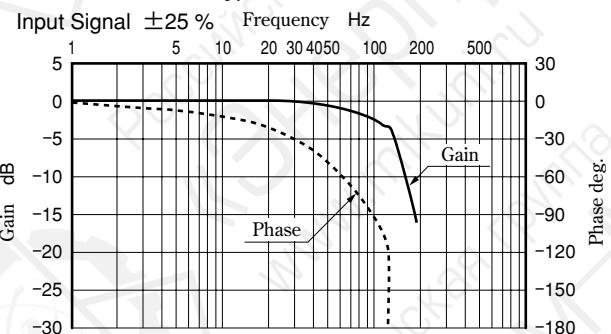
### Frequency Response

Conditions Hydraulic Circuit: Port A/B Closed Supply/Pilot Pressure : 14 MPa

Pilot Valve: Dry Type



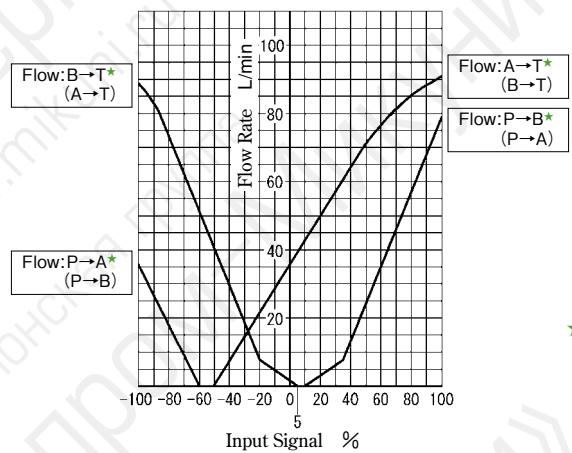
Pilot Valve: Wet Type



## Characteristics of LSVHG-03EH-210-4J (Fluid Viscosity: 30 mm<sup>2</sup>/s)

### No-Load Flow Characteristics

Conditions: Valve Pressure Difference:  $\Delta P = 0.5 \text{ MPa}$  (per Land)

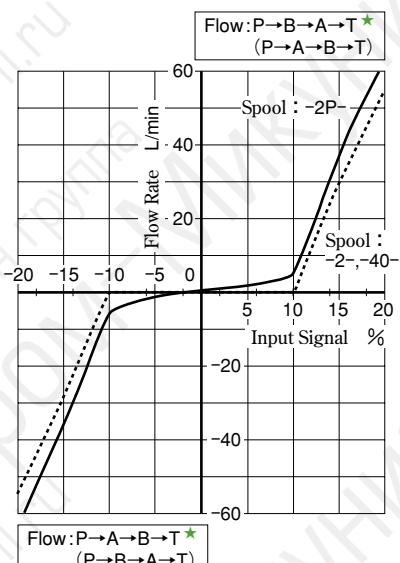
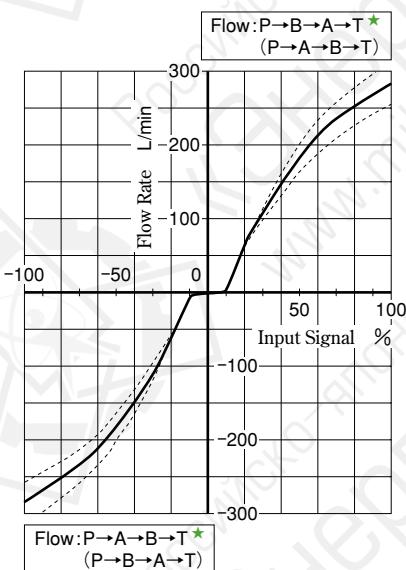


★ The flow outside of parentheses is achieved when the input signal type "A", "B", or "C" is selected. The flow in parentheses is achieved when "D", "E", or "F" is selected.

## Characteristics of LSVHG-04EH-750-2/40/2P (Fluid Viscosity: 30 mm<sup>2</sup>/s)

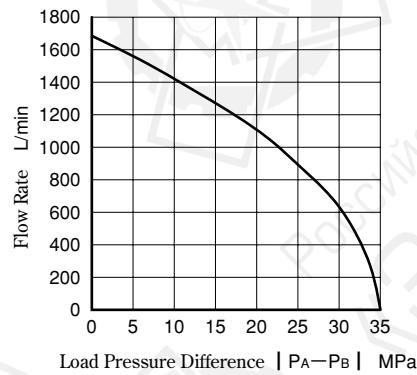
### No-Load Flow Characteristics

Conditions Valve Pressure Difference: 1 MPa (Pressure Difference per Land: 0.5 MPa)  
Around Null Position Input Signal -20 ⇄ +20 %



### Load Flow Characteristics

Conditions Input Signal : 100 %  
Note) Tolerance for Load Flow : ±10 %

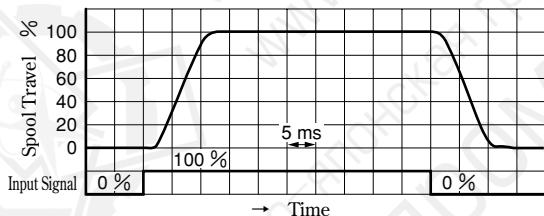


★ The flow outside of parentheses is achieved when the input signal type "A", "B", or "C" is selected. The flow in parentheses is achieved when "D", "E", or "F" is selected.

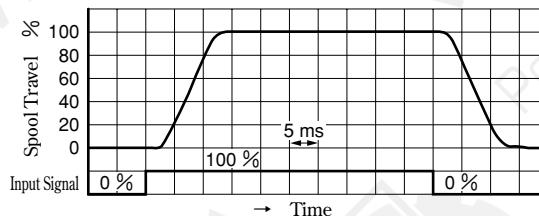
### Step Response

Conditions Input Signal : 0 ⇄ 100 % Supply/Pilot Pressure : 14 MPa

Pilot Valve: Dry Type



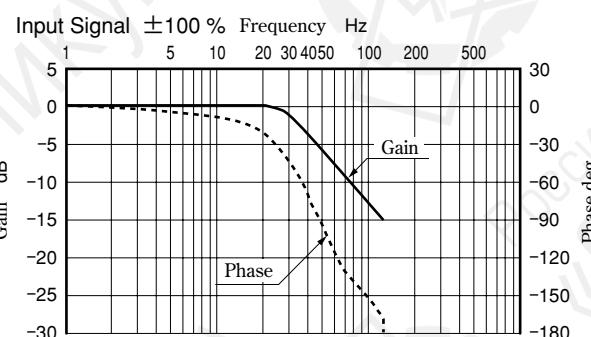
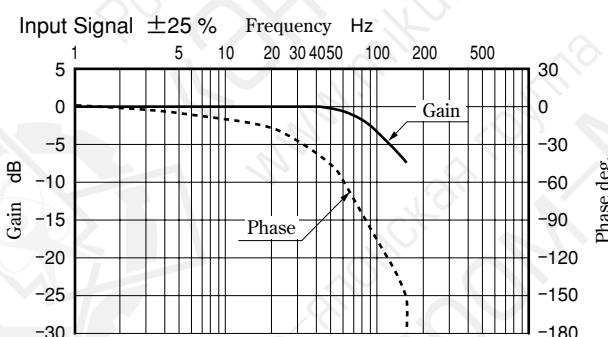
Pilot Valve: Wet Type



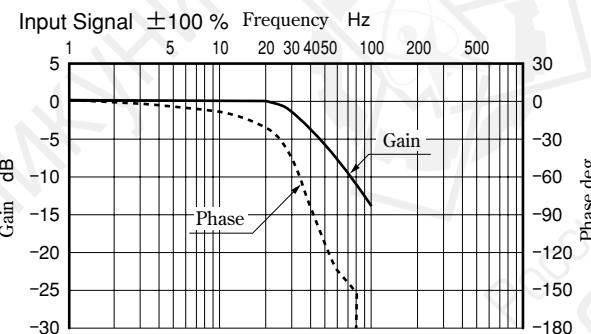
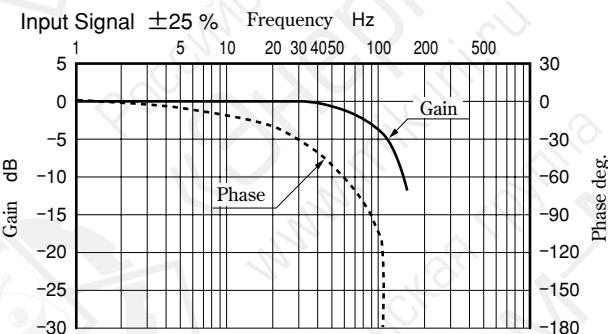
### Frequency Response

Conditions Hydraulic Circuit: Port A/B Closed Supply/Pilot Pressure : 14 MPa

Pilot Valve: Dry Type



Pilot Valve: Wet Type



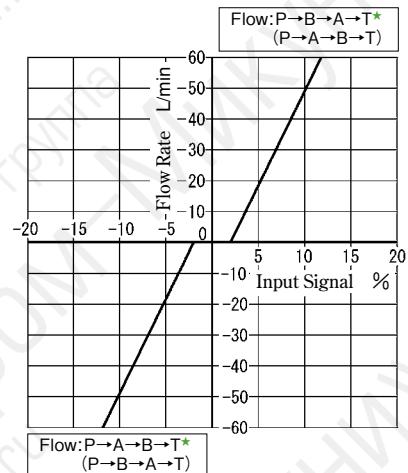
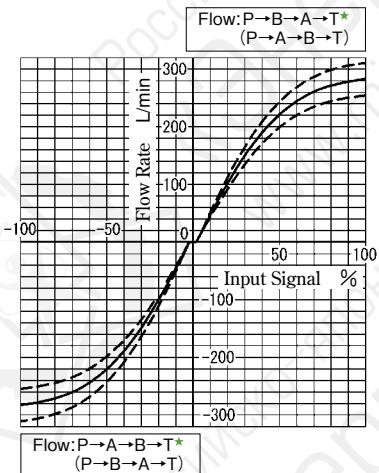
## Characteristics of LSVHG-04EH-750-2L (Fluid Viscosity: 30 mm<sup>2</sup>/s)

### No-Load Flow Characteristics

Conditions Valve Pressure Difference:  $\Delta P = 1 \text{ MPa}$  (4-Way Valve) (Pressure Difference per Land: 0.5 MPa)

Around Null Position Input Signal -20 ⇔ +20 %

The load flow characteristics, step response, and frequency response are the same as those of the spool types "2", "40", and "2P".

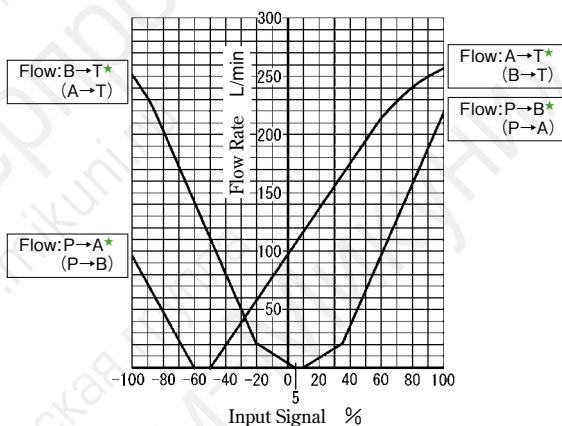


★ The flow outside of parentheses is achieved when the input signal type "A", "B", or "C" is selected. The flow in parentheses is achieved when "D", "E", or "F" is selected.

## Characteristics of LSVHG-04EH-580-4J (Fluid Viscosity: 30 mm<sup>2</sup>/s)

### No-Load Flow Characteristics

Conditions Valve Pressure Difference:  $\Delta P = 0.5 \text{ MPa}$  (per Land)

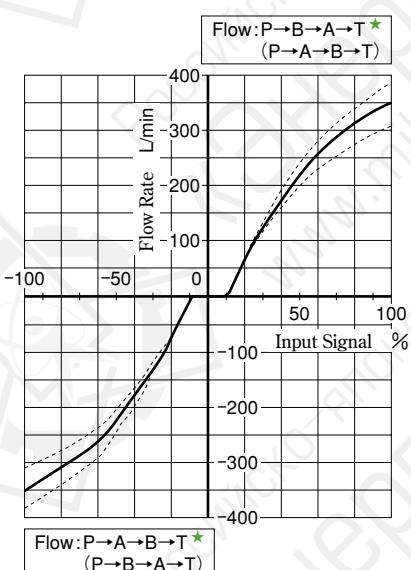


★ The flow outside of parentheses is achieved when the input signal type "A", "B", or "C" is selected. The flow in parentheses is achieved when "D", "E", or "F" is selected.

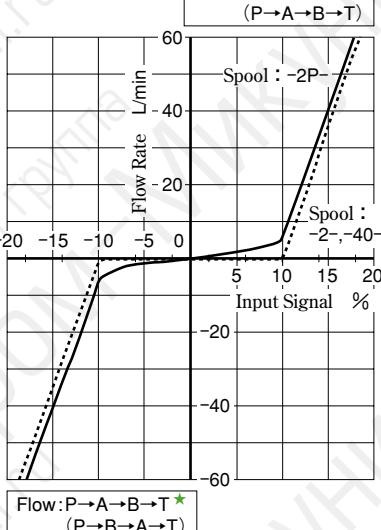
## Characteristics of LSVHG-06EH-900-2/40/2P (Fluid Viscosity: 30 mm<sup>2</sup>/s)

### No-Load Flow Characteristics

Conditions: Valve Pressure Difference: 1 MPa (Pressure Difference per Land: 0.5 MPa)



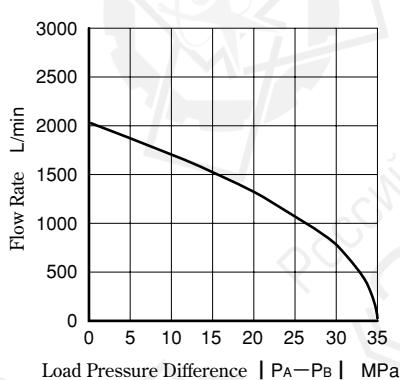
Around Null Position      Input Signal:  $-20 \leftrightarrow +20\%$



### Load Flow Characteristics

Conditions: Input Signal: 100 %

Note) Tolerance for Load Flow: ±10 %

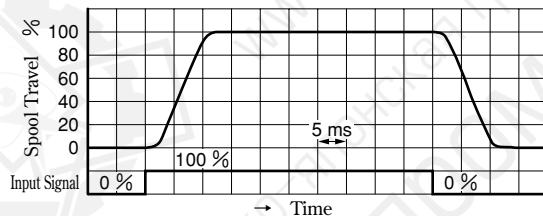


★ The flow outside of parentheses is achieved when the input signal type "A", "B", or "C" is selected. The flow in parentheses is achieved when "D", "E", or "F" is selected.

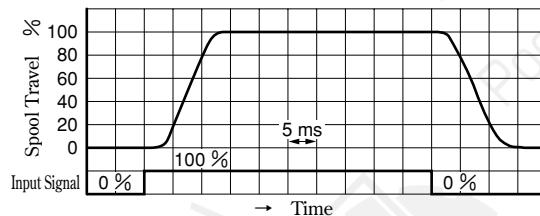
### Step Response

Conditions: Input Signal:  $0 \leftrightarrow 100\%$  Supply/Pilot Pressure: 14 MPa

#### Pilot Valve: Dry Type



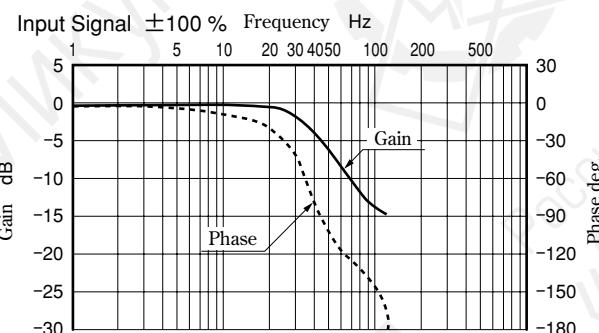
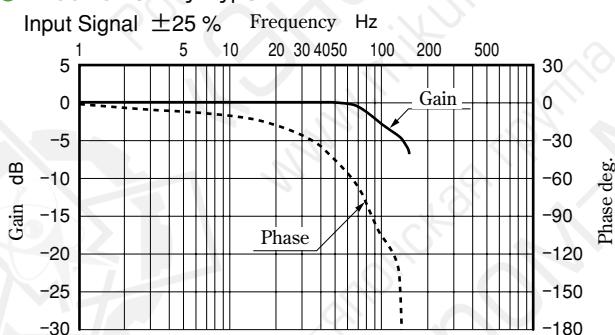
#### Pilot Valve: Wet Type



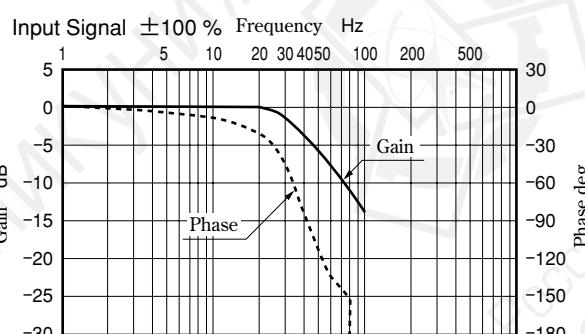
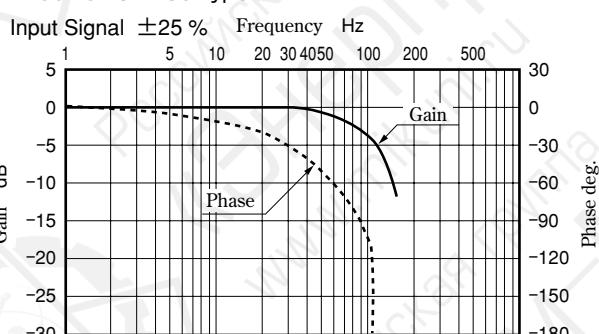
### Frequency Response

Conditions: Hydraulic Circuit: Port A/B Closed Supply/Pilot Pressure: 14 MPa

#### Pilot Valve: Dry Type



#### Pilot Valve: Wet Type



## Characteristics of LSVHG-06EH-900-2L (Fluid Viscosity: 30 mm<sup>2</sup>/s)

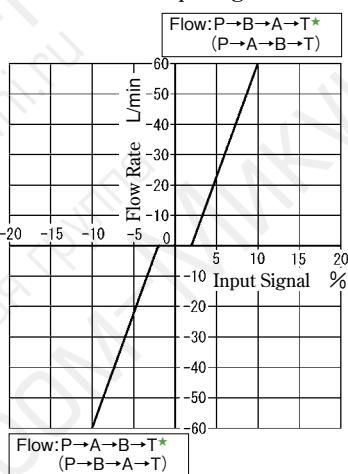
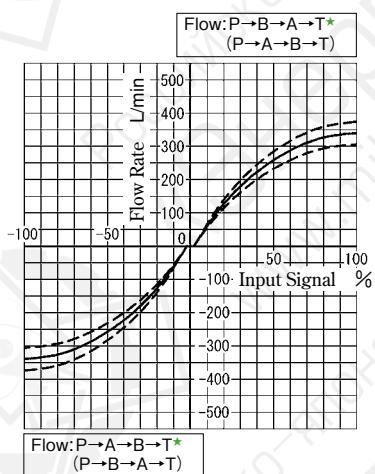
### No-Load Flow Characteristics

Conditions

Valve Pressure Difference:  $\Delta P = 1 \text{ MPa}$  (4-Way Valve) (Pressure Difference per Land: 0.5 MPa)

Around Null Position

Input Signal-20 ⇔ +20 %



The load flow characteristics, step response, and frequency response are the same as those of the spool types "2", "40", and "2P".

★ The flow outside of parentheses is achieved when the input signal type "A", "B", or "C" is selected. The flow in parentheses is achieved when "D", "E", or "F" is selected.

## Characteristics of LSVHG-06EH-1300-2L (Fluid Viscosity: 30 mm<sup>2</sup>/s)

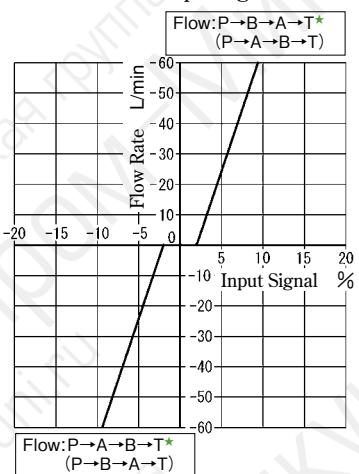
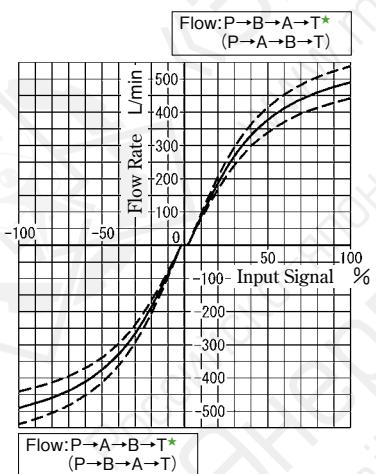
### No-Load Flow Characteristics

Conditions

Valve Pressure Difference:  $\Delta P = 1 \text{ MPa}$  (4-Way Valve) (Pressure Difference per Land: 0.5 MPa)

Around Null Position

Input Signal-20 ⇔ +20 %



The load flow characteristics, step response, and frequency response are the same as those of the spool types "2", "40", and "2P".

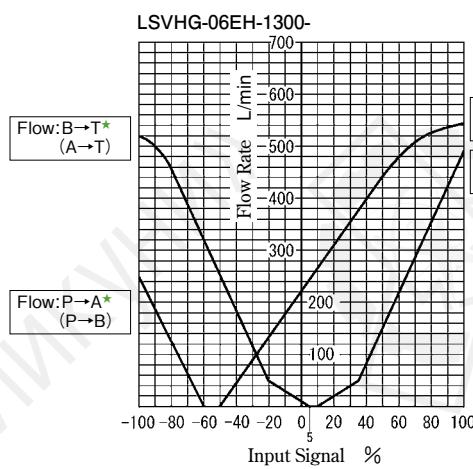
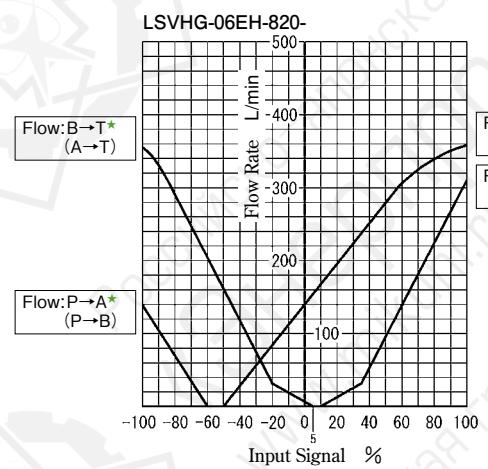
★ The flow outside of parentheses is achieved when the input signal type "A", "B", or "C" is selected. The flow in parentheses is achieved when "D", "E", or "F" is selected.

## Characteristics of LSVHG-06EH-820/1300-4J (Fluid Viscosity: 30 mm<sup>2</sup>/s)

### No-Load Flow Characteristics

Conditions

Valve Pressure Difference:  $\Delta P = 0.5 \text{ MPa}$  (per Land)



★ The flow outside of parentheses is achieved when the input signal type "A", "B", or "C" is selected. The flow in parentheses is achieved when "D", "E", or "F" is selected.

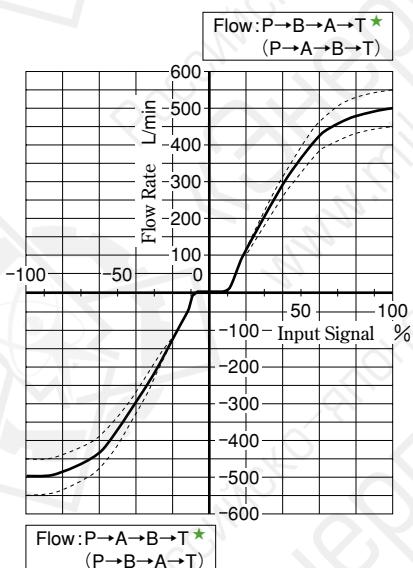
## Characteristics of LSVHG-06EH-1300-2/40/2P (Fluid Viscosity: 30 mm<sup>2</sup>/s)

### No-Load Flow Characteristics

Conditions Valve Pressure Difference: 1 MPa (Pressure Difference per Land: 0.5 MPa)

Around Null Position

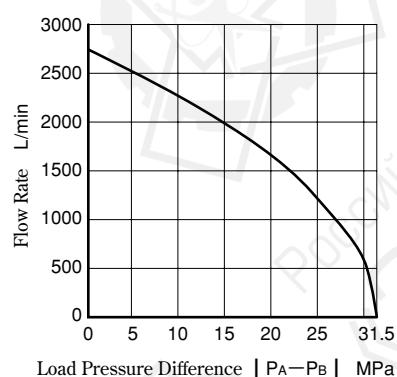
Input Signal -20 ⇄ +20 %



### Load Flow Characteristics

Conditions Input Signal : 100 %

Note) Tolerance for Load Flow : ±10 %

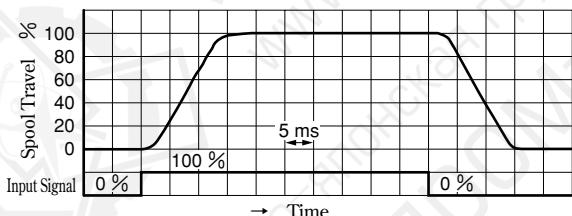


★ The flow outside of parentheses is achieved when the input signal type "A", "B", or "C" is selected. The flow in parentheses is achieved when "D", "E", or "F" is selected.

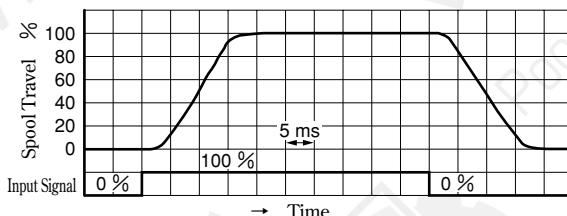
### Step Response

Conditions Input Signal : 0 ⇄ 100 % Supply/Pilot Pressure : 14 MPa

Pilot Valve: Dry Type



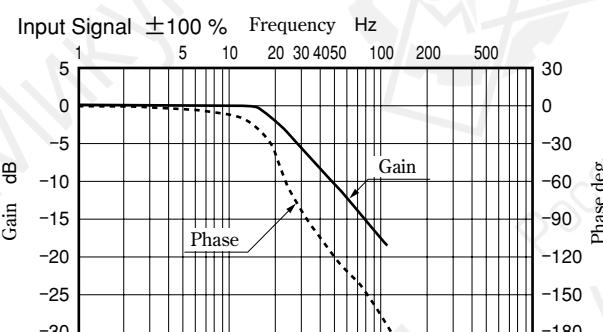
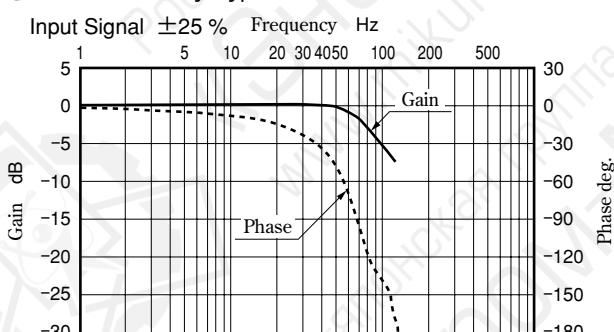
Pilot Valve: Wet Type



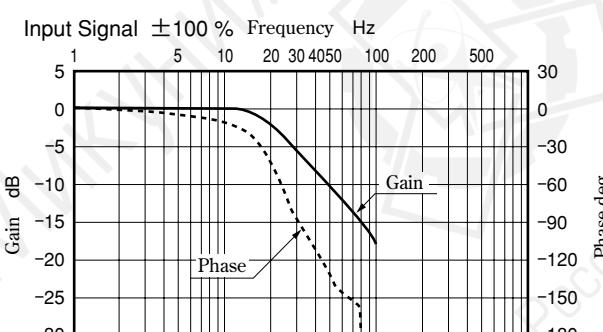
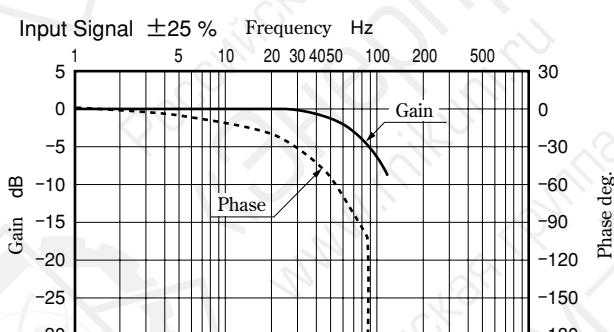
### Frequency Response

Conditions Hydraulic Circuit: Port A/B Closed Supply/Pilot Pressure : 14 MPa

Pilot Valve: Dry Type



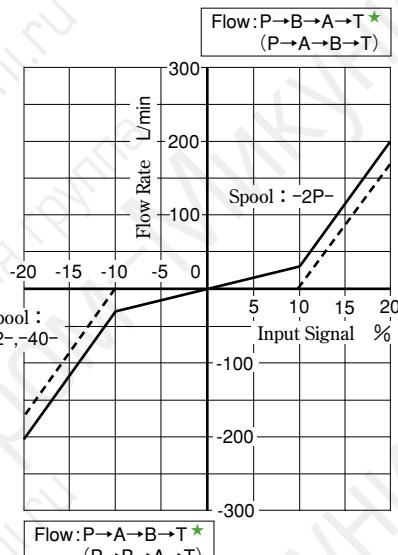
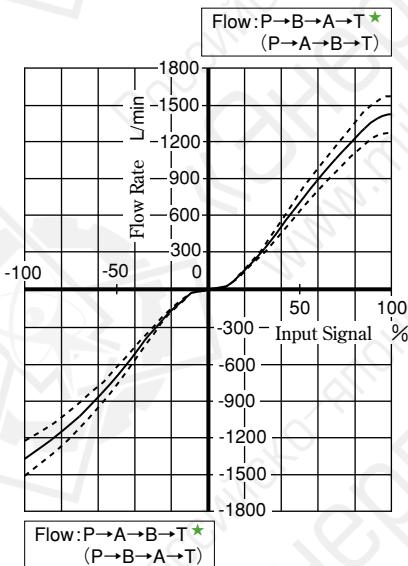
Pilot Valve: Wet Type



## Characteristics of LSVHG-10EH-3800-2/40/2P (Fluid Viscosity: 30 mm<sup>2</sup>/s)

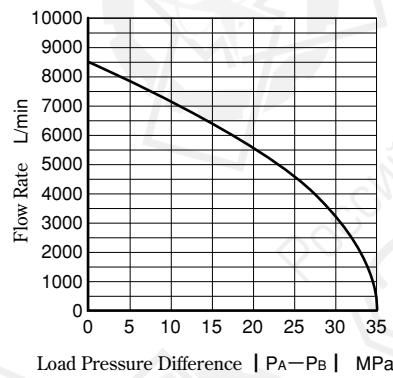
### No-Load Flow Characteristics

Conditions Valve Pressure Difference: 1 MPa (Pressure Difference per Land: 0.5 MPa)  
Around Null Position Input Signal -20 ⇄ +20 %



### Load Flow Characteristics

Conditions Input Signal : 100 %  
Note) Tolerance for Load Flow : ±10 %

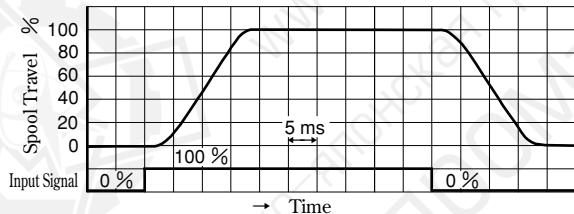


\* The flow outside of parentheses is achieved when the input signal type "A", "B", or "C" is selected. The flow in parentheses is achieved when "D", "E", or "F" is selected.

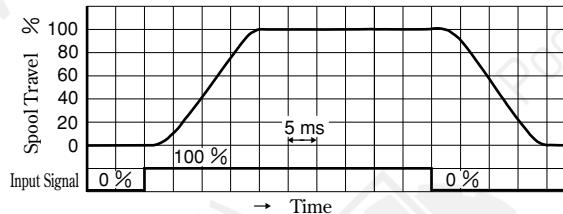
### Step Response

Conditions Input Signal : 0 ⇄ 100 % Supply/Pilot Pressure : 14 MPa

Pilot Valve: Dry Type



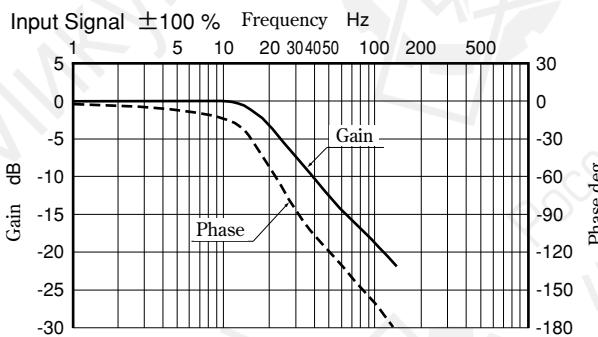
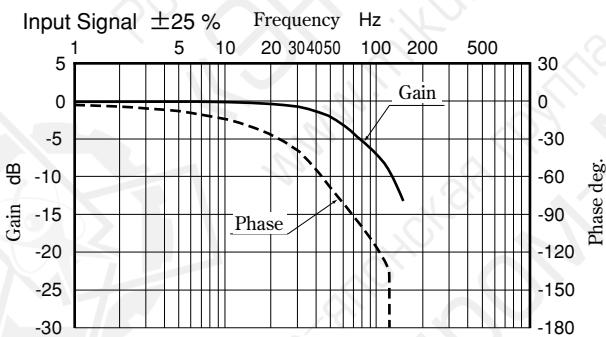
Pilot Valve: Wet Type



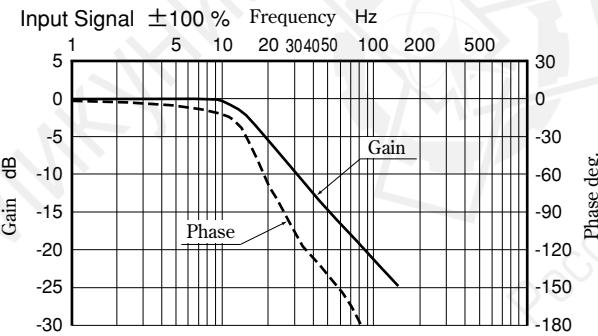
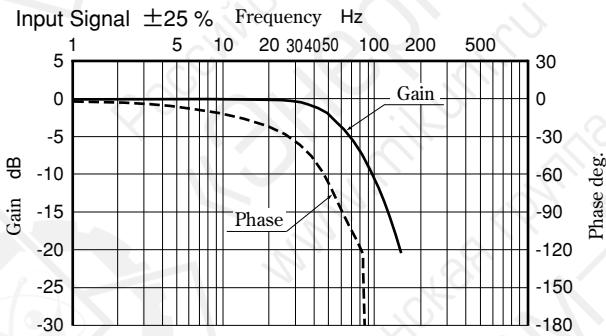
### Frequency Response

Conditions Hydraulic Circuit: Port A/B Closed Supply/Pilot Pressure : 14 MPa

Pilot Valve: Dry Type



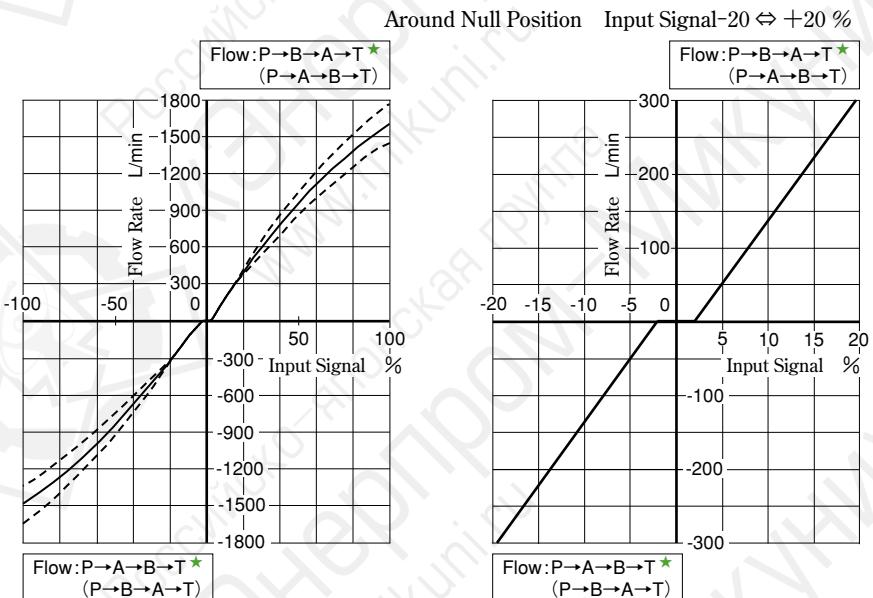
Pilot Valve: Wet Type



Characteristics of LSVHG-10EH-3800-2L (Fluid Viscosity: 30 mm<sup>2</sup>/s)

## No-Load Flow Characteristics

Conditions Valve Pressure Difference:  $\Delta P = 1 \text{ MPa}$  (4-Way Valve) (Pressure Difference per Land: 0.5 MPa)



The load flow characteristics, step response, and frequency response are the same as those of the spool types "2", "40", and "2P".

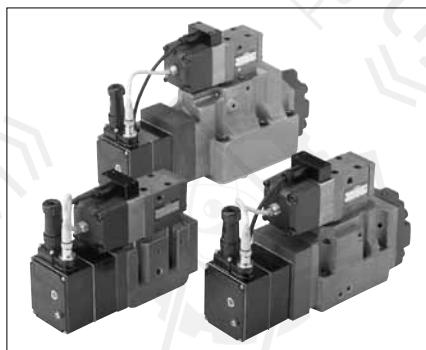
★ The flow outside of parentheses is achieved when the input signal type "A", "B", or "C" is selected. The flow in parentheses is achieved when "D", "E", or "F" is selected.

# OBE (on-Board Electronic) type Linear Servo Valves

## (High Performance Type)

On-board electronics (OBE) type linear servo valves (high performance type) are produced for achieving higher accuracy and durability by incorporating a sleeve in the main stage of the OBE type linear servo valves (standard type), which have been well accepted for their "high accuracy, easiness to use, and great usability".

Since the spool and the sleeve are processed to fit well and properly keep 1% overlap between one another, they are suited to be used for a system requiring high accuracy and durability.



### ● High accuracy

As is the case with the standard type valves, all of the OBE type linear servo valves (high performance type) have a low hysteresis of 0.1 % or less, realizing high accuracy. These valves allow the main unit to operate with much higher repeatability.

### ● High response characteristics

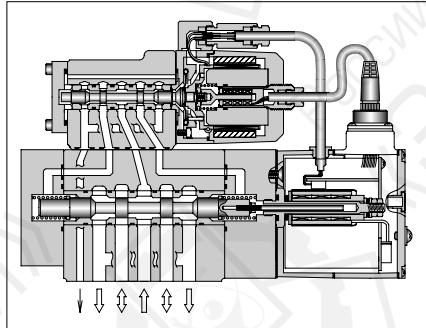
Compared to other equivalent models, these valves provide higher levels of step and frequency responses, which are typically used as measures of response characteristics; the step response is 7 ms (0 <=> 100 %)\*, and the frequency response is 110 Hz/-3 dB ( $\pm 25\%$  amplitude)\*. (\* : Representative values for LSVHG-03EH-\*S\*)

### ● Easiness to use

These valves can offer high accuracy for hydraulic control systems just with 24 V DC power supply and command signal input.

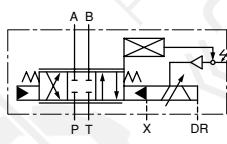
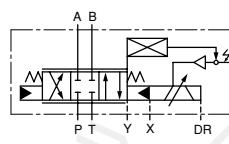
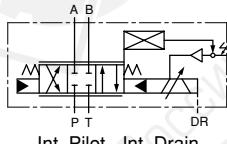
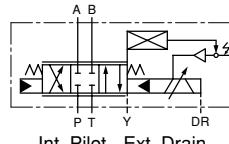
Six types of input signals in three input voltage/current ranges are available:

0 -  $\pm 10$  V, 0 -  $\pm 10$  mA, and 4 - 20 mA.

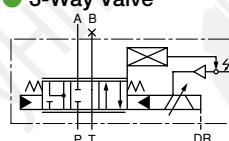


Graphic Symbols

#### ● 4-Way Valve



#### ● 3-Way Valve



Note) The pilot/drain types are the same as those for the "4-Way Valve" shown above.

### ● Two types of pilot valves available

There are two types of pilot valves available: a dry type good in response characteristics and a wet type that eliminates the drain (DR) port to improve usability. They can be selected according to users' purposes.

## ■ Model Number Designation

F-	LSVHG	-06	EH	-900	-S	4	-E	T	-W	A	-A	1	-20
Fluid Type	Series Number	Valve Size	Amp. Type	Rated Flow @ $\Delta P = 7$ MPa	Spool Type	Control Type	Pilot Type	Drain Type	DR Port and Permissible Back Pres.	Fail-safe Function	Input Signal/Spool Travel Monitoring	Connector Type	Design Number
F : Special Seals for Phosphate Ester Type Fluid (Omit if not required)	LSVHG : Two Stage Type Linear Servo Valves	03	EH : OBE Type	60 : 60 L/min 100 : 100 L/min 160 : 160 L/min	S : 1 % Overlap	3 : 3-Way Valve <sup>★1</sup> (Port A is used.)	None: Internal Pilot	None: External Drain	None: With DR Port (Permissible Back Pres.: 0.05 MPa)	A: Voltage Signal ± 10 V (P → B → A → T) Position Valve Opening: Full	A: Voltage Signal ± 10 V (P → B → A → T) Flow with Input Signal (+)	1: 6+PE Pole	
		04		100 : 100 L/min 200 : 200 L/min 280 : 280 L/min 450 : 450 L/min		4 : 4-Way Valve	E: External Pilot	T: Internal Drain	W: Without DR Port <sup>★2</sup> (Wet Type Pilot Valve)	B: Current Signal 4 - 20 mA (P → B → A → T) Flow with Current Signal 12 - 20 mA	B: Current Signal 4 - 20 mA (P → B → A → T) Flow with Current Signal 12 - 20 mA	2: 11+PE Pole	
		06		500 : 500 L/min 900 : 900 L/min						C: Current Signal ± 10 mA (P → B → A → T) Flow with Input Signal (+)	C: Current Signal ± 10 mA (P → B → A → T) Flow with Input Signal (+)		20
										D: Voltage Signal ± 10 V (P → A → B → T) Flow with Input Signal (+)	D: Voltage Signal ± 10 V (P → A → B → T) Flow with Input Signal (+)		
										E: With Solenoid Operated Valve Position Valve Opening: 10 %	E: With Solenoid Operated Valve Position Valve Opening: 10 %		
										F: With Solenoid Operated Valve Position Valve Opening: 10 %	F: With Solenoid Operated Valve Position Valve Opening: 10 %		
										G: Current Signal 4 - 20 mA (P → A → B → T) Flow with Input Signal (+)	G: Current Signal 4 - 20 mA (P → A → B → T) Flow with Input Signal (+)		

★1. For the valves with a 3-way valve and a fail-safe solenoid operated valve, select "EB" for the fail-safe function type and "D", "E", or "F" for the input signal/spool travel monitoring type.

★2. The valves with the model number "W" (without DR port) cannot use water-glycol fluids.

## ■ Specifications

The values in parentheses in the specification table below are applicable to the models "LSVHG-\*EH-\*S\*-\*-W\*" (without DR port).

Description		Model Numbers			LSVHG-03EH-*S*						LSVHG-04EH-*S*						LSVHG-06EH-*S*																			
Spool Type		S4				S3				S4				S3				S4		S3																
Rated Flow @ $\Delta P = 7 \text{ MPa}$ (4-Way Valve) L/min		60	100	160	—	—	—	100	200	280	450	—	—	—	—	500	900	—	—																	
Rated Flow @ $\Delta P = 3.5 \text{ MPa}$ (3-Way Valve) L/min		—	—	—	60	100	160	—	—	—	—	100	200	280	450	—	—	500	900	—	—															
Max. Operating Pressure		MPa		31.5				35				35				35				35																
Proof Pres. at Return Port <sup>(1)</sup>	External Drain	T Port	MPa	21				31.5				35				35				35																
		Y Port	MPa	21 <sup>(7)</sup> (7)				21 (7)				21 (7)				21 (7)				21 (7)																
	Internal Drain	T & Y Ports	MPa	21 <sup>(7)</sup> (7)				21 (7)				21 (7)				21 (7)				21 (7)																
DR Port Permissible Back Pressure <sup>(2)</sup>		MPa		0.05 (The valves with the model number "W" have no DR port.)																																
Pilot Pressure <sup>(3)</sup>		MPa		1.5 - 21																																
Pilot Flow Rate <sup>(4)</sup>		L/min		4 or more				6 or more				21 or more				21 or more				21 or more																
Pilot Valve Max. Leakage	Pres.: $P_s = P_p = 14 \text{ MPa}$	L/min		0.4																																
Main Valve Max. Leakage	Fluid Viscosity: 32 mm <sup>2</sup> /s	L/min		0.6	1.1	2.1	0.3	0.6	1.1	0.9	1.7	2.5	5.0	0.5	0.9	1.3	2.5	1.9	4.8	1.0	2.4															
Hysteresis		%		0.1 or less																																
Step Response (0 <=> 100 %, Typical) <sup>(5)</sup>		ms		7 (8)				11 (12)				12 (13)				12 (13)				12 (13)																
Frequency Response (±25 % Amplitude Typical) <sup>(6)</sup>	Gain: -3 dB	Hz		110 (80)				100 (80)				100 (80)				100 (80)				100 (80)																
	Phase: -90°	Hz		110 (90)				100 (90)				100 (90)				95 (90)				95 (90)																
Vibration Proof <sup>(6)</sup>		m/s <sup>2</sup>		100																																
Protection		—		IP 65																																
Ambient Temperature		°C		0 - +50																																
Spool Stroke to Stops		mm		±3.5				±3.5				±5				±5				±5																
Spool End Area		cm <sup>2</sup>		1.3				3.1				8				8				8																
Linear Motor Specification	Current	A		Max. 2.1																																
	Coil Resistance	Ω		9.6 [at 20 °C ]																																
Approx. Mass <sup>(8)</sup>		kg		8.5 [11]				14 [16]				20 [24]				20 [24]				20 [24]																
Mounting Surface				ISO 4401-05-05-0-94				ISO 4401-07-06-0-94				ISO 4401-08-07-0-94				ISO 4401-08-07-0-94				ISO 4401-08-07-0-94																
Electric Connection		6 + PE/11 + PE Connector (EN175201 Part 804)																																		

Note: <sup>(1)</sup> Pressure at the return port should be at actual supply pressure or less.

<sup>(2)</sup> Back pressure at the drain port should be 0.05 MPa or less and not be a negative pressure. For the valves with the model number "W", no drain port connection is required.

<sup>(3)</sup> Supply pressure for the pilot valve should be 1.5 - 21 MPa and should also be 60% of actual supply pressure or more.

<sup>(4)</sup> The pilot flow is calculated based on a pilot pressure of 14 MPa and the above step response.

<sup>(5)</sup> This value is measured for each valve based on a pilot pressure of 14 MPa; it may vary depending on the actual circuit/operation conditions.

<sup>(6)</sup> There are restrictions on the mounting position; refer to the instructions for details.

<sup>(7)</sup> To use an external pilot type valve with a supply pressure of 21 MPa or more, pressures at the T and Y ports should be 7 MPa or less.

<sup>(8)</sup> A value in brackets indicates the mass of each valve with a fail-safe solenoid operated valve.

<sup>(9)</sup> For the effective range of the fail-safe function, see page 59.

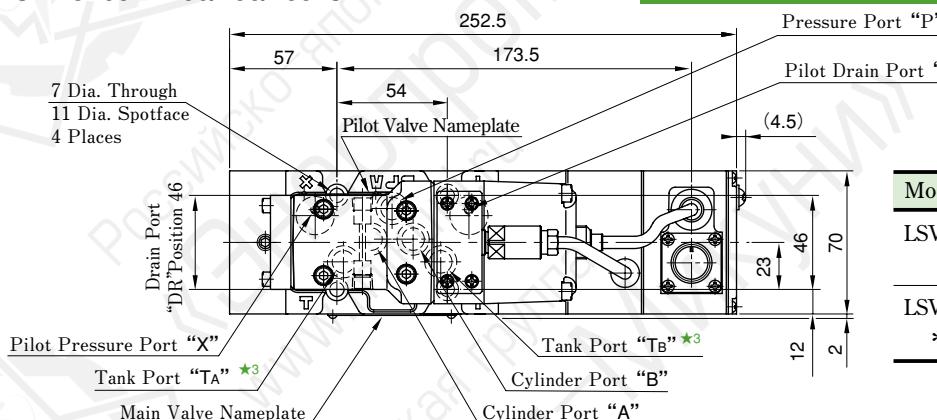
## ■ Attachment/Electrical Specifications/Block Diagram

These are the same as those of the standard type. See the relevant pages.

Item	Page for Reference
Attachment	34
Electrical Specifications	35
Block Diagram	36

## LSVHG-03EH-60/100/160-S \*

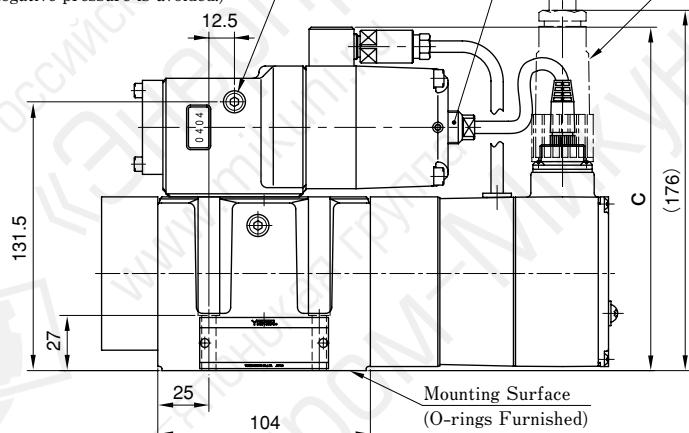
Mounting Surface: Conforming to ISO 4401-05-05-0-94



Model Number	C	Remarks
LSVHG-03EH- * -S*	168	Pilot Valve: Dry Type
LSVHG-03EH- * -S*-W	177	Pilot Valve: Wet Type

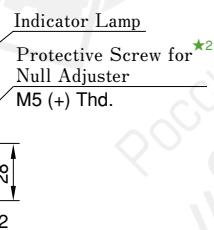
## External Connection Drain Port "DR" ★1

Rc 1/8 (Back Side)  
(Dry type pilot valve only)  
(Connect piping in such a way that negative pressure is avoided.)



Pilot Spool Position Sensor  
Cable Applicable: Outside Dia. 8 - 10 mm  
6 + PE/11 + PE Electrical Plug  
EN175201 Part 804

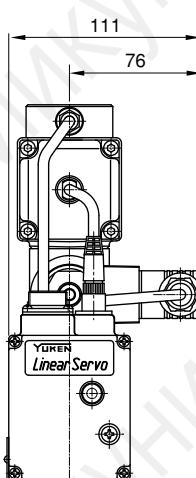
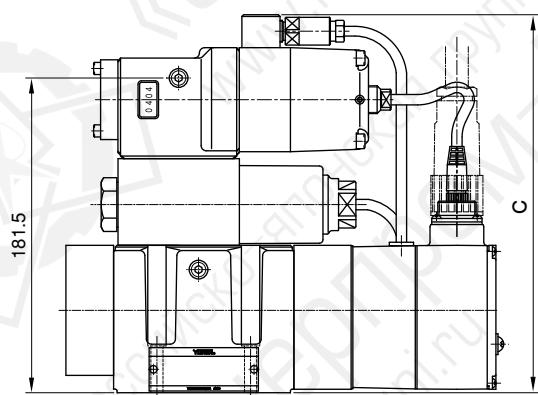
Color	Indicator Lamp
Green	Power Supply
Red	Pilot Valve Deviation Alarm
Yellow	Main Valve Deviation Alarm



★1. The external connection drain port "DR" on the front side is usually plugged. To use the port on the front side, remove the hexagon socket head plug (5 Hex.) and plug the port on the back side.

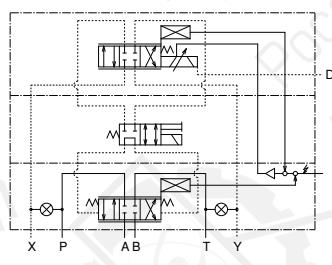
★2. To adjust the null, remove the protective screw and turn the null trimmer. After adjustment, be sure to attach the protective screw.

★3. There are two tank ports "TA" and "TB"; however, "TA" may be used alone.

LSVHG-03EH-60/100/160-S \* - EA/EB  
(With Fail-safe Solenoid Operated Valve)

**[Dimensions of Mounting Surface]**  
The dimensions of the mounting surface are the same as those of the models LSVHG-03EH (page 37).

## Detailed Graphic Symbol



## ● O-rings for the Ports

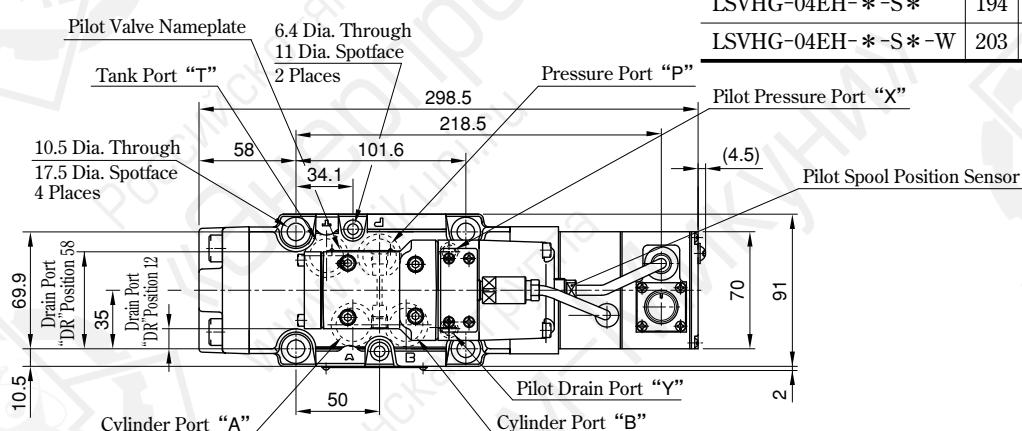
Port	O-ring Size	Qty.
P, A, B, T	AS568-014 (NBR, Hs90)	5
X, Y	AS568-016 (NBR, Hs90)	2

O-rings made of fluorinated rubber are required to use phosphate ester type fluids.

Model Number	C	Remarks
LSVHG-03EH- * -S*-E*	218	Pilot Valve: Dry Type
LSVHG-03EH- * -S*-WE*	227	Pilot Valve: Wet Type

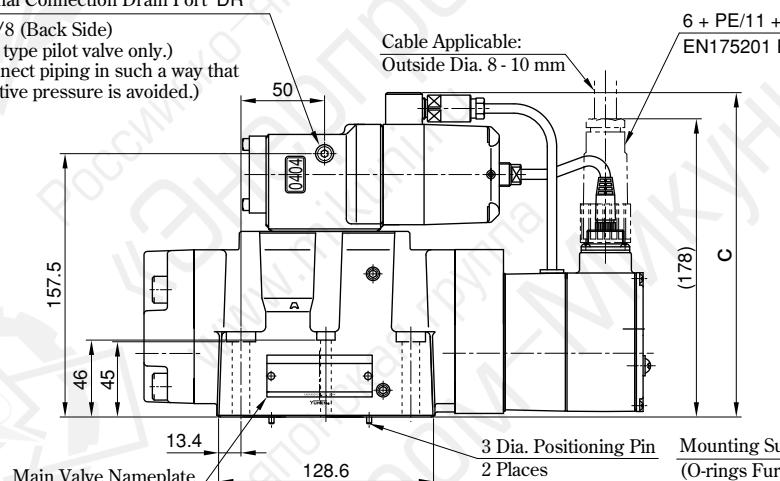
●For other dimensions, see the figures above (the models without a fail-safe solenoid operated valve).

## LSVHG-04EH-100/200/280/450-S \*



### External Connection Drain Port "DR" <sup>\*1</sup>

Rc 1/8 (Back Side)  
(Dry type pilot valve only.)  
(Connect piping in such a way that negative pressure is avoided.)



6 + PE/11 + PE Electrical Plug  
EN175201 Part 804

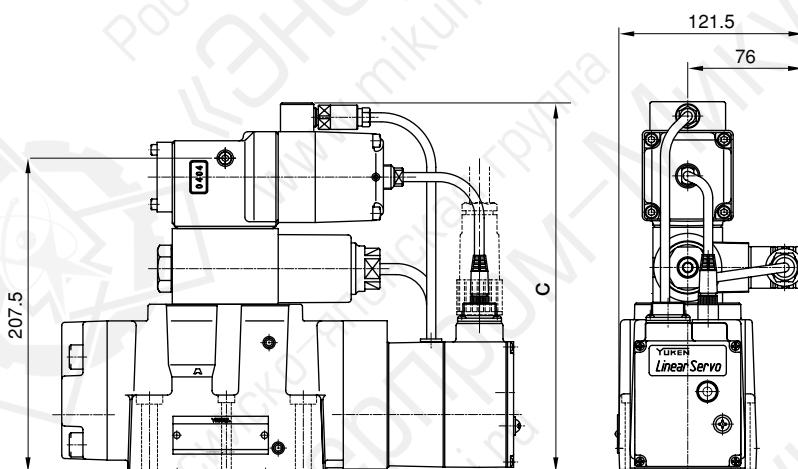
Color	Indicator Lamp
Green	Power Supply
Red	Pilot Valve Deviation Alarm
Yellow	Main Valve Deviation Alarm

Indicator Lamp	Protective Screw for Null Adjuster M5 (+) Thd.

★1. The external connection drain port "DR" on the front side is usually plugged. To use the port on the front side, remove the hexagon socket head plug (5 Hex.) and plug the port on the back side.

★2. To adjust the null, remove the protective screw and turn the null trimmer. After adjustment, be sure to attach the protective screw.

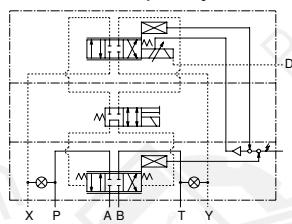
## LSVHG-04EH-100/200/280/450-\*S-\*EA/EB (With Fail-safe Solenoid Operated Valve)



### [Dimensions of Mounting Surface]

The dimensions of the mounting surface are the same as those of the models LSVHG-04 (page 11).

### Detailed Graphic Symbol



⊗: Plugs for selecting the pilot and drain types

### O-rings for the Ports

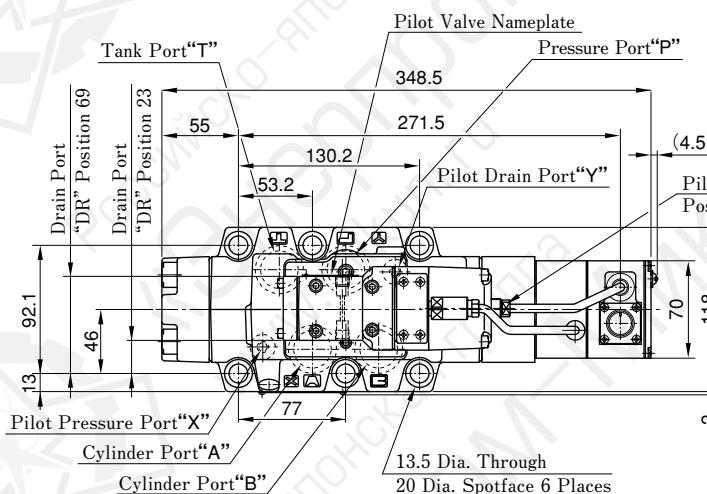
Port	O-ring Size	Qty.
P, A, B, T	JIS B2401-1B-P22	4
X, Y	AS568-012 (NBR, Hs90)	2

O-rings made of fluorinated rubber are required to use phosphate ester type fluids.

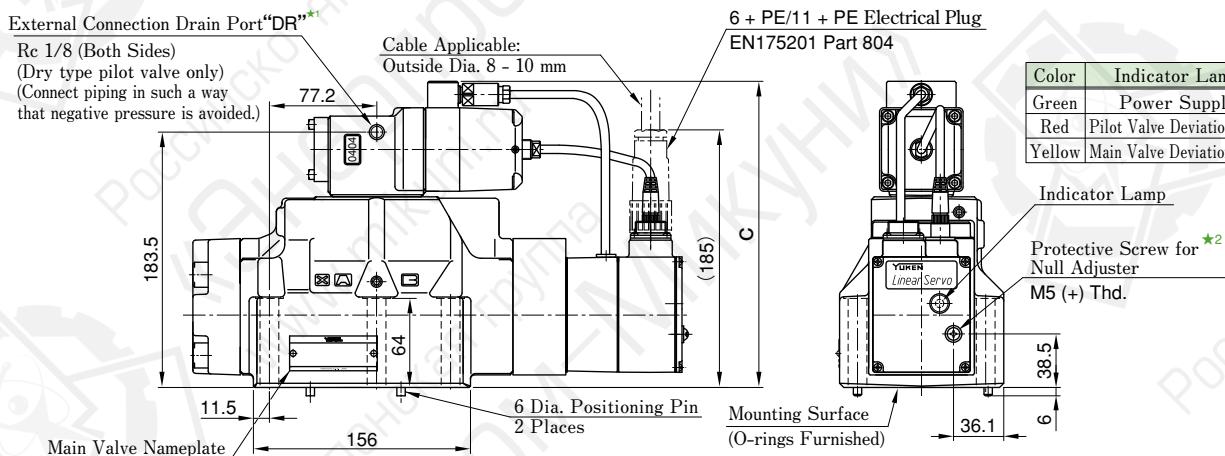
Model Number	C	Remarks
LSVHG-04EH-*S*-E*	244	Pilot Valve: Dry Type
LSVHG-04EH-*S*-WE*	253	Pilot Valve: Wet Type

● For other dimensions, see the figures above (the models without a fail-safe solenoid operated valve).

## LSVHG-06EH-500/900-S\*



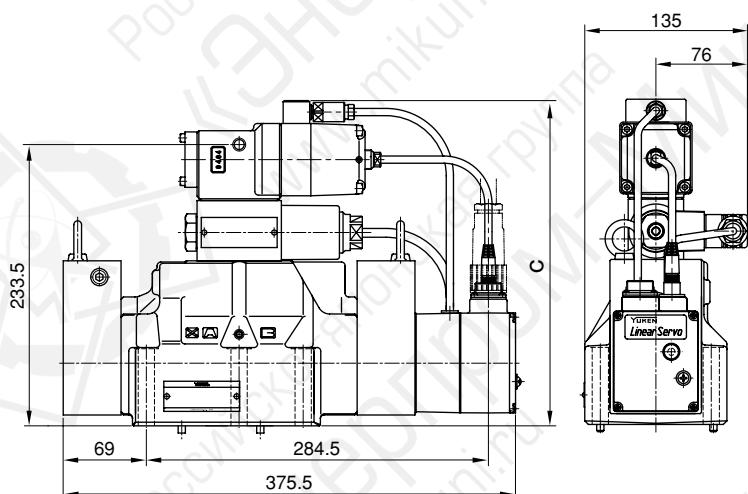
Model Number	C	Remarks
LSVHG-06EH- *-S*	220	Pilot Valve: Dry Type
LSVHG-06EH- *-S*-W	229	Pilot Valve: Wet Type



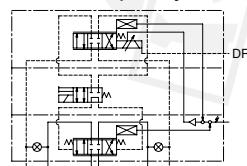
★1. The external connection drain port "DR" on the back side is usually plugged. To use the port on the back side, remove the hexagon socket head plug (5 Hex.) and plug the port on the front side.

★2. To adjust the null, remove the protective screw and turn the null trimmer. After adjustment, be sure to attach the protective screw.

## LSVHG-06EH-500/900- \*-S-\* EA/EB (With Fail-safe Solenoid Operated Valve)



Detailed Graphic Symbol



⊗: Plugs for selecting the pilot and drain types

Model Number	C	Remarks
LSVHG-06EH- *-S-* -E*	270	Pilot Valve: Dry Type
LSVHG-06EH- *-S-* -WE*	279	Pilot Valve: Wet Type

●For other dimensions, see the figures above (the models without a fail-safe solenoid operated valve).

## [Dimensions of Mounting Surface]

The dimensions of the mounting surface are the same as those of the models LSVHG-06-900 (page 12).

## ● O-rings for the Ports

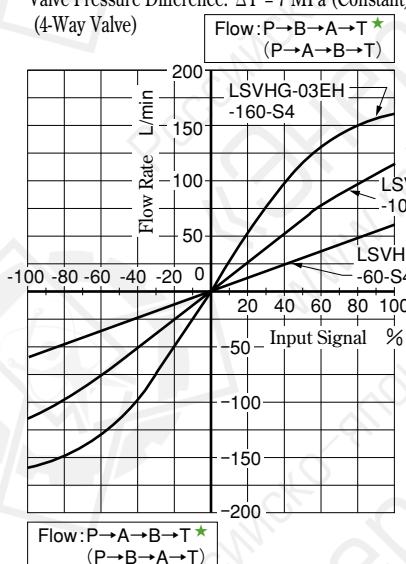
Port	O-ring Size	Qty.
P, A, B, T	AS568-123 (NBR ,Hs90)	4
X, Y	JIS B2401-1B-P14	2

O-rings made of fluorinated rubber are required to use phosphate ester type fluids.

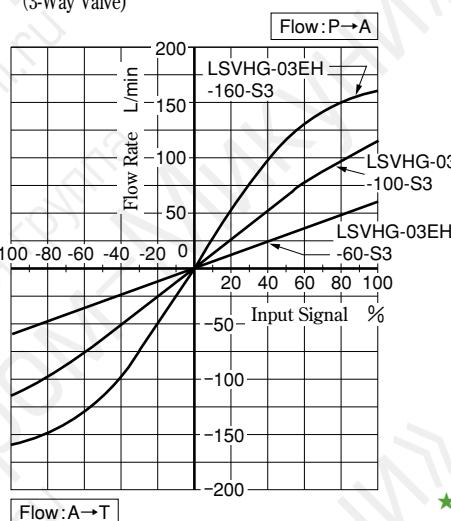
## Characteristics of LSVHG-03EH-60/100/160-S \*

### No-Load Flow Characteristics

Valve Pressure Difference:  $\Delta P = 7 \text{ MPa}$  (Constant)  
(4-Way Valve)



Valve Pressure Difference:  $\Delta P = 3.5 \text{ MPa}$  (Constant)  
(3-Way Valve)

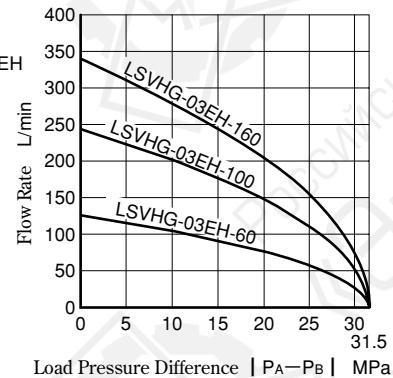


### Load Flow Characteristics

Conditions

● Input Signal : 100 %

Note) Tolerance for Load Flow :  $\pm 10 \%$

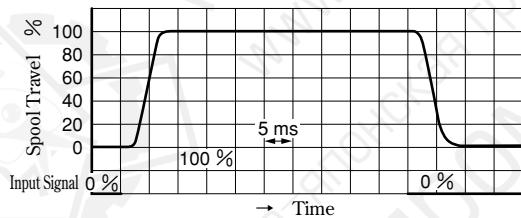


★ The flow outside of parentheses is achieved when the input signal type "A", "B", or "C" is selected. The flow in parentheses is achieved when "D", "E", or "F" is selected.

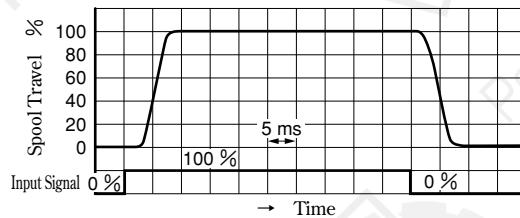
### Step Response

Conditions ● Input Signal : 0 ⇔ 100 % ● Supply/Pilot Pressure : 14 MPa

#### Pilot Valve: Dry Type



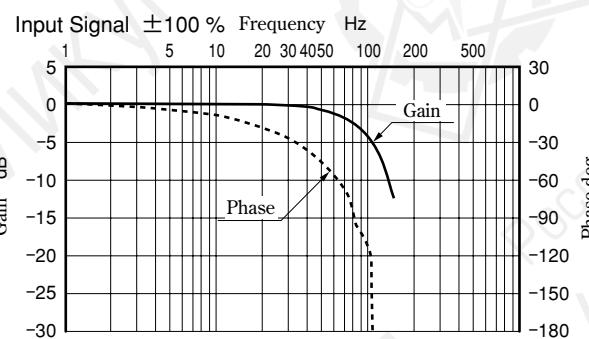
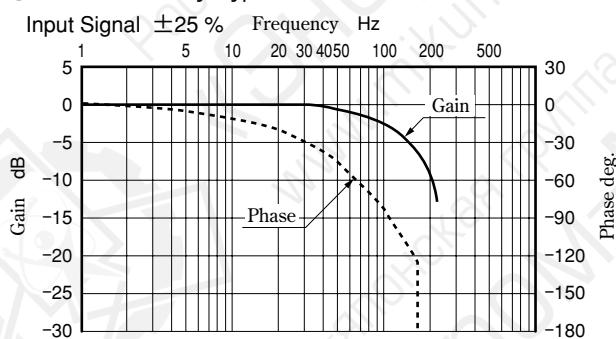
#### Pilot Valve: Wet Type



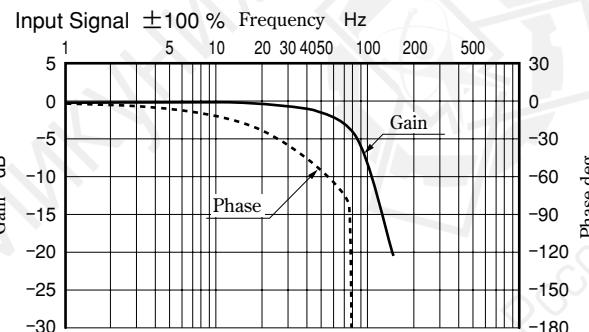
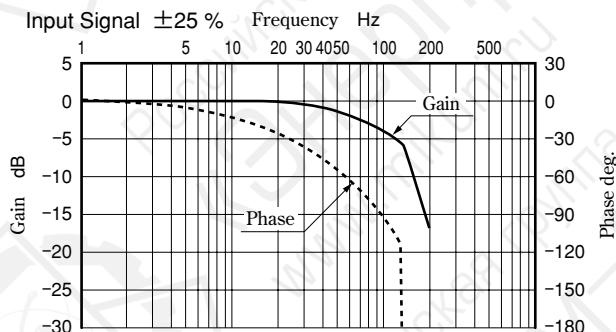
### Frequency Response

Conditions ● Hydraulic Circuit: Port A/B Closed ● Supply/Pilot Pressure : 14 MPa

#### Pilot Valve: Dry Type



#### Pilot Valve: Wet Type

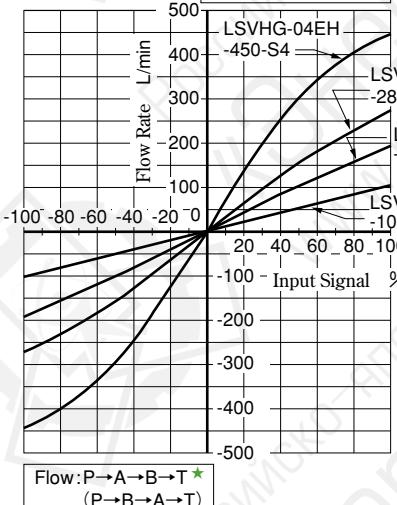


## Characteristics of LSVHG-04EH-100/200/280/450-S\* (Fluid Viscosity: 30 mm<sup>2</sup>/s)

### No-Load Flow Characteristics

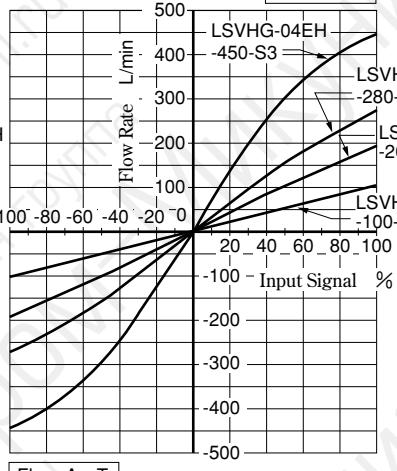
Valve Pressure Difference:  $\Delta P = 7 \text{ MPa}$  (Constant)  
(4-Way Valve)

Flow: P → B → A → T ★  
(P → A → B → T)



Valve Pressure Difference:  $\Delta P = 3.5 \text{ MPa}$  (Constant)  
(3-Way Valve)

Flow: P → A

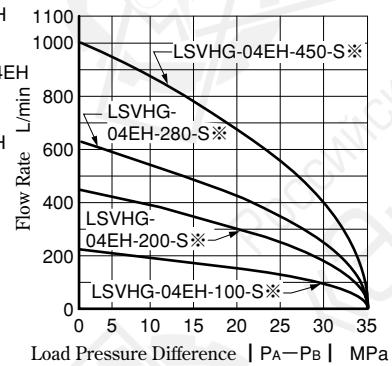


### Load Flow Characteristics

<Conditions>

● Input Signal : 100 %

Note) Tolerance for Load Flow : ±10 %



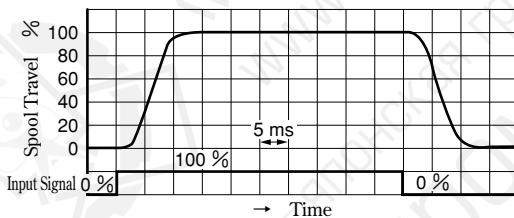
★ The flow outside of parentheses is achieved when the input signal type "A", "B", or "C" is selected. The flow in parentheses is achieved when "D", "E", or "F" is selected.

### Step Response

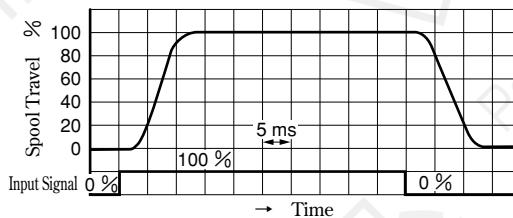
<Conditions> ● Input Signal : 0 ⇄ 100 %

● Supply/Pilot Pressure : 14 MPa

● Pilot Valve: Dry Type



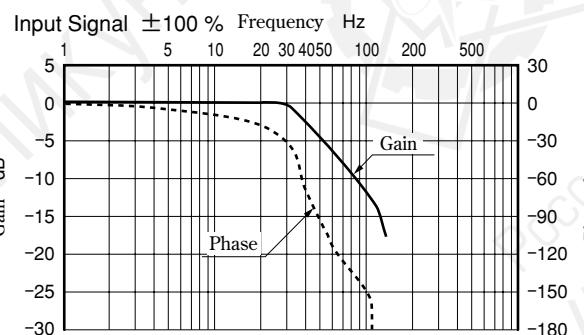
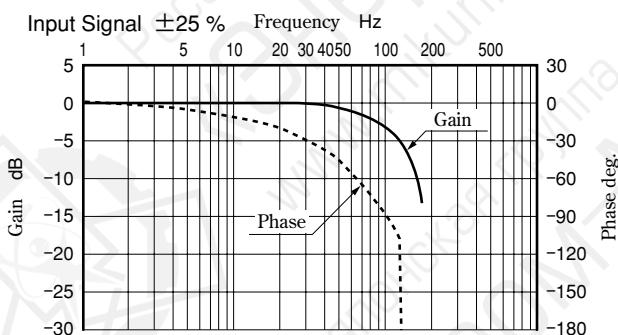
● Pilot Valve: Wet Type



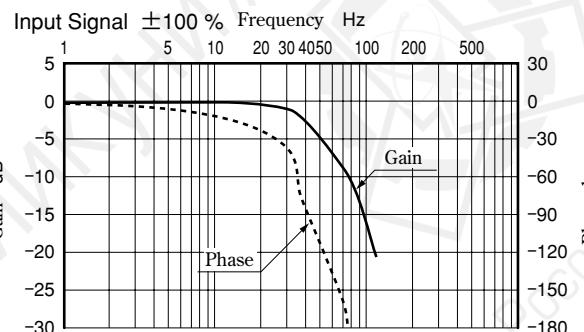
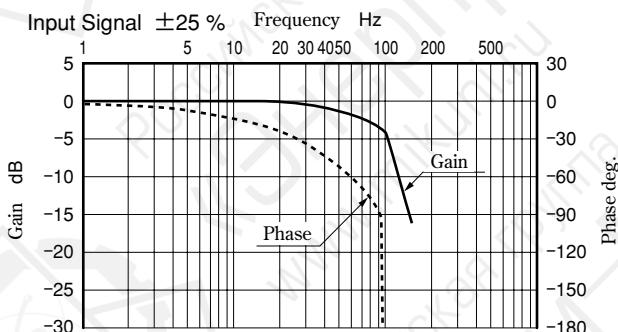
### Frequency Response

<Conditions> ● Hydraulic Circuit: Port A/B Closed ● Supply/Pilot Pressure : 14 MPa

● Pilot Valve: Dry Type



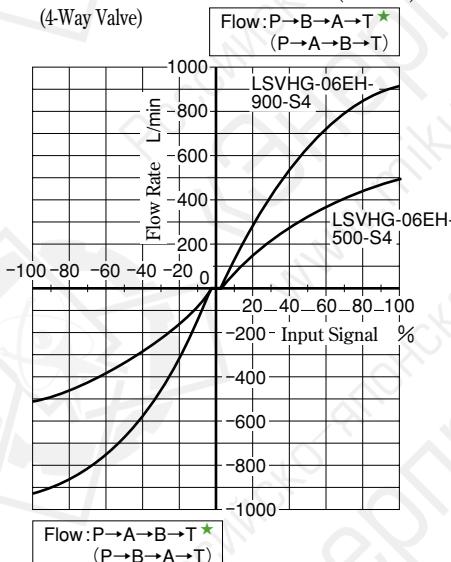
● Pilot Valve: Wet Type



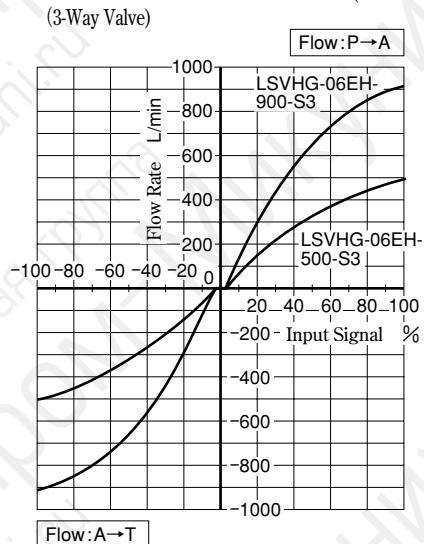
## Characteristics of LSVHG-06EH-500/900-S \*

### No-Load Flow Characteristics

Valve Pressure Difference:  $\Delta P = 7 \text{ MPa}$  (Constant)  
(4-Way Valve)



Valve Pressure Difference:  $\Delta P = 3.5 \text{ MPa}$  (Constant)  
(3-Way Valve)

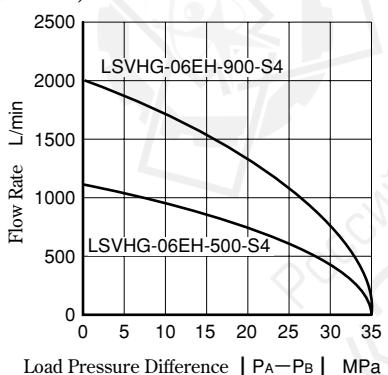


### Load Flow Characteristics

Conditions

● Input Signal : 100 %

Note) Tolerance for Load Flow :  $\pm 10 \%$



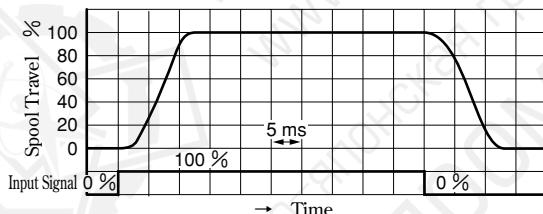
\* The flow outside of parentheses is achieved when the input signal type "A", "B", or "C" is selected. The flow in parentheses is achieved when "D", "E", or "F" is selected.

### Step Response

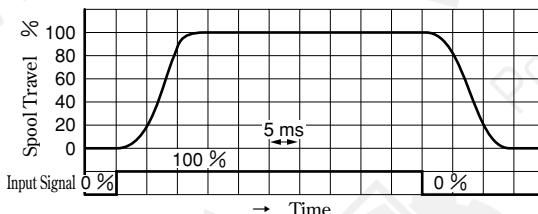
Conditions ● Input Signal : 0 ⇄ 100 %

● Supply/Pilot Pressure : 14 MPa

#### Pilot Valve: Dry Type



#### Pilot Valve: Wet Type

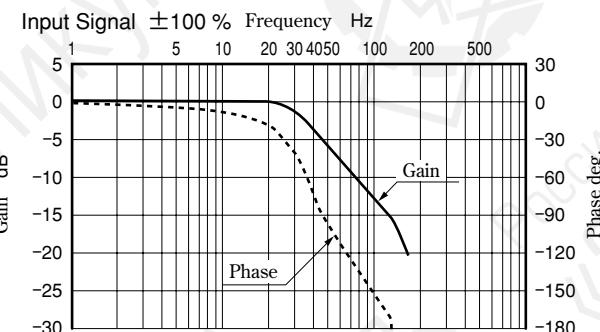
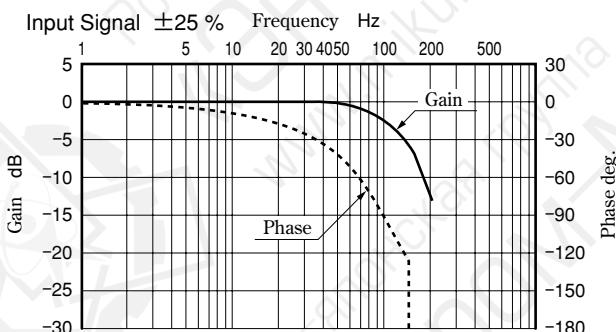


### Frequency Response

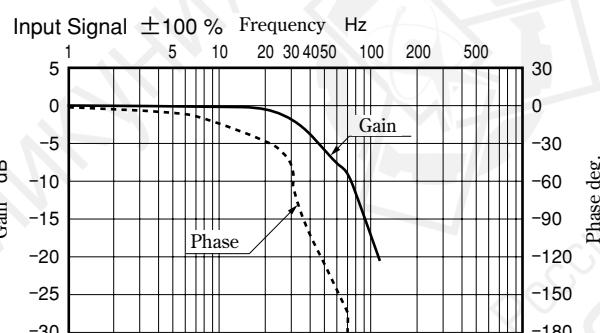
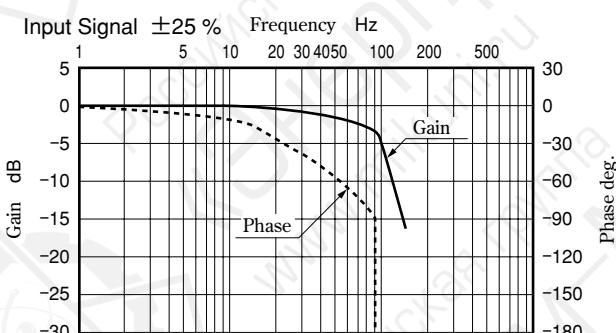
Conditions ● Hydraulic Circuit: Port A/B Closed

● Supply/Pilot Pressure : 14 MPa

#### Pilot Valve: Dry Type

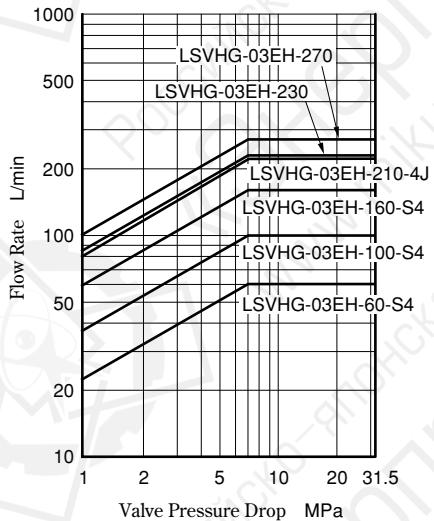


#### Pilot Valve: Wet Type

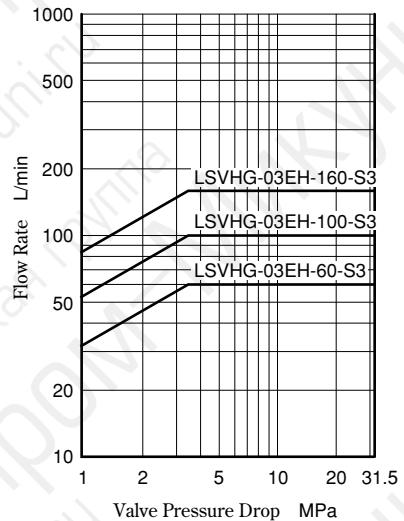


## Effective Ranges of the Fail-safe Function for OBE (On-Board Electronics) Type Linear Servo Valves

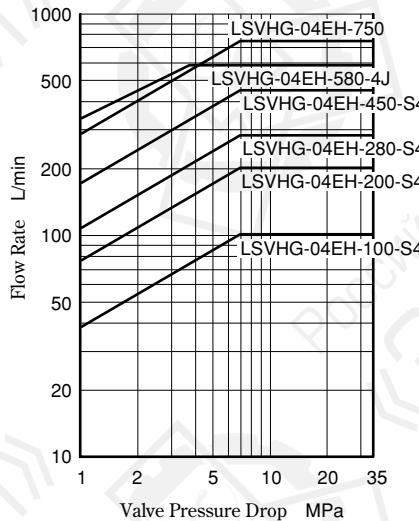
- LSVHG-03EH-230/270-
- LSVHG-03EH-210-4J-
- LSVHG-03EH-60/100/160-S4-



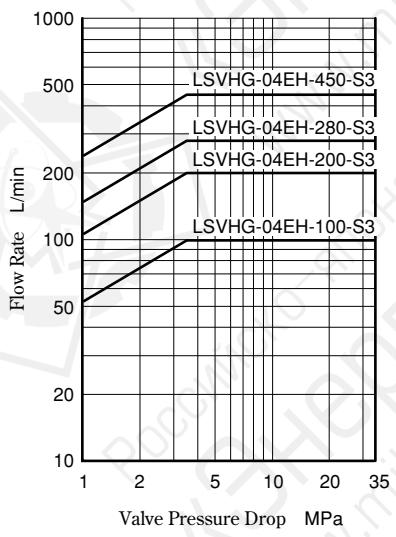
- LSVHG-03EH-60/100/160-S3-



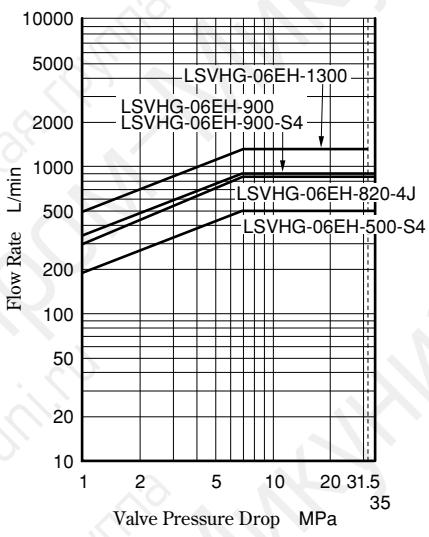
- LSVHG-04EH-750-
- LSVHG-04EH-580-4J-
- LSVHG-04EH-100/200/280/450-S4-



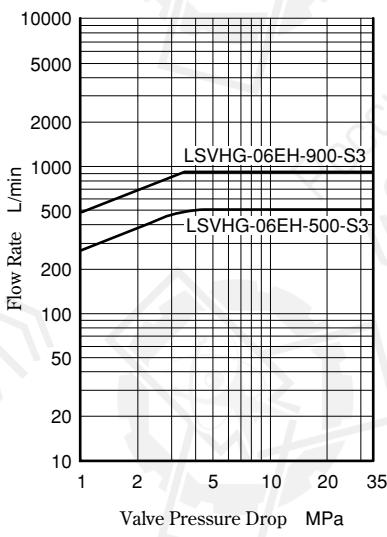
- LSVHG-04EH-100/200/280/450-S3-



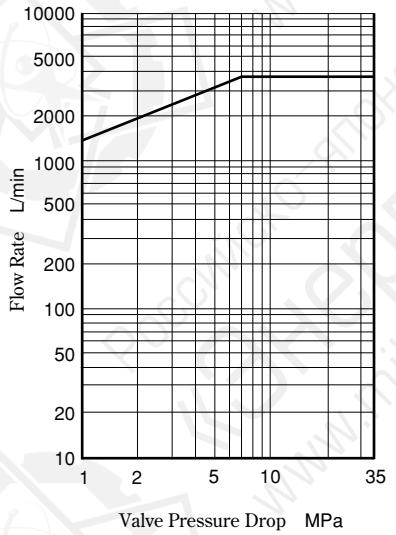
- LSVHG-06EH-900/1300



- LSVHG-06EH-500/900-S3-



- LSVHG-10EH-3800-



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## **Linear Servo Valves Catalogue**

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